

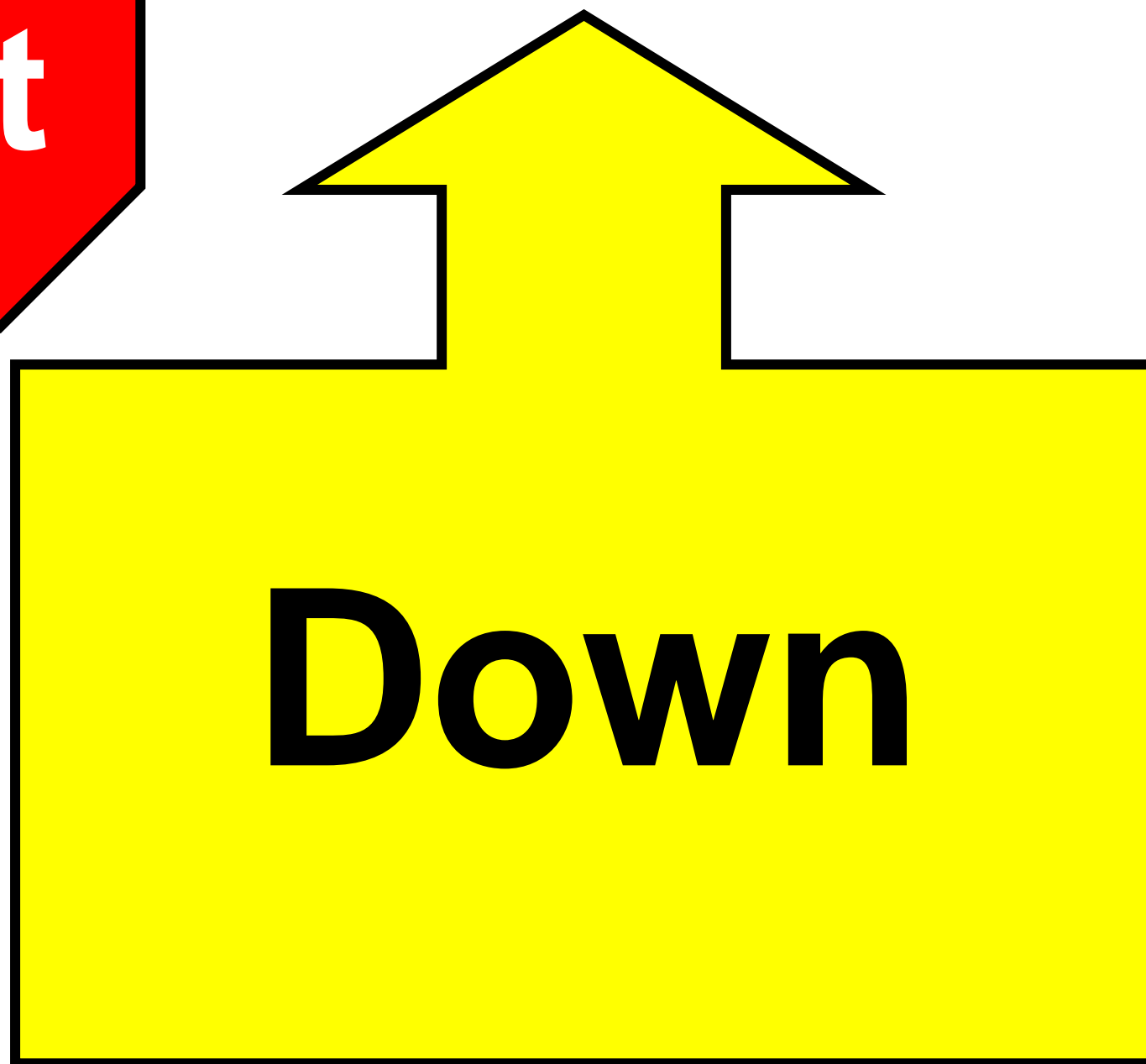


**Start**

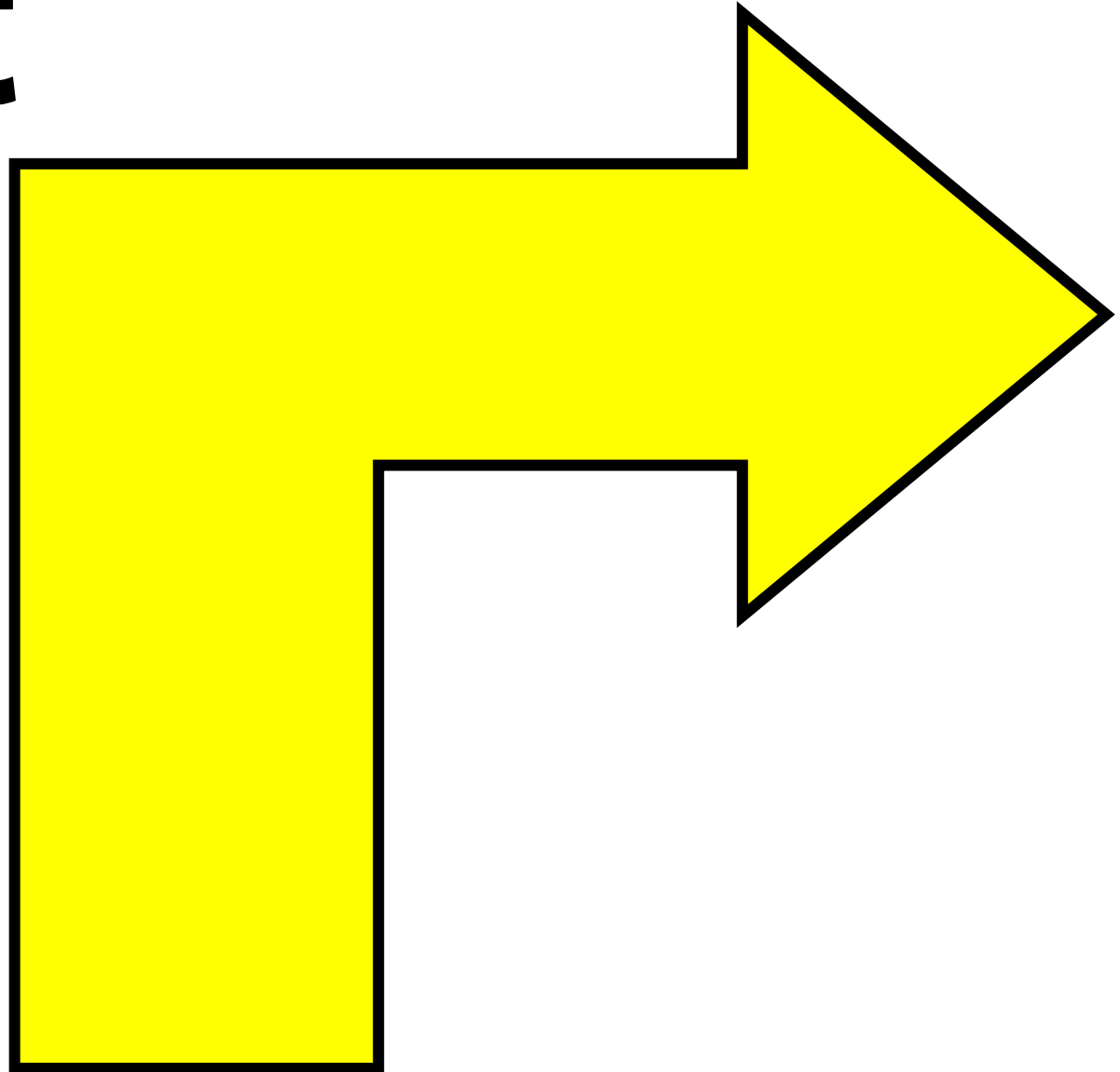


**Finish**

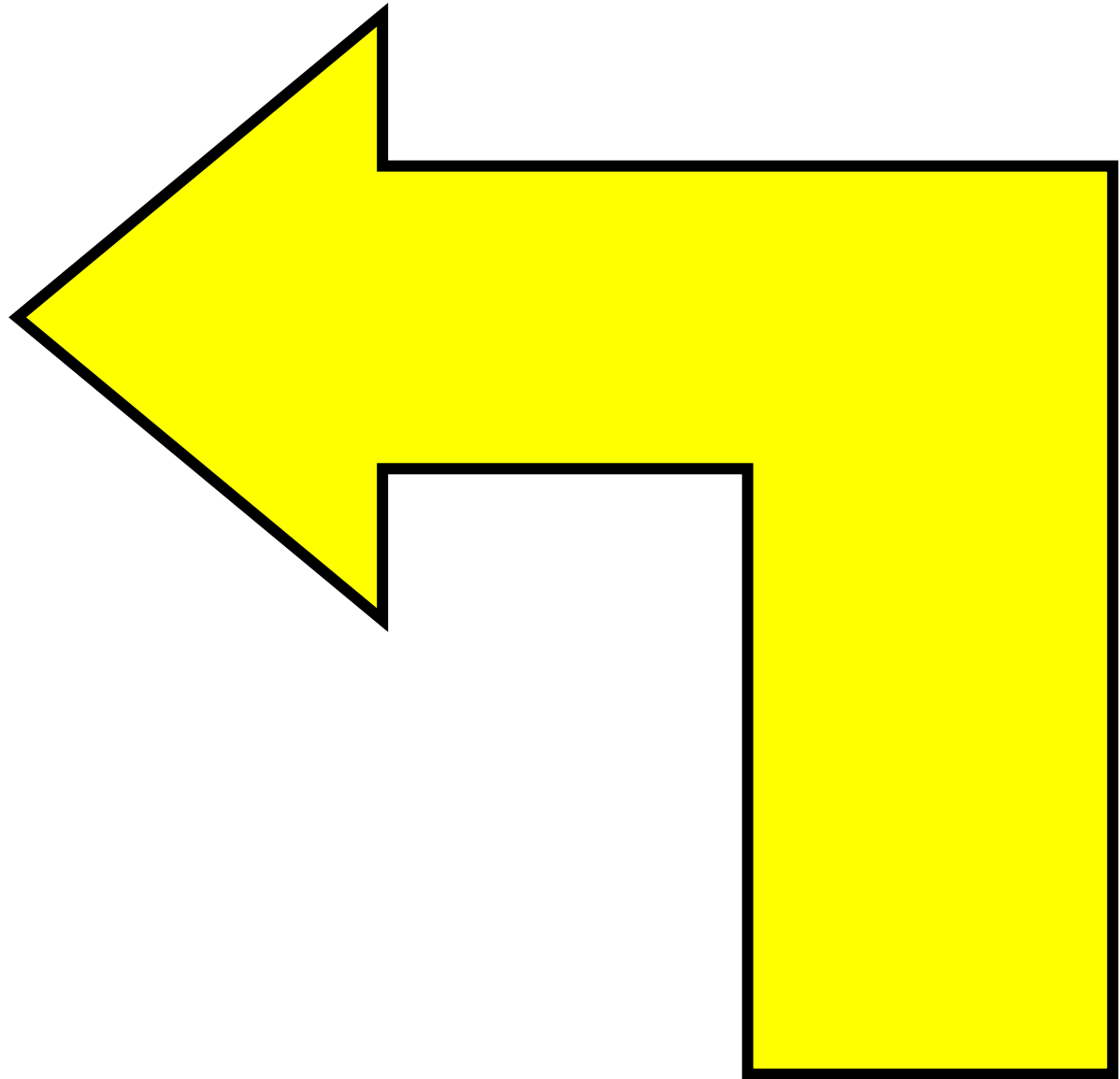




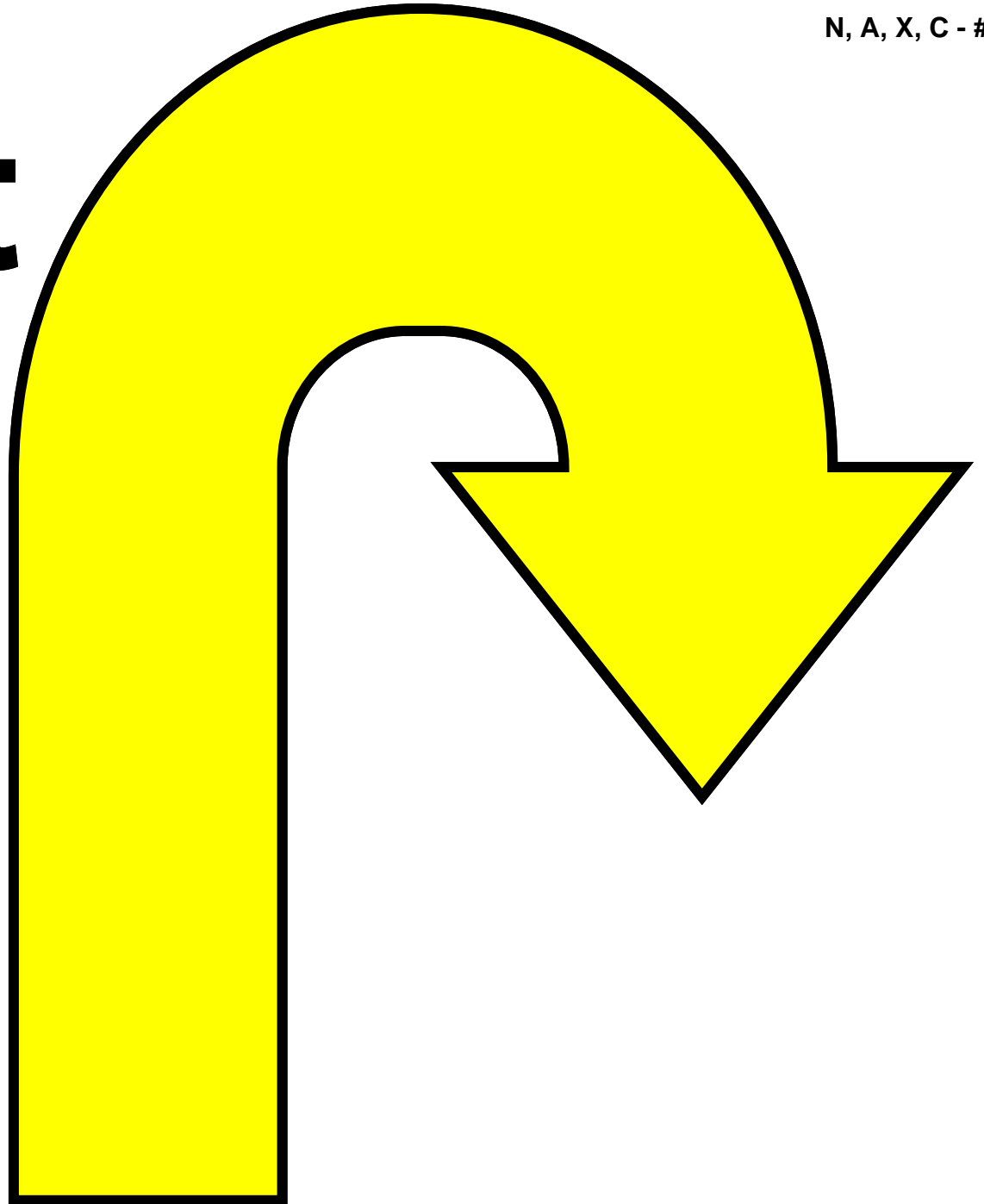
**Right  
Turn**



**Left  
Turn**



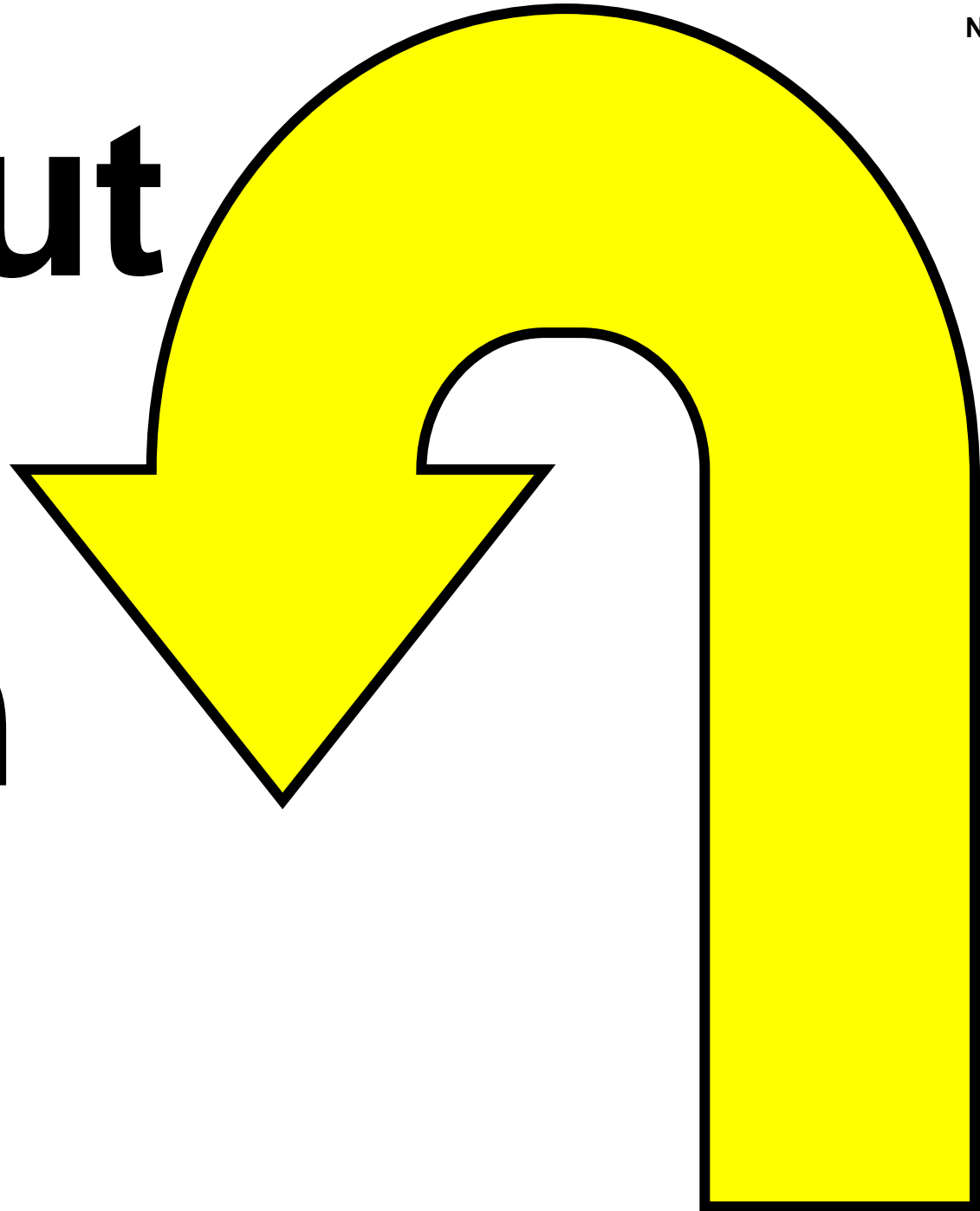
**About  
Turn  
Right**



**About**

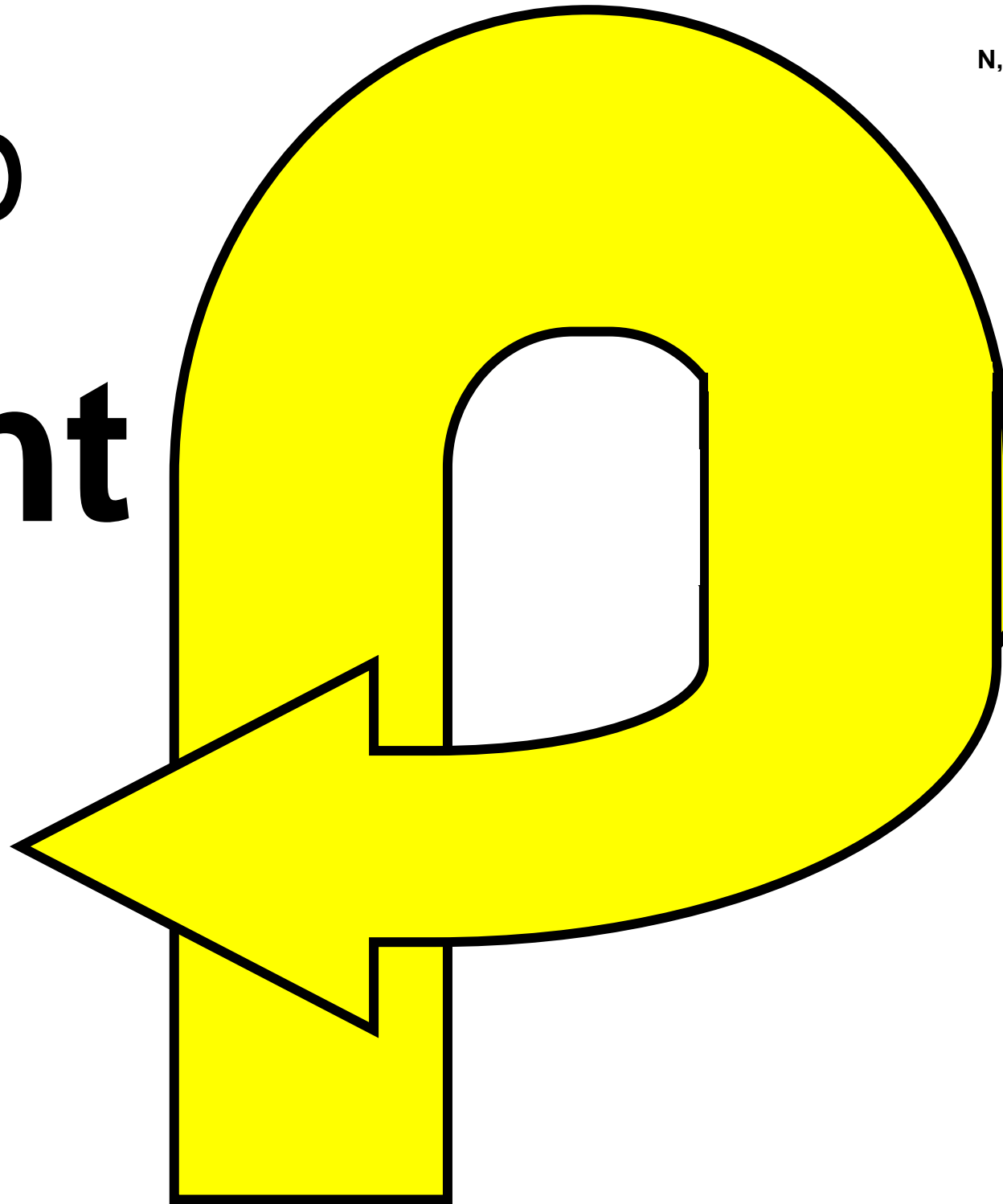
**U**

**Turn**



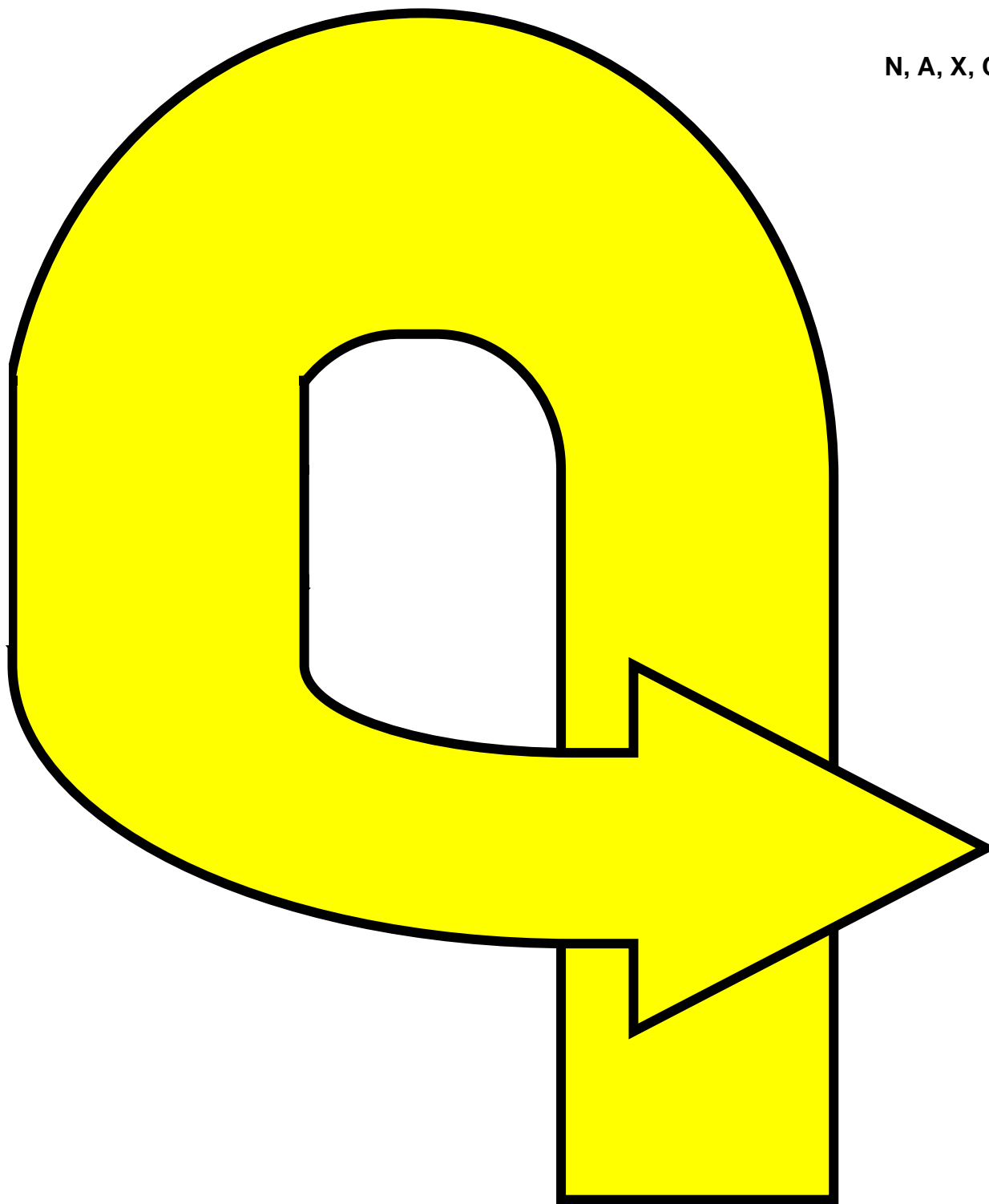


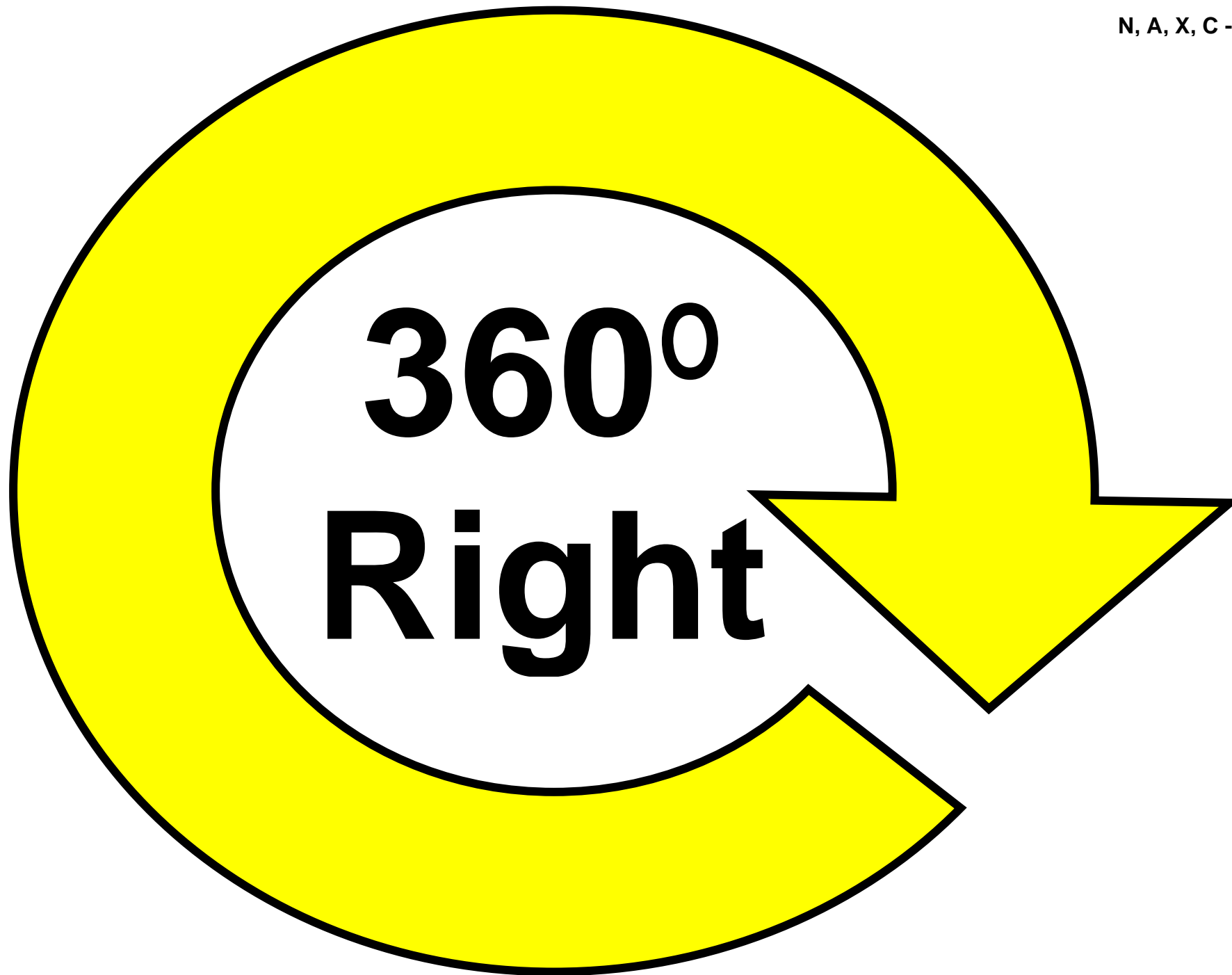
**270°  
Right**

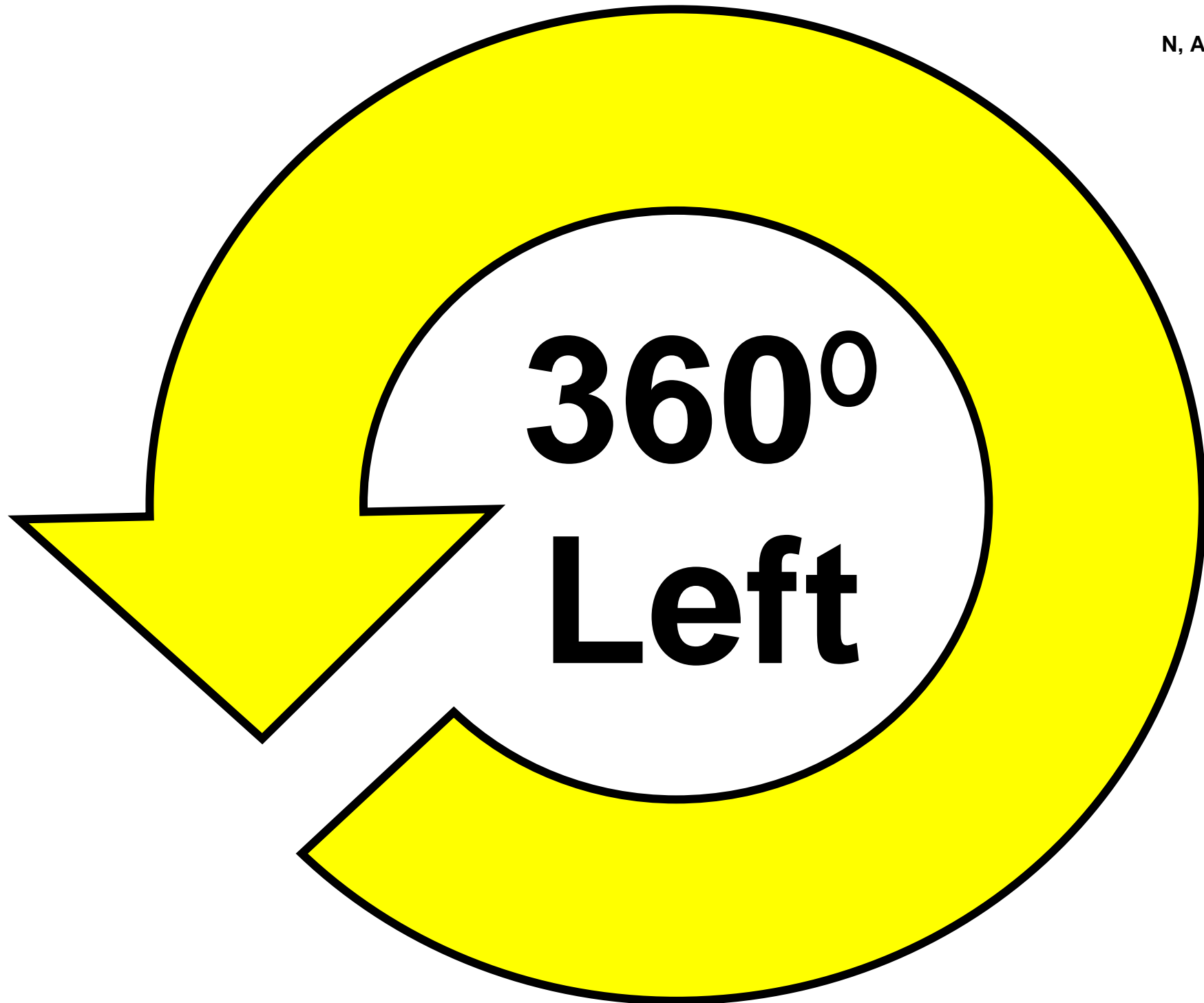


**270°**

**Left**









**Call**  
**Front**  
**Finish Right**  
**Forward**



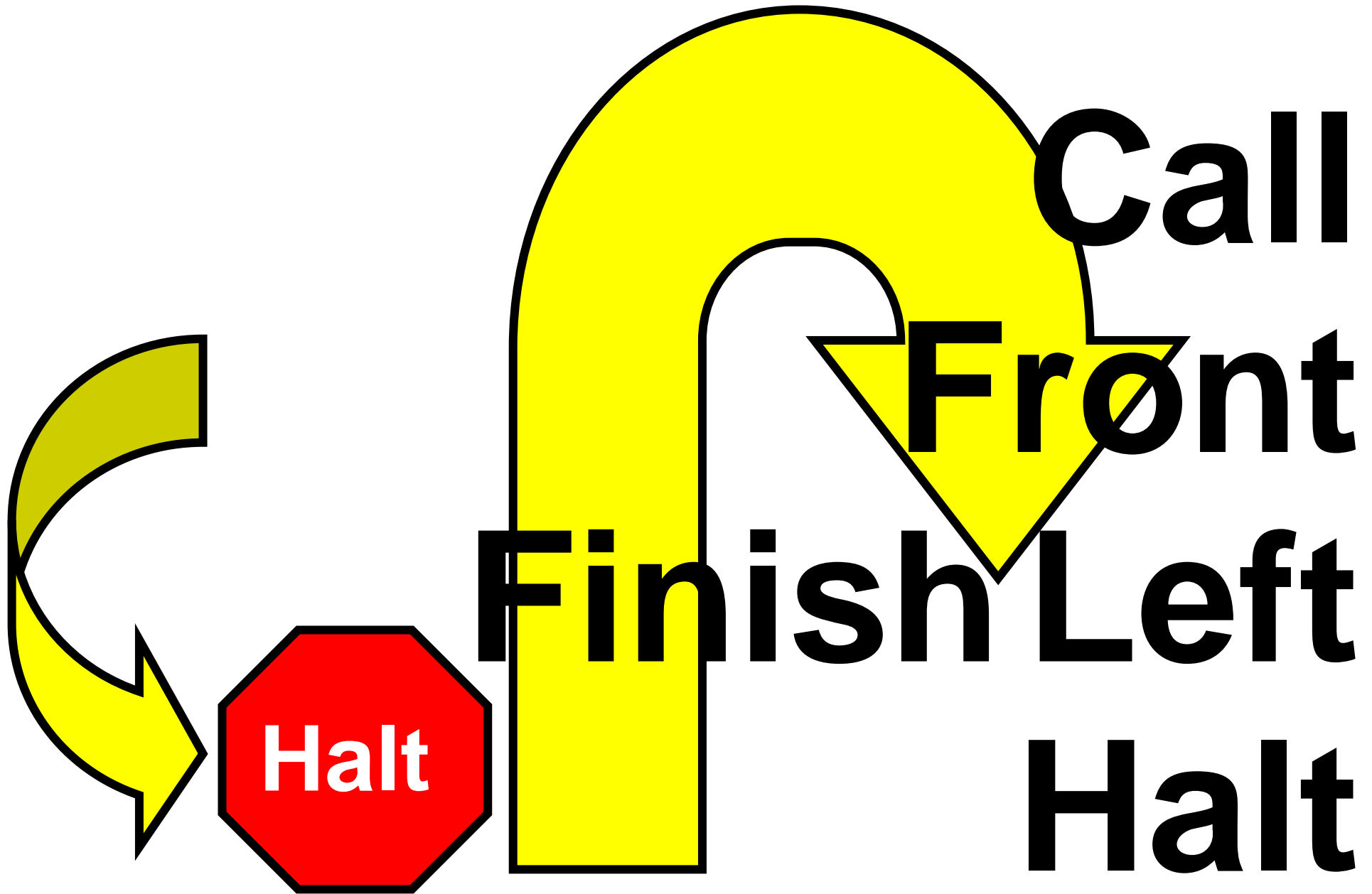
**Call**

**Front**

**Left**

**Forward**









**Slow  
Pace**

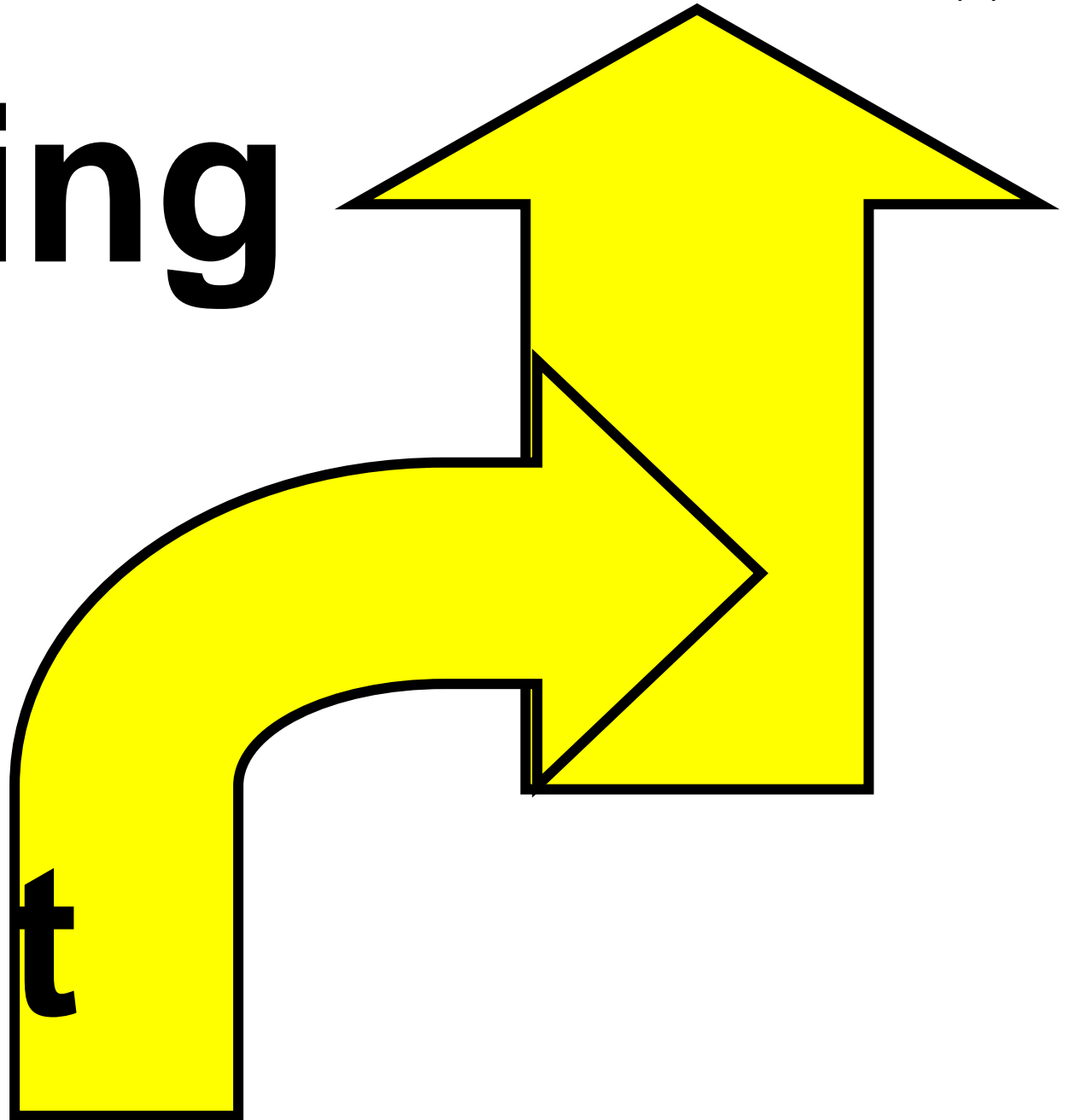


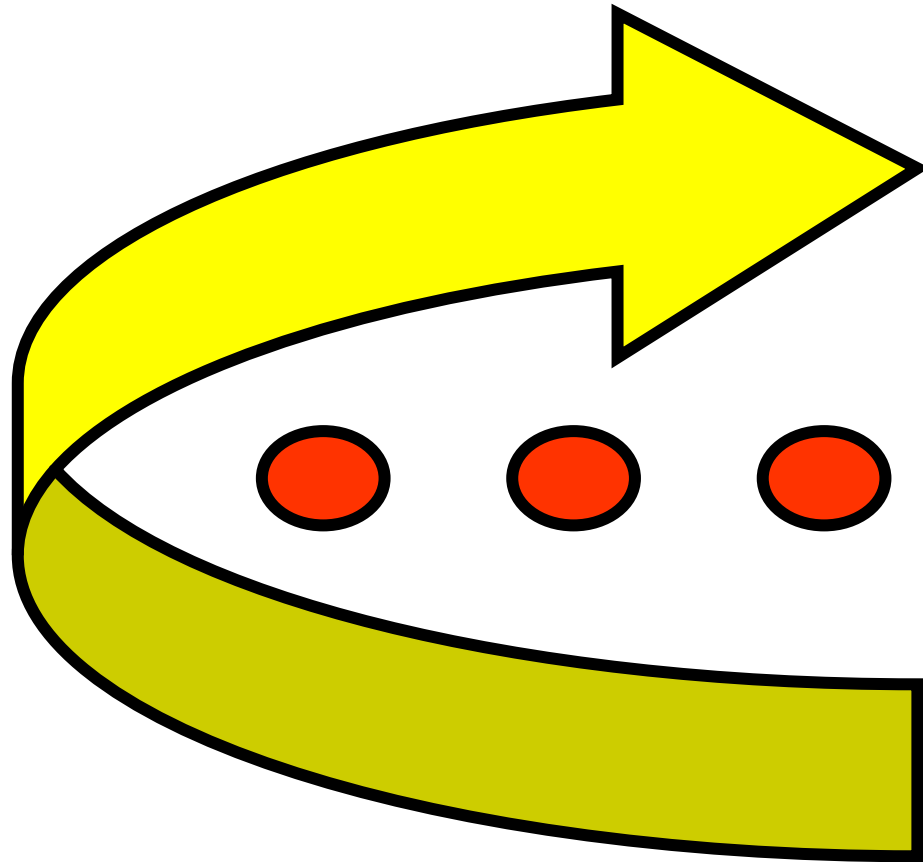
**Fast  
Pace**



**Normal  
Pace**

**Moving**  
**Side**  
**Step**  
**Right**



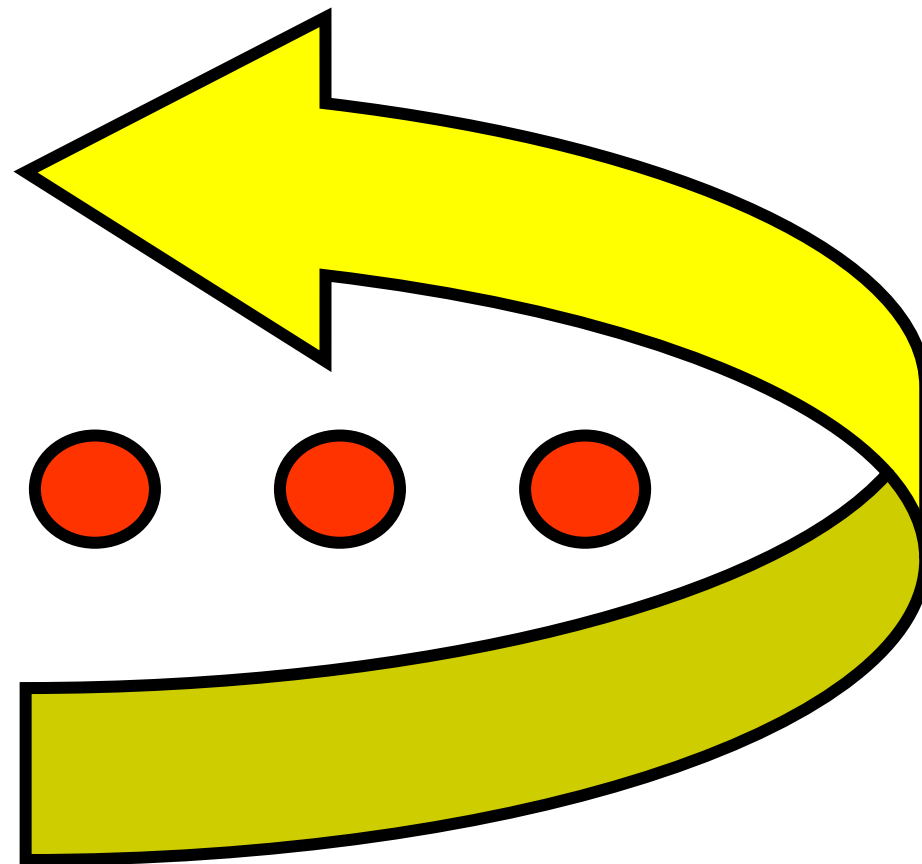


**Spiral  
Right**

**Dog Outside**

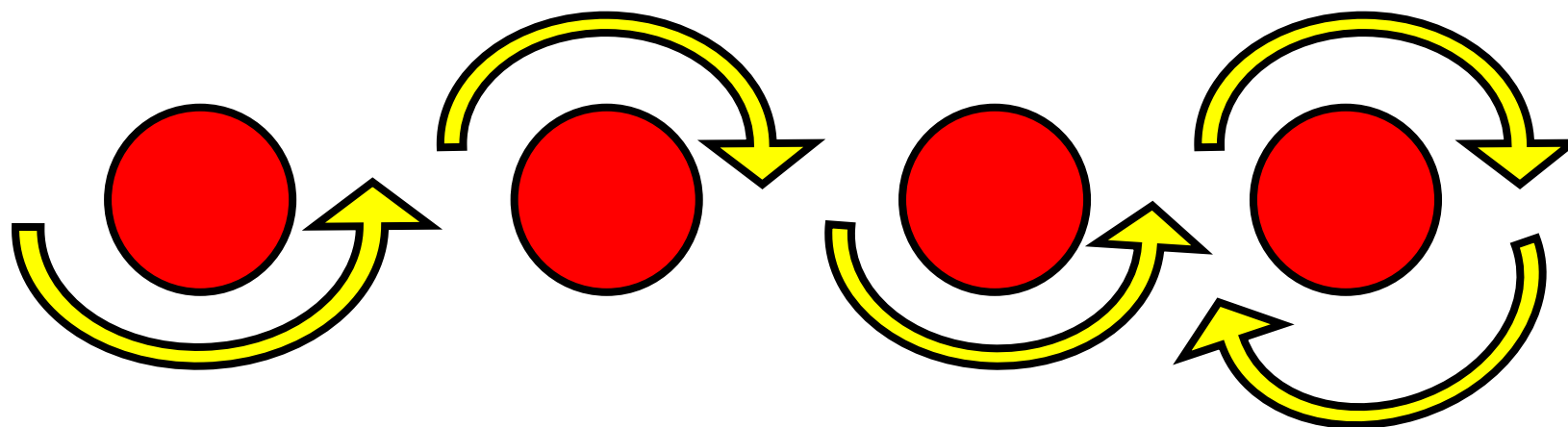
**Spiral**

**Left**

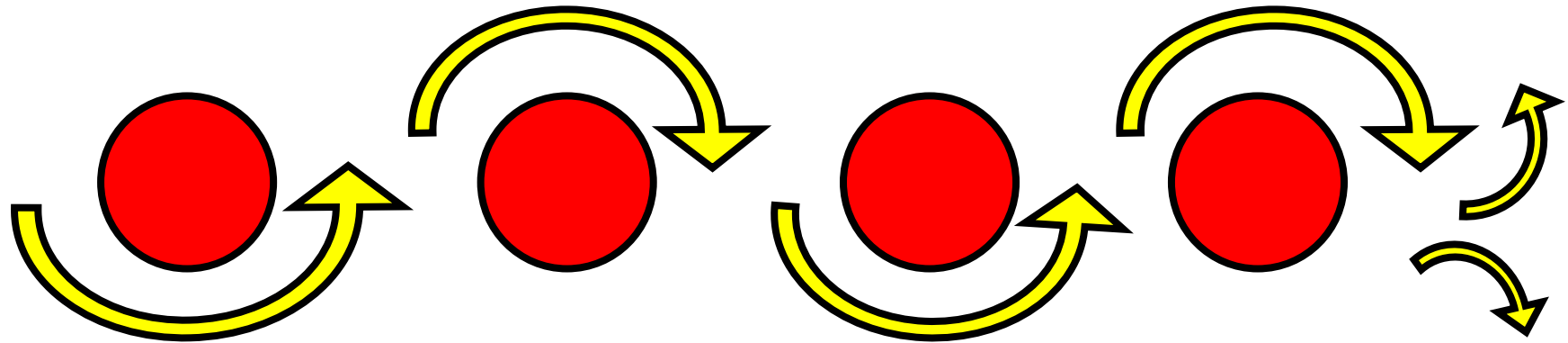


**Dog Inside**

# Weave Twice



# Weave Once







**1 Step**

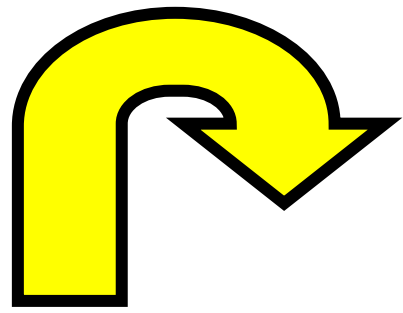


**2 Steps**



**3 Steps**





# Call Front

**1 Step Back**



**2 Steps Back**



**3 Steps Back**

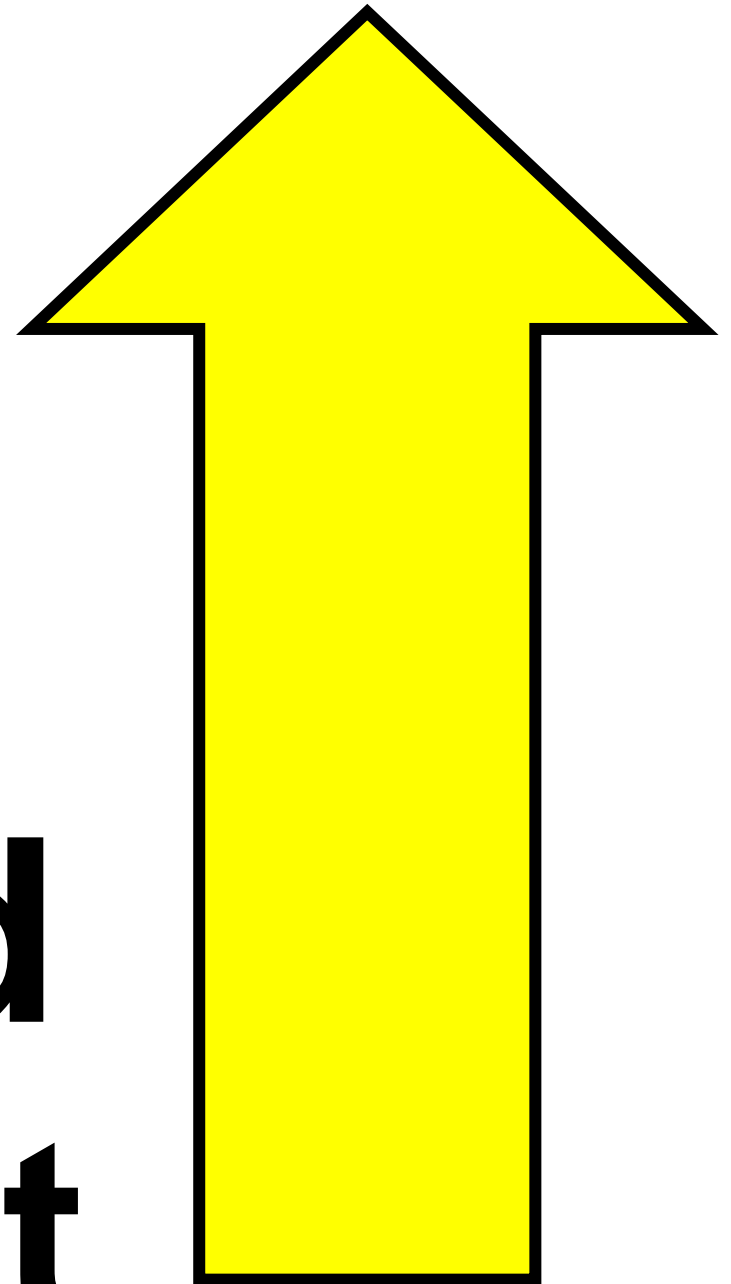




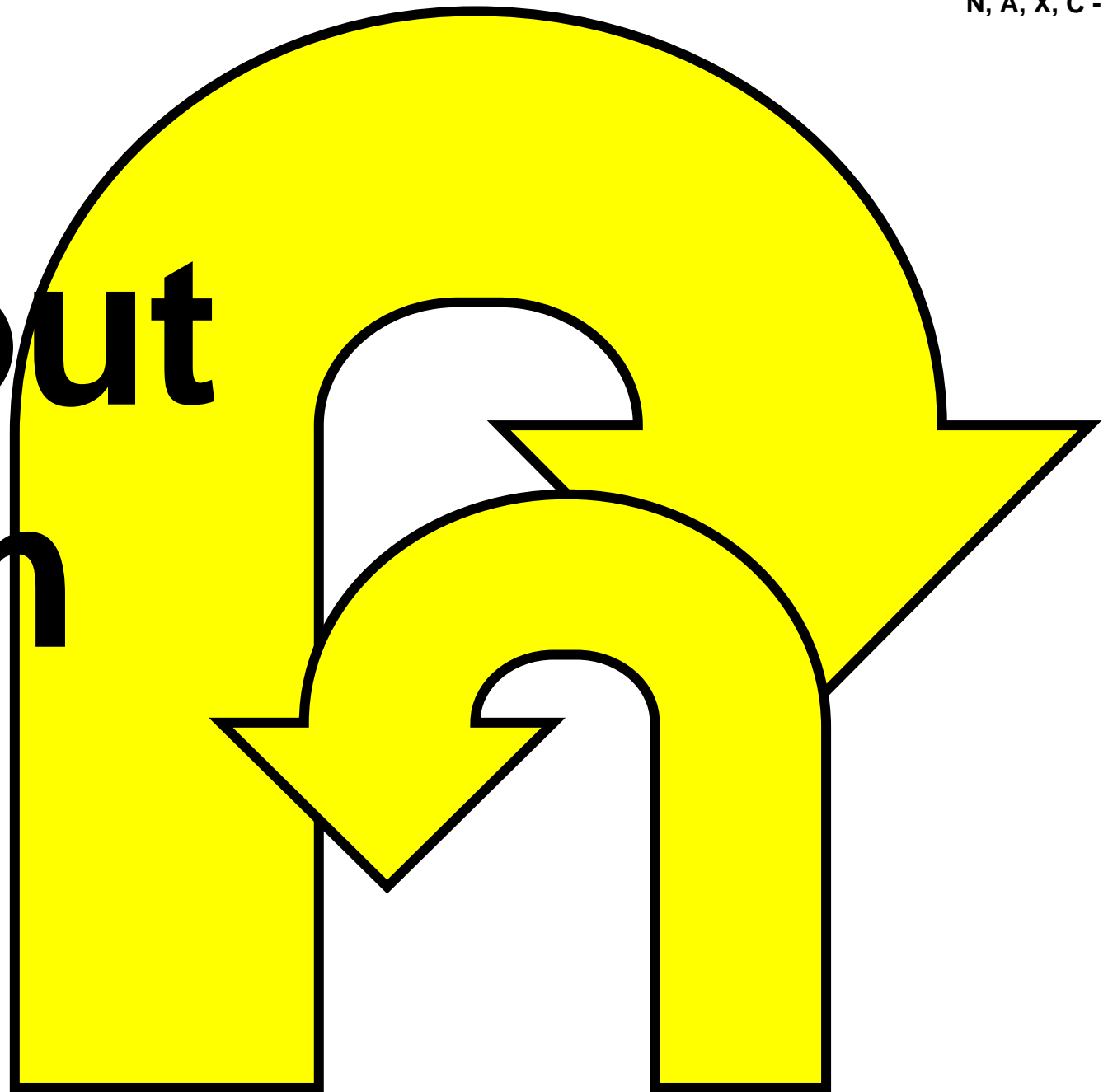
**Fast**

**Forward**

**From Sit**

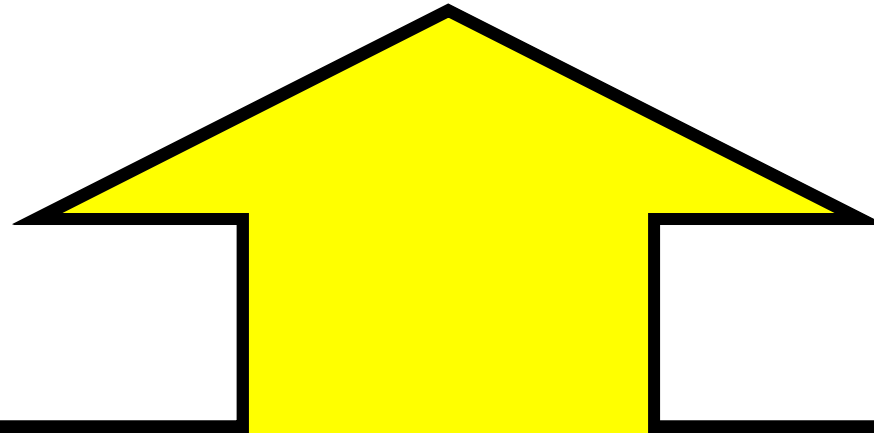


# Left About Turn

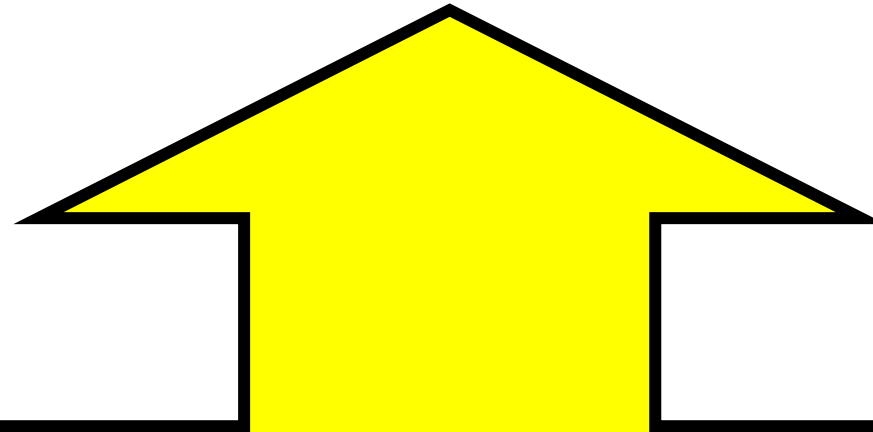


DOG

HANDLER



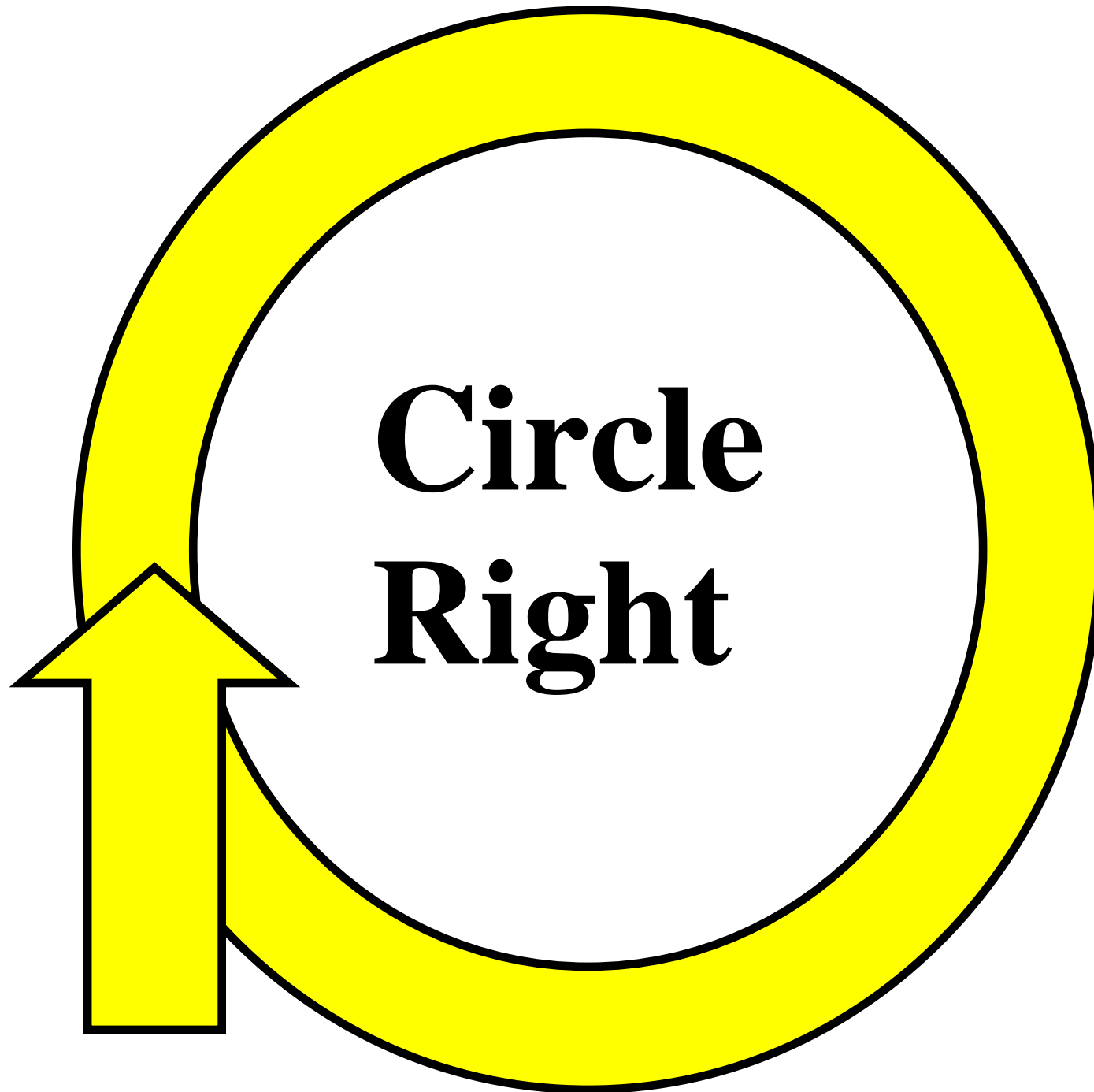
**Walk Around  
Dog**



**Down  
Walk Around  
Dog**

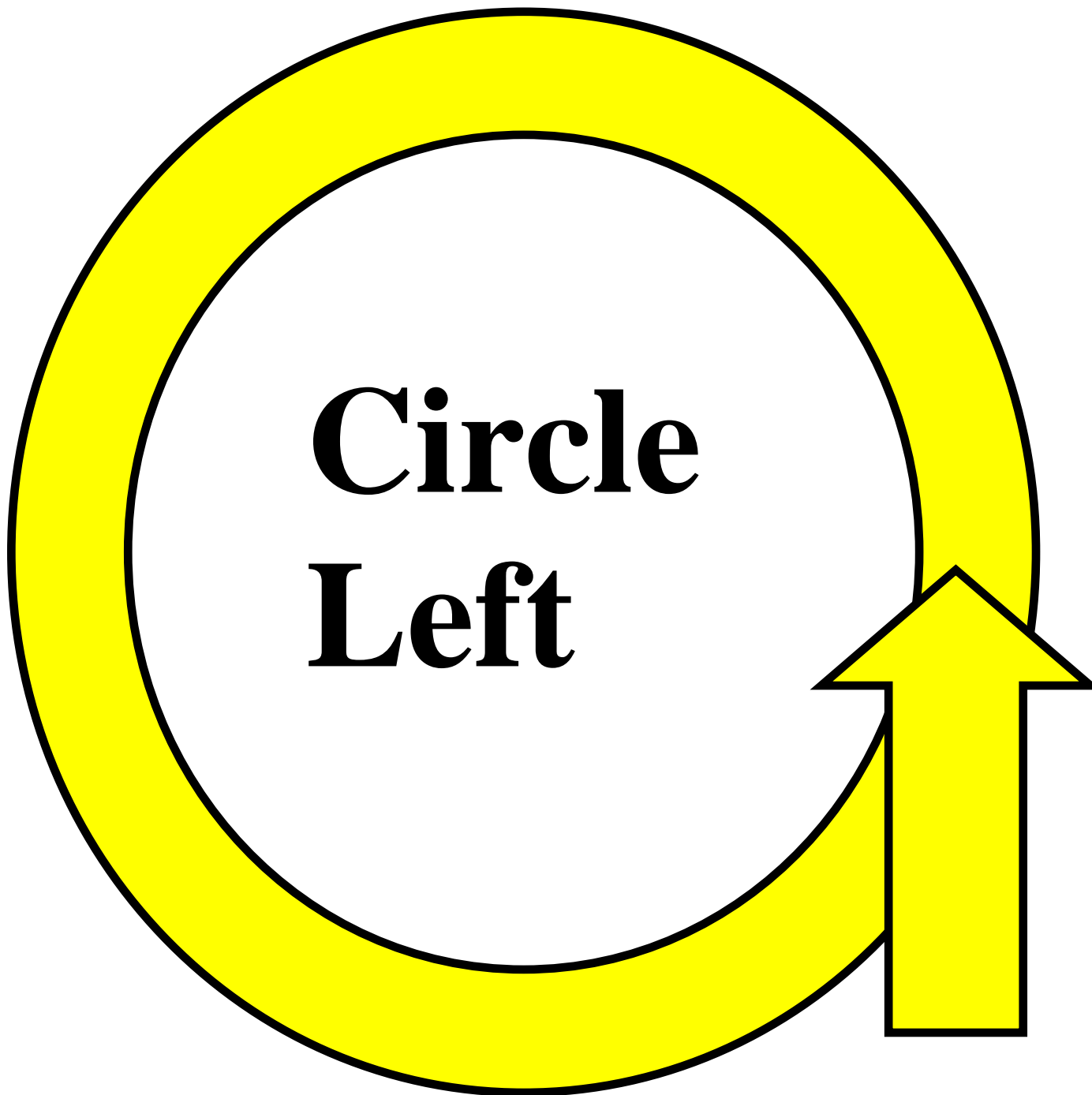


**Off-Set**  
**Figure Eight**

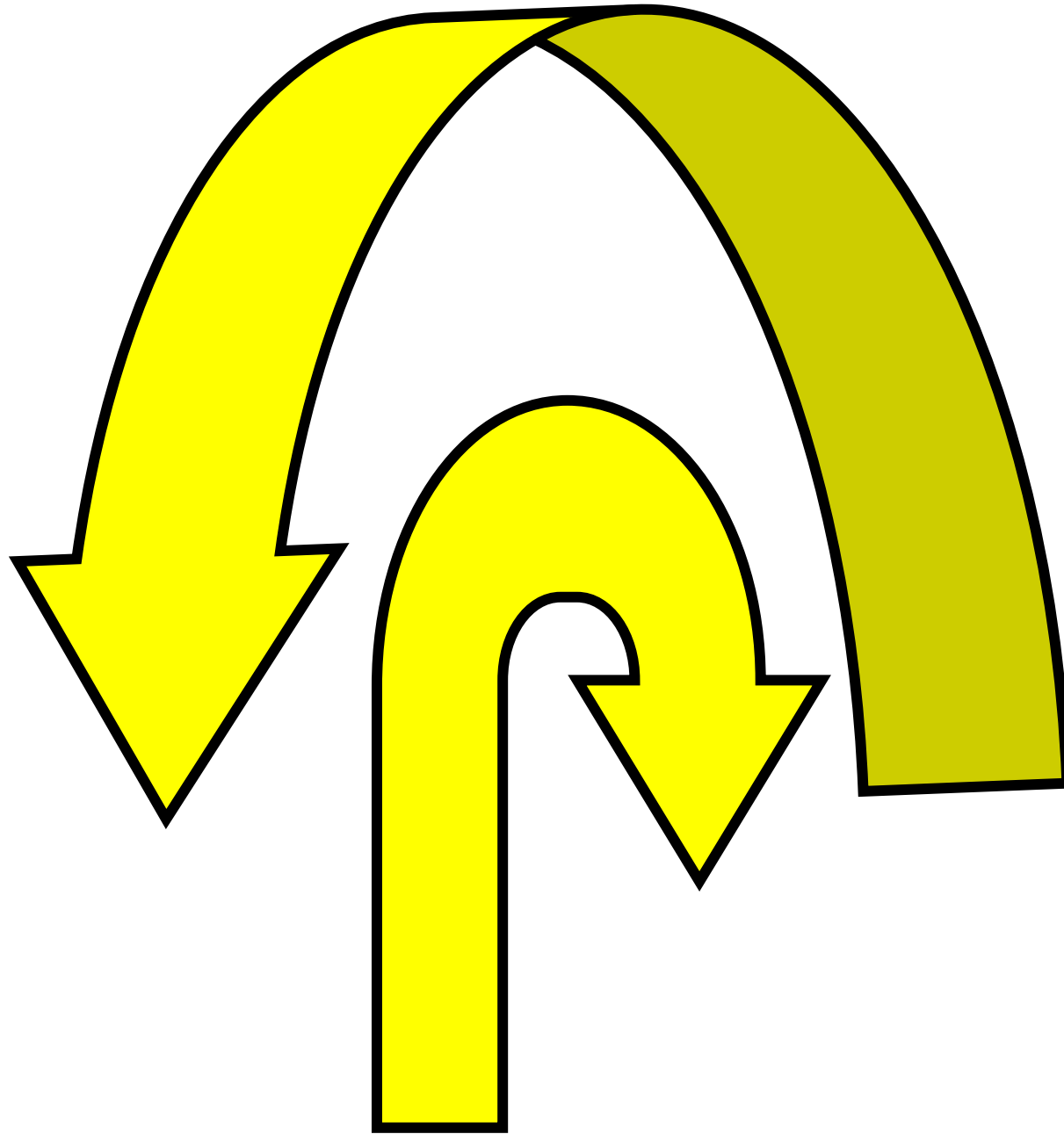


**Circle**  
**Right**

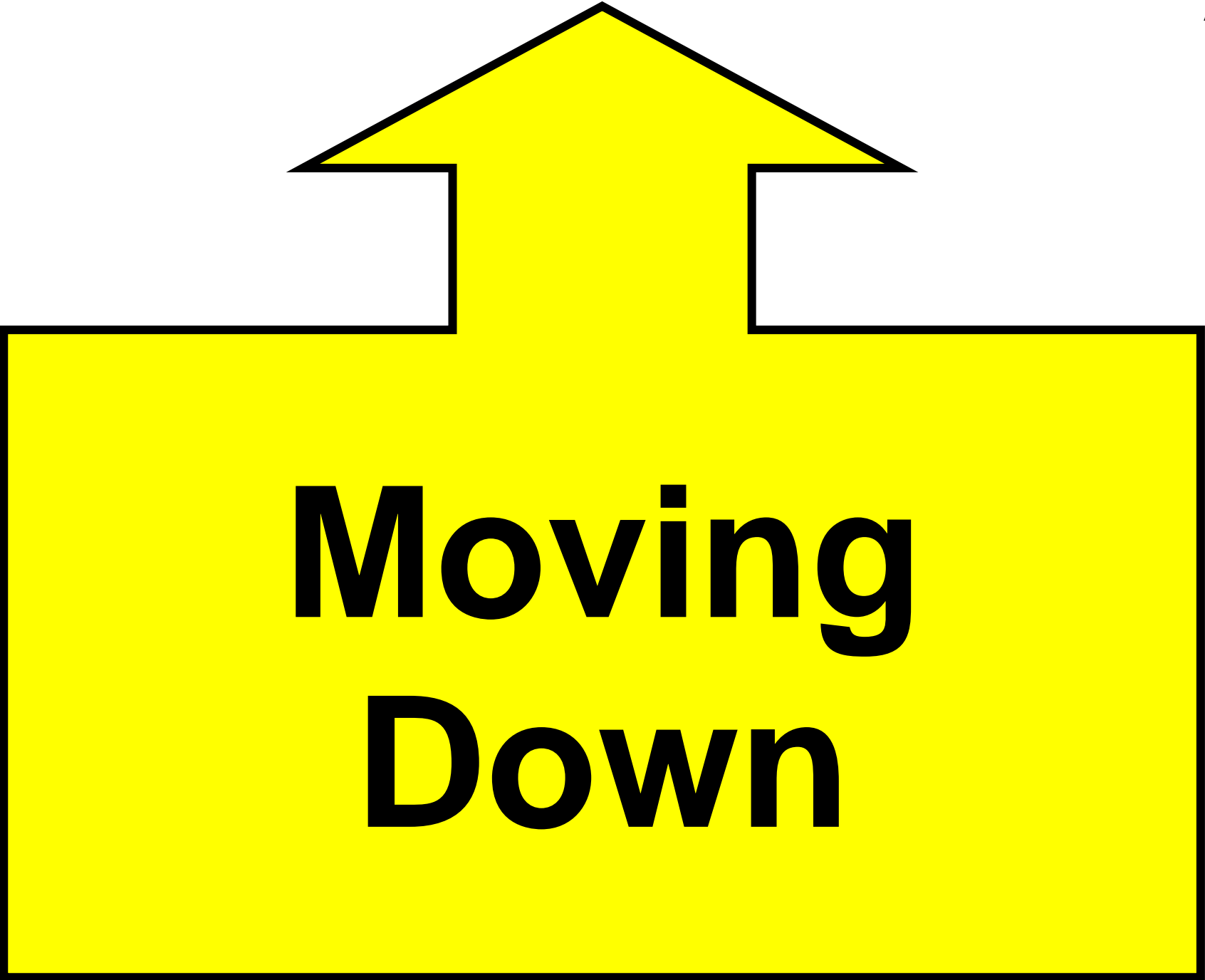




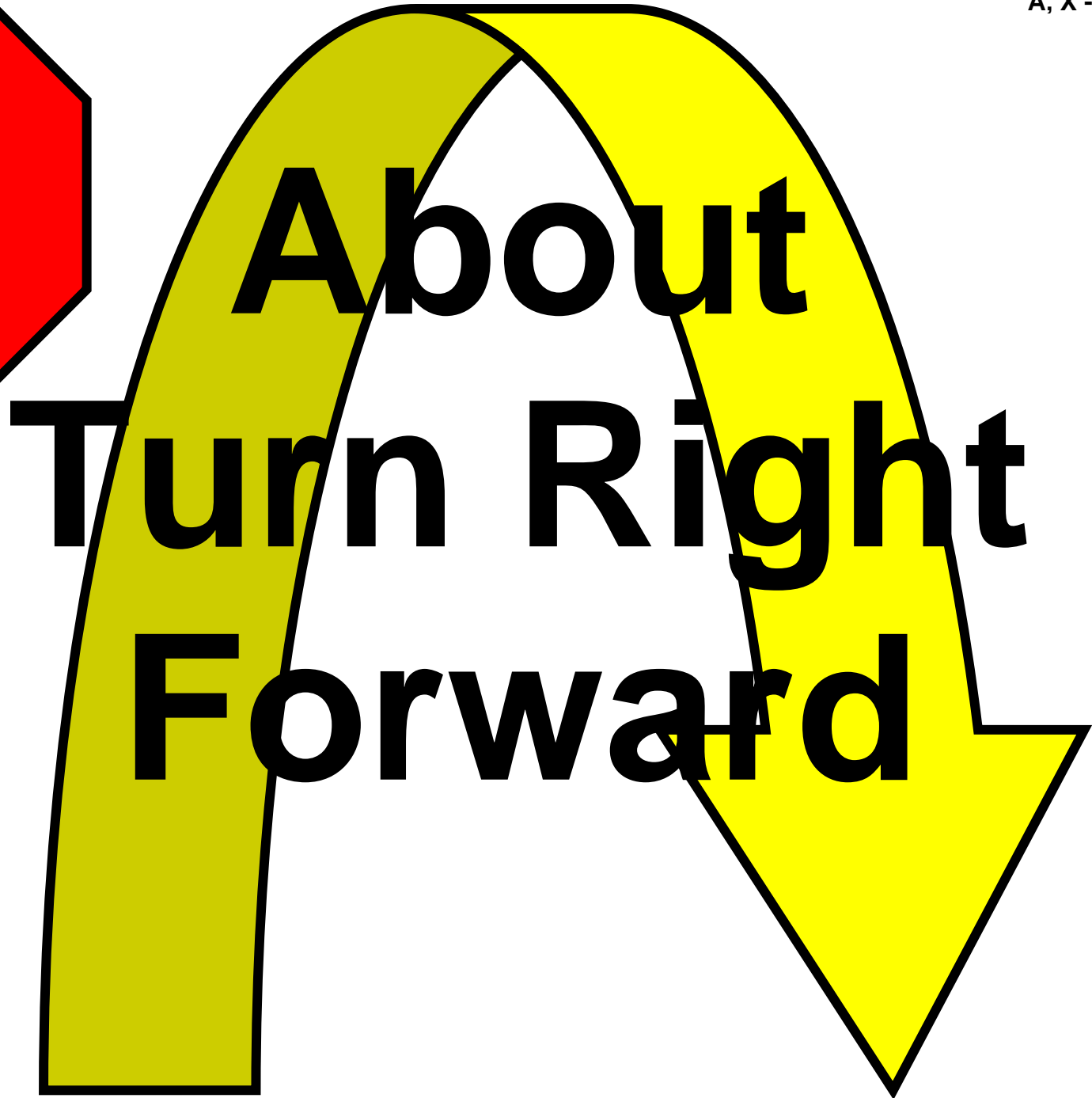
**Circle  
Left**

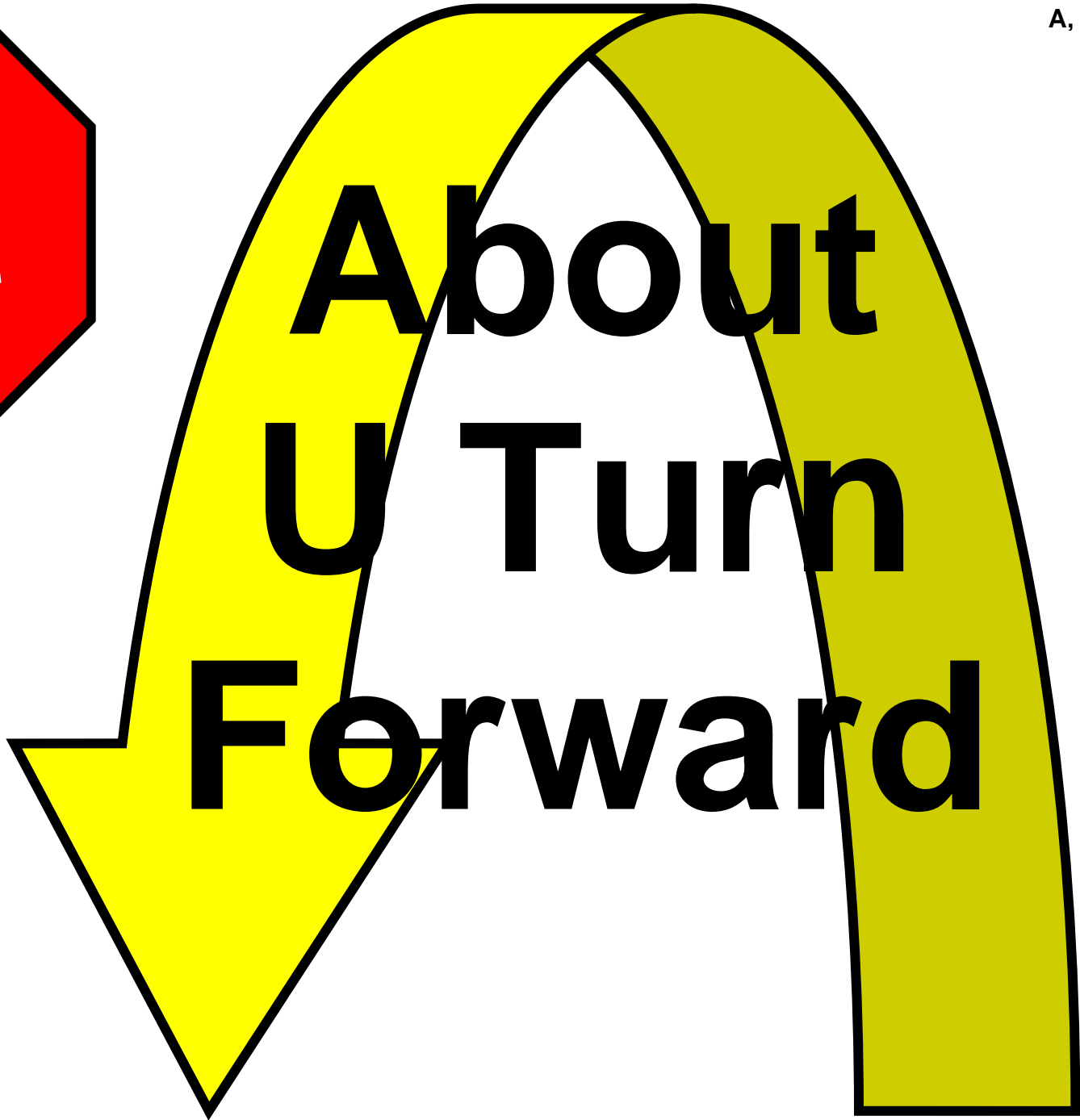


**Call  
Front  
Return  
To Heel**

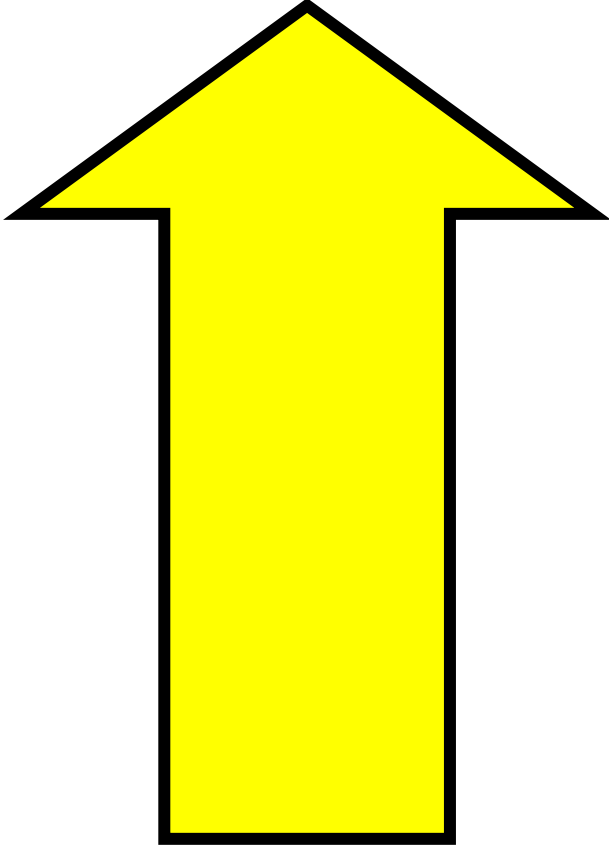
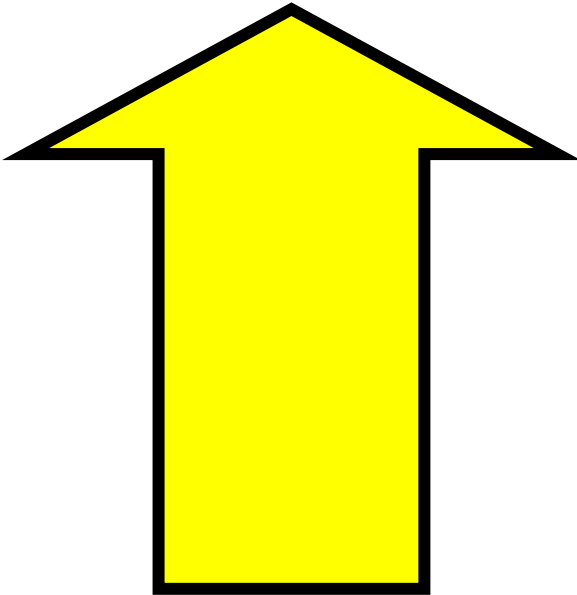


**Moving  
Down**





# Send Over Jump

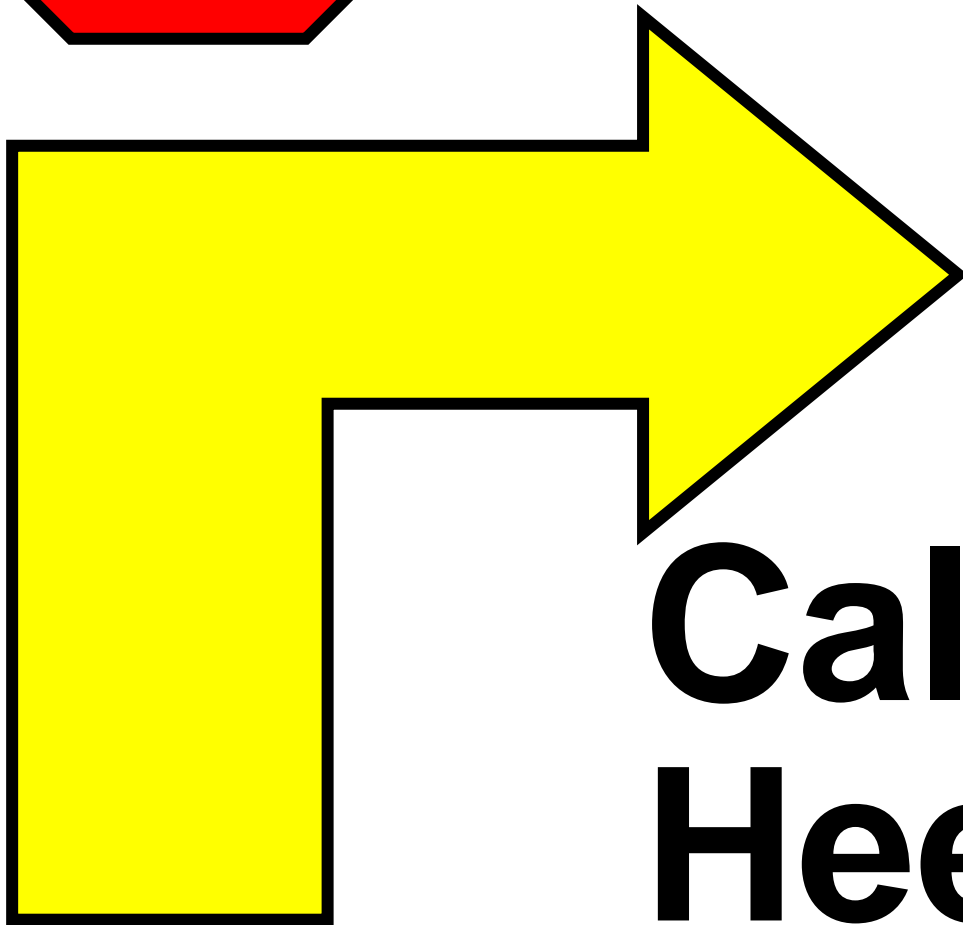
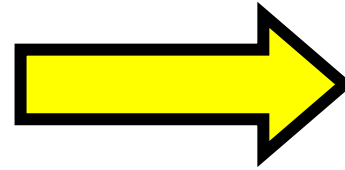


Handler Passes By



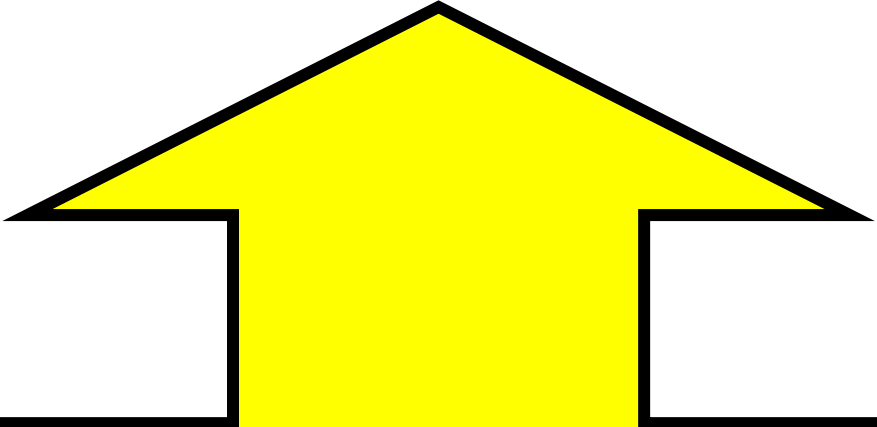
**Turn Right**

**1 Step**



**Call To  
Heel**



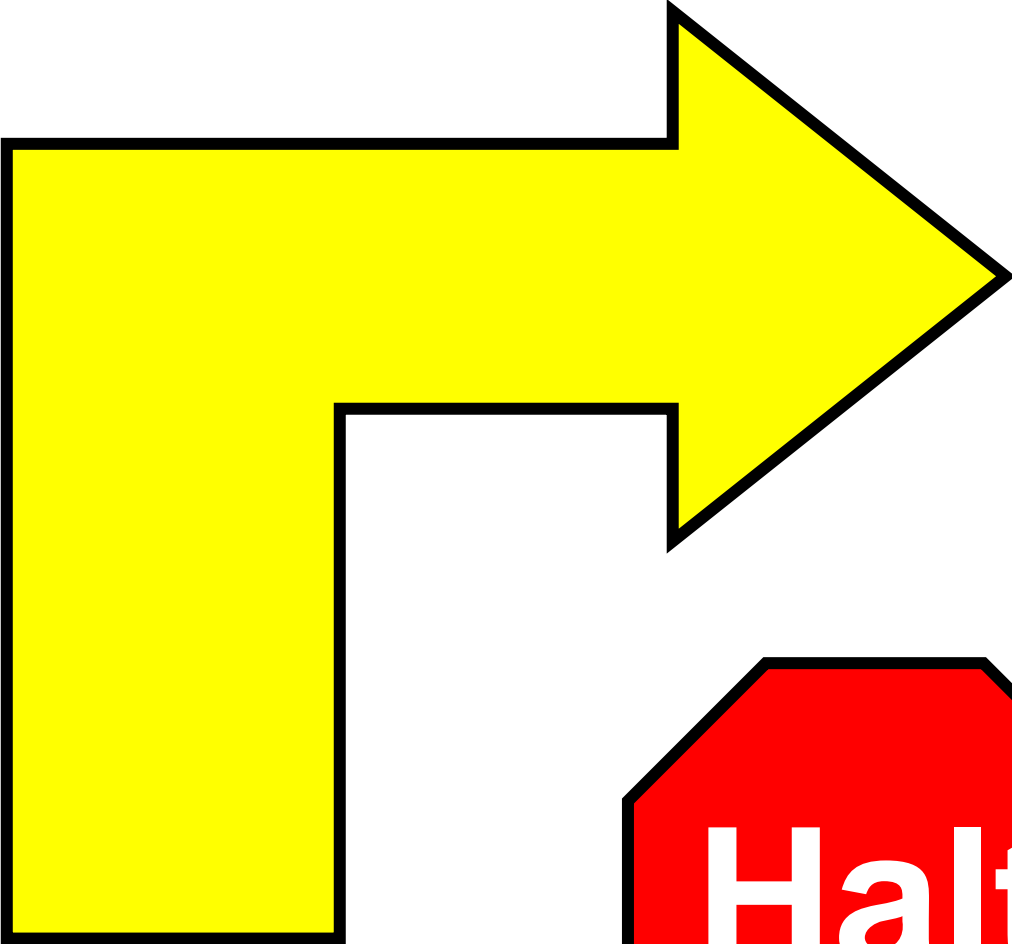


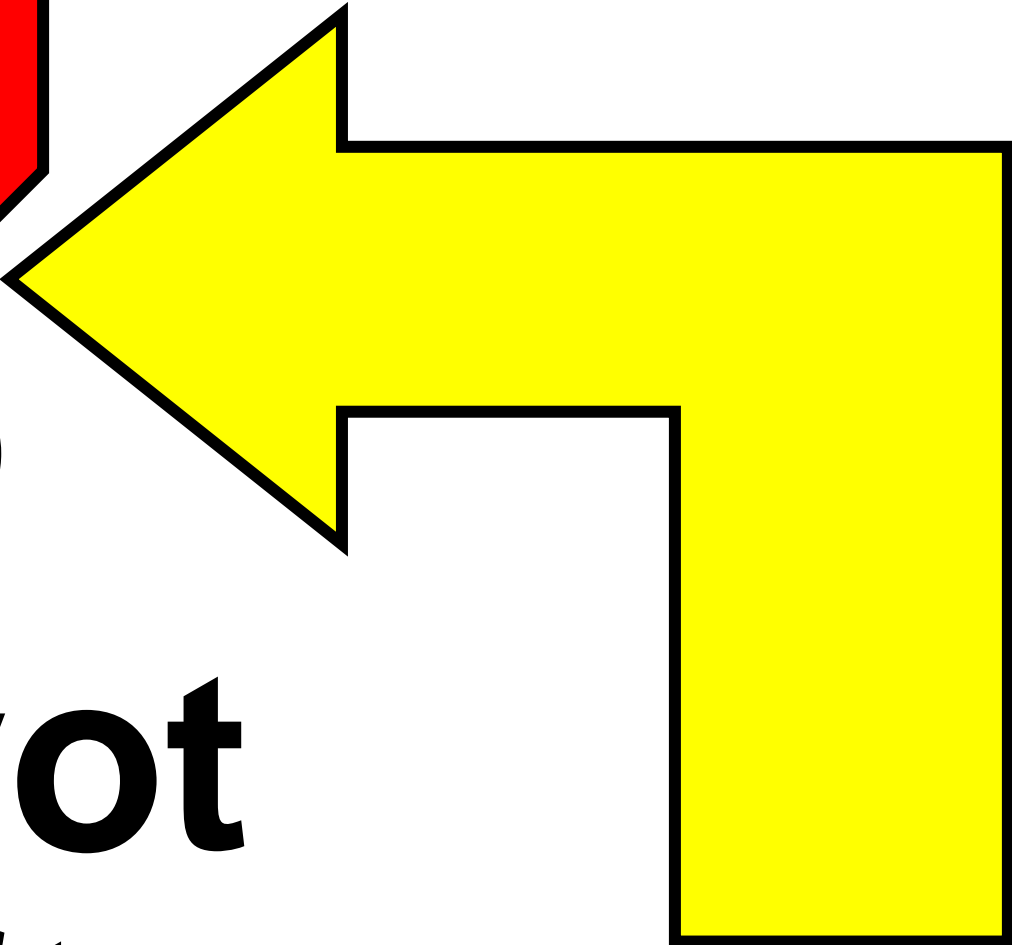
**Stand  
Walk Around  
Dog**





**90°  
Pivot  
Right**



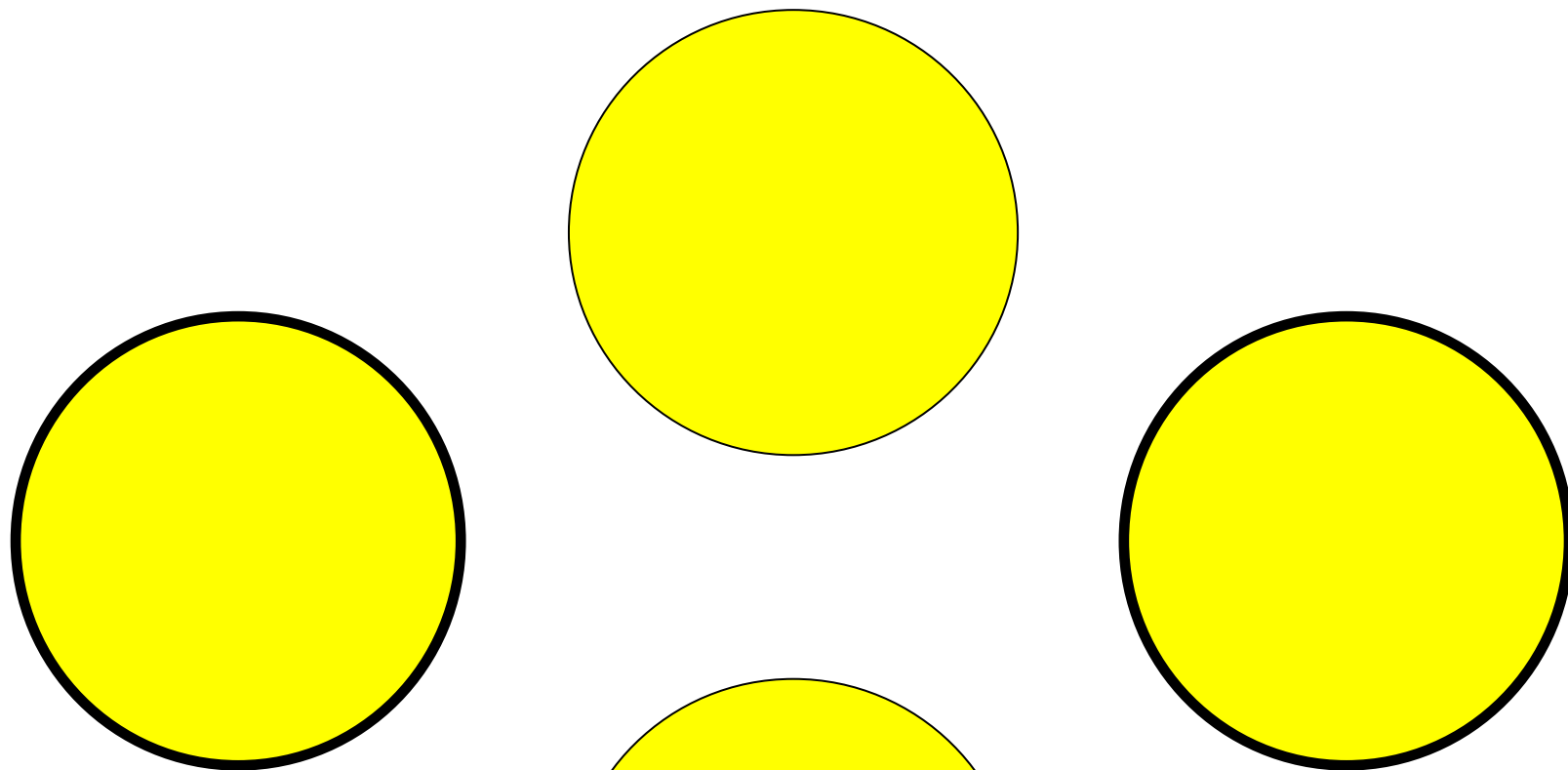


**90°**

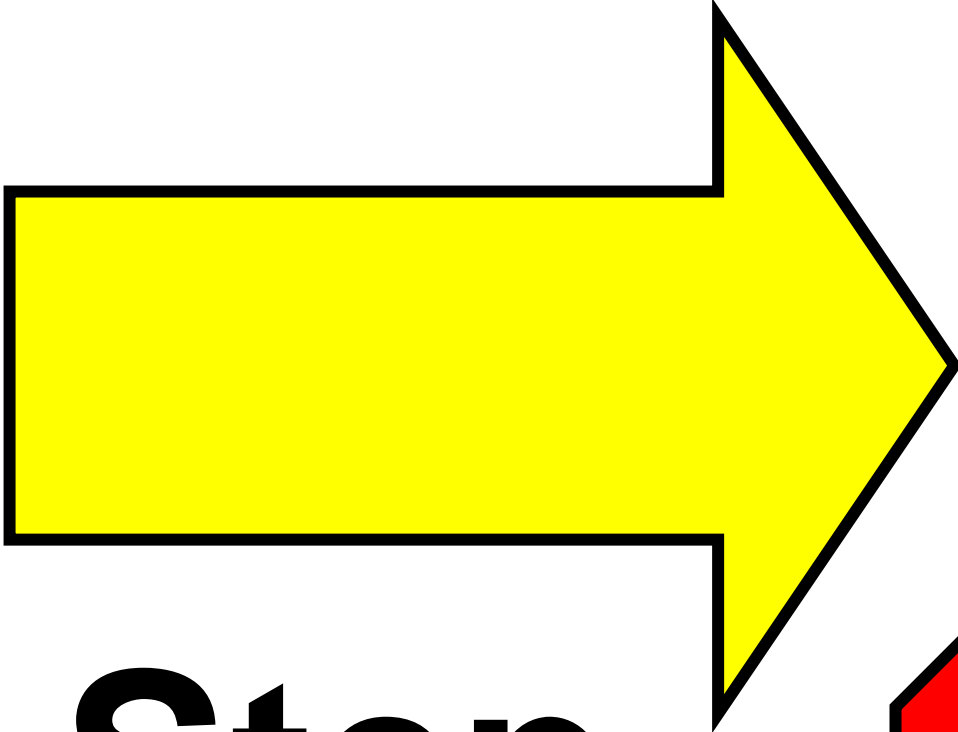
**Pivot**

**Left**

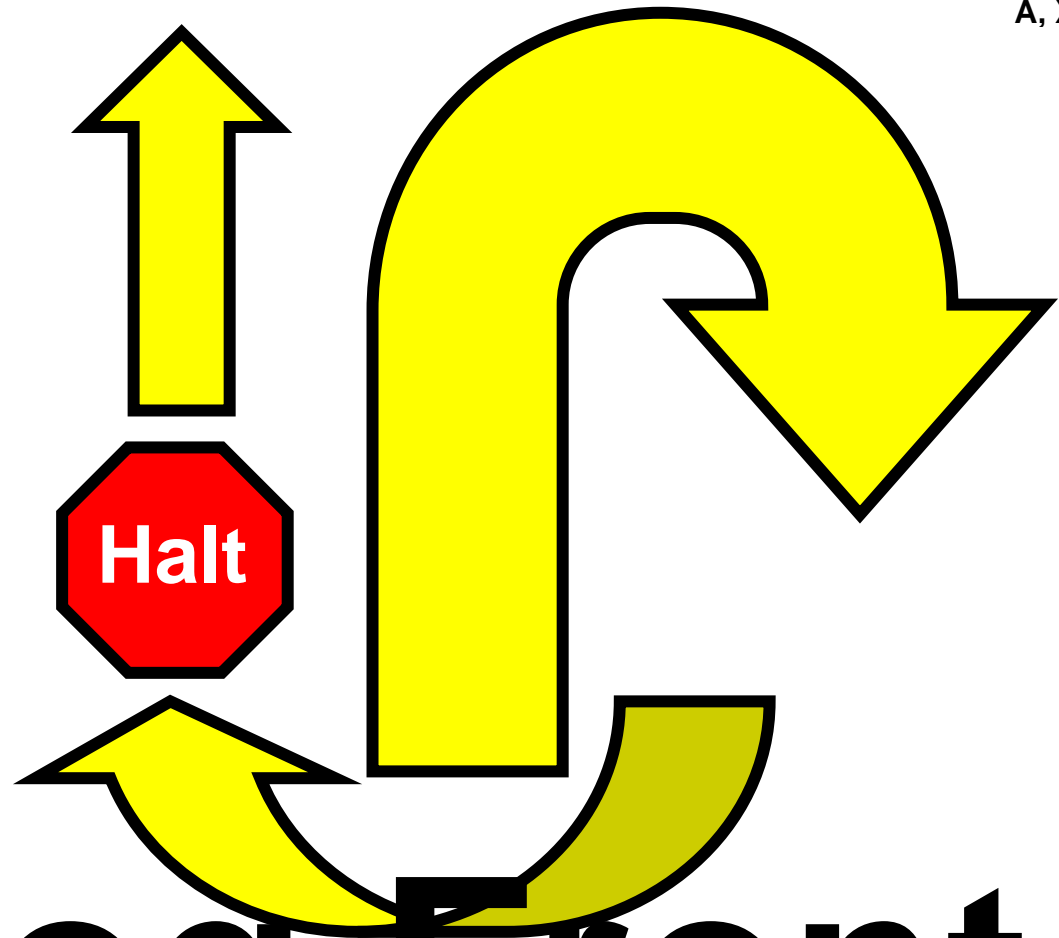




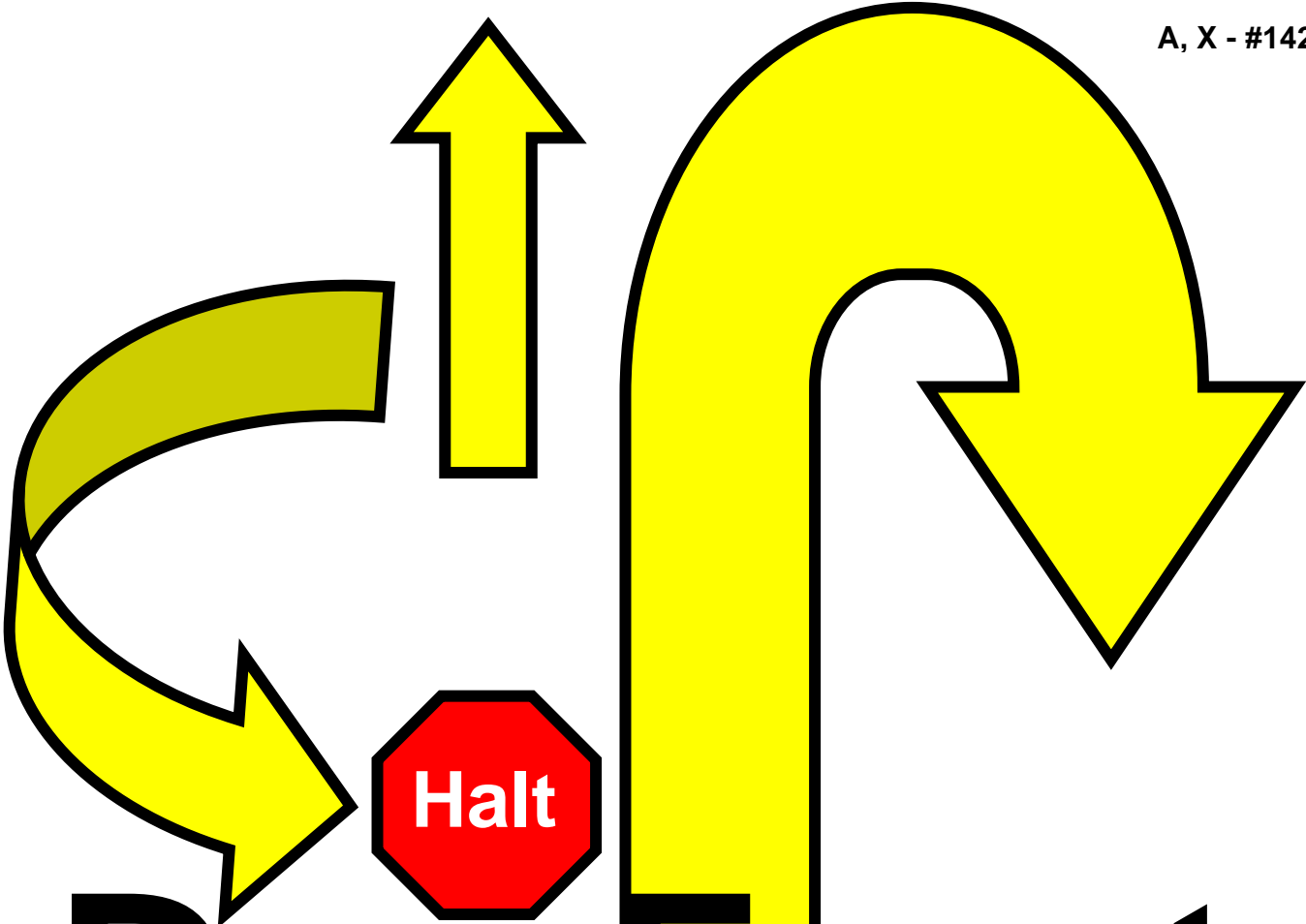
# Off-Set Figure Eight



**Side Step**  
**Right**



**Call Dog Front**  
**Finish Right**

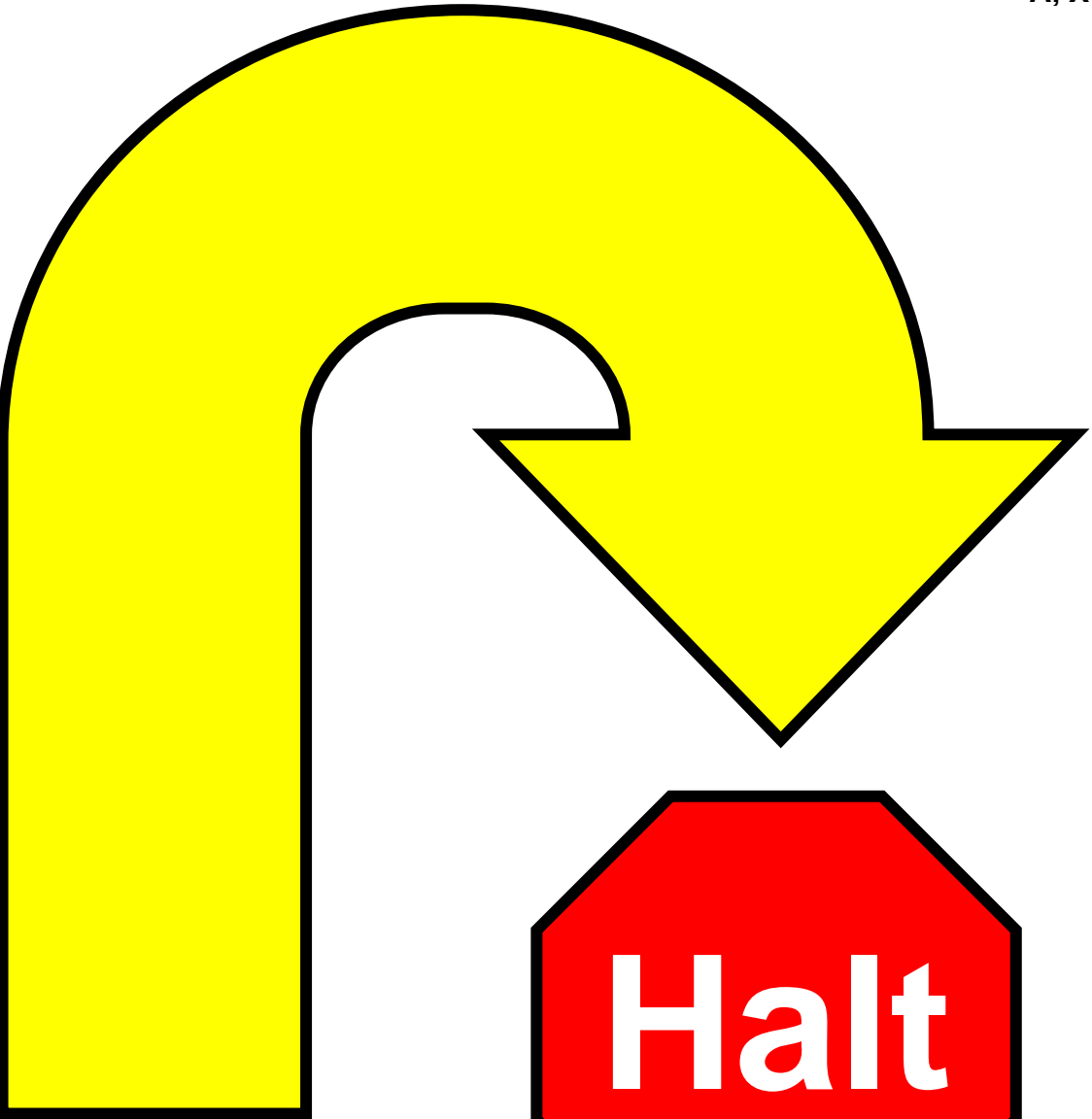


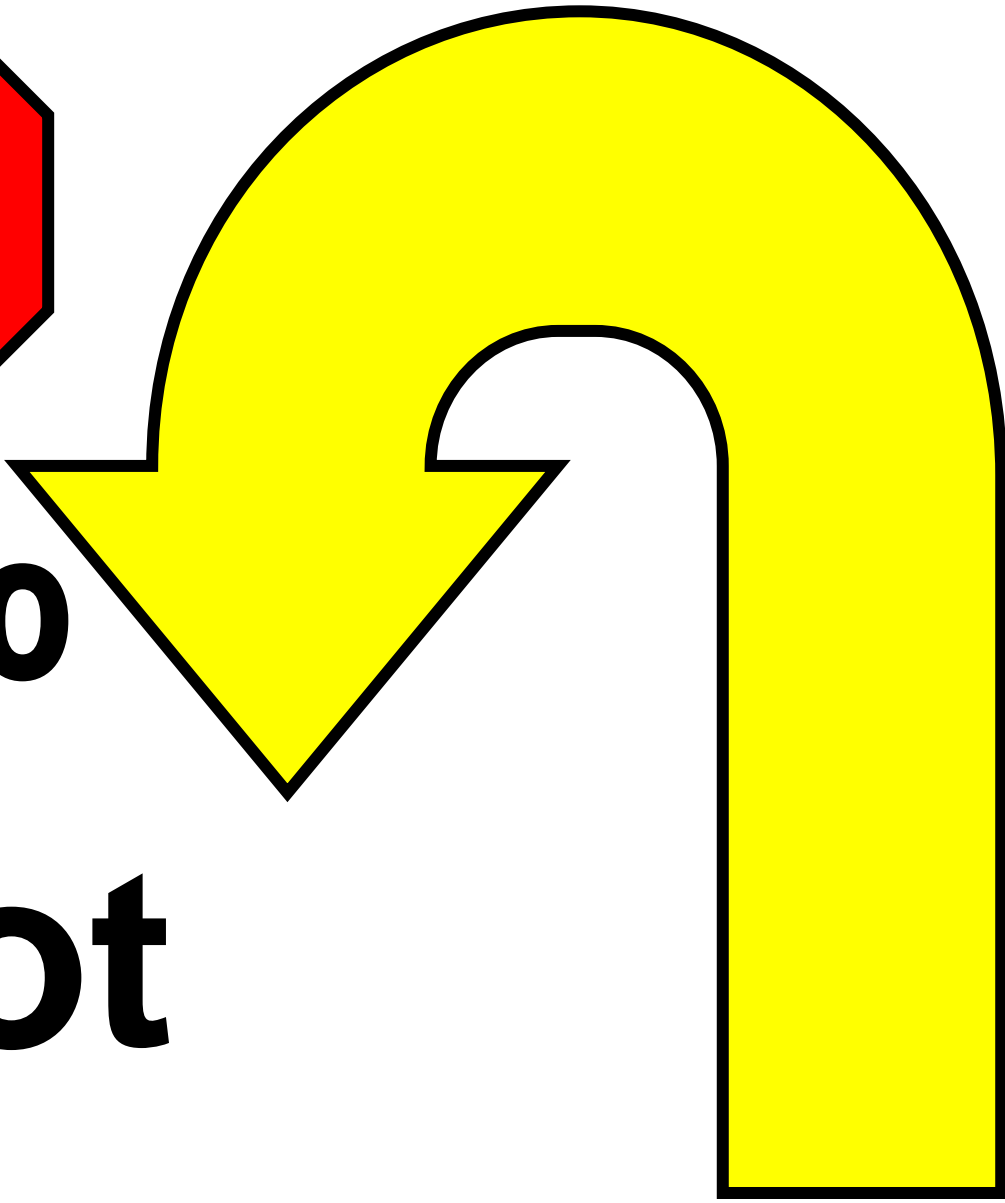
**Call Dog Front**

**Finish Left**



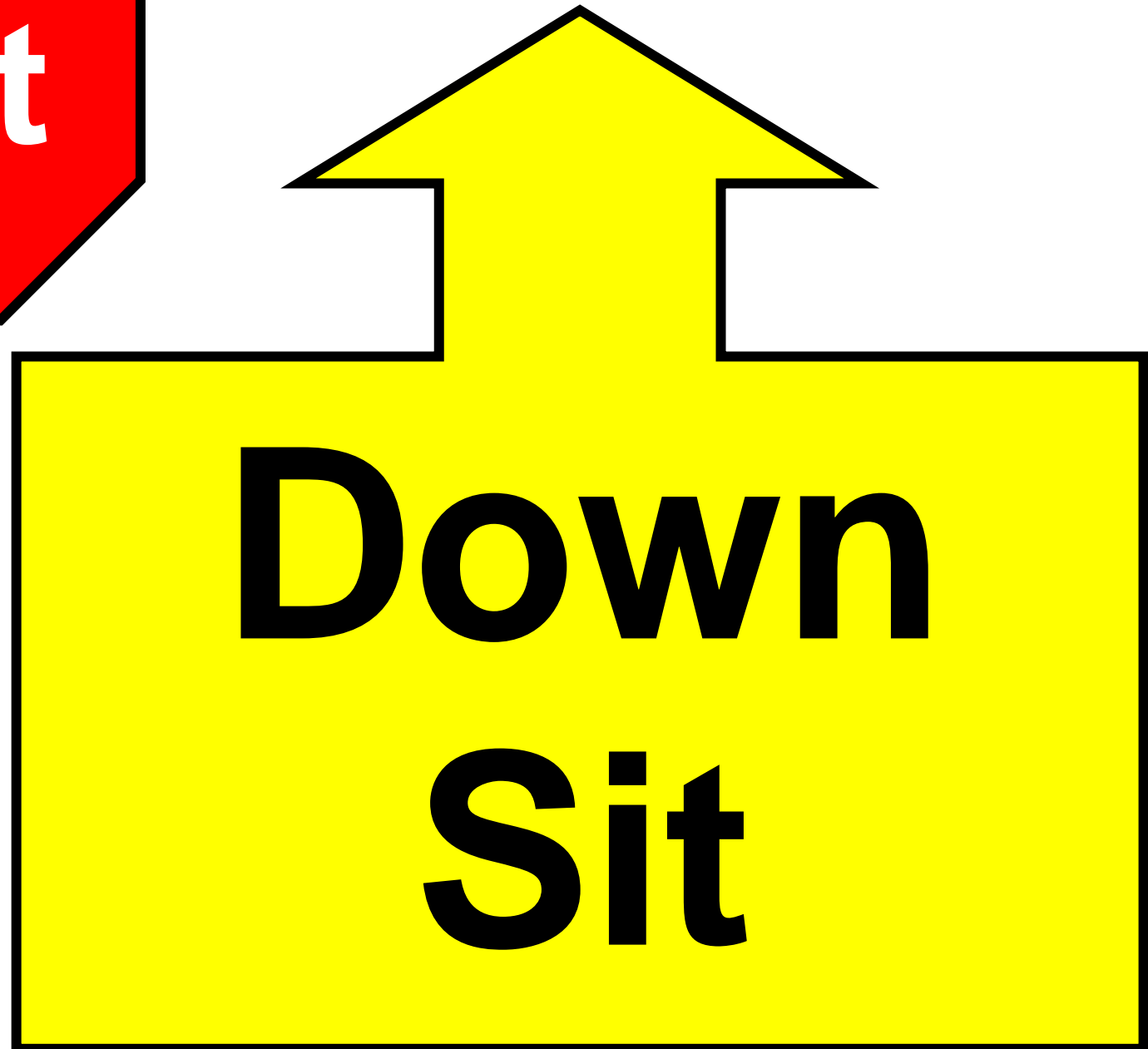
**180°  
Pivot  
Right**

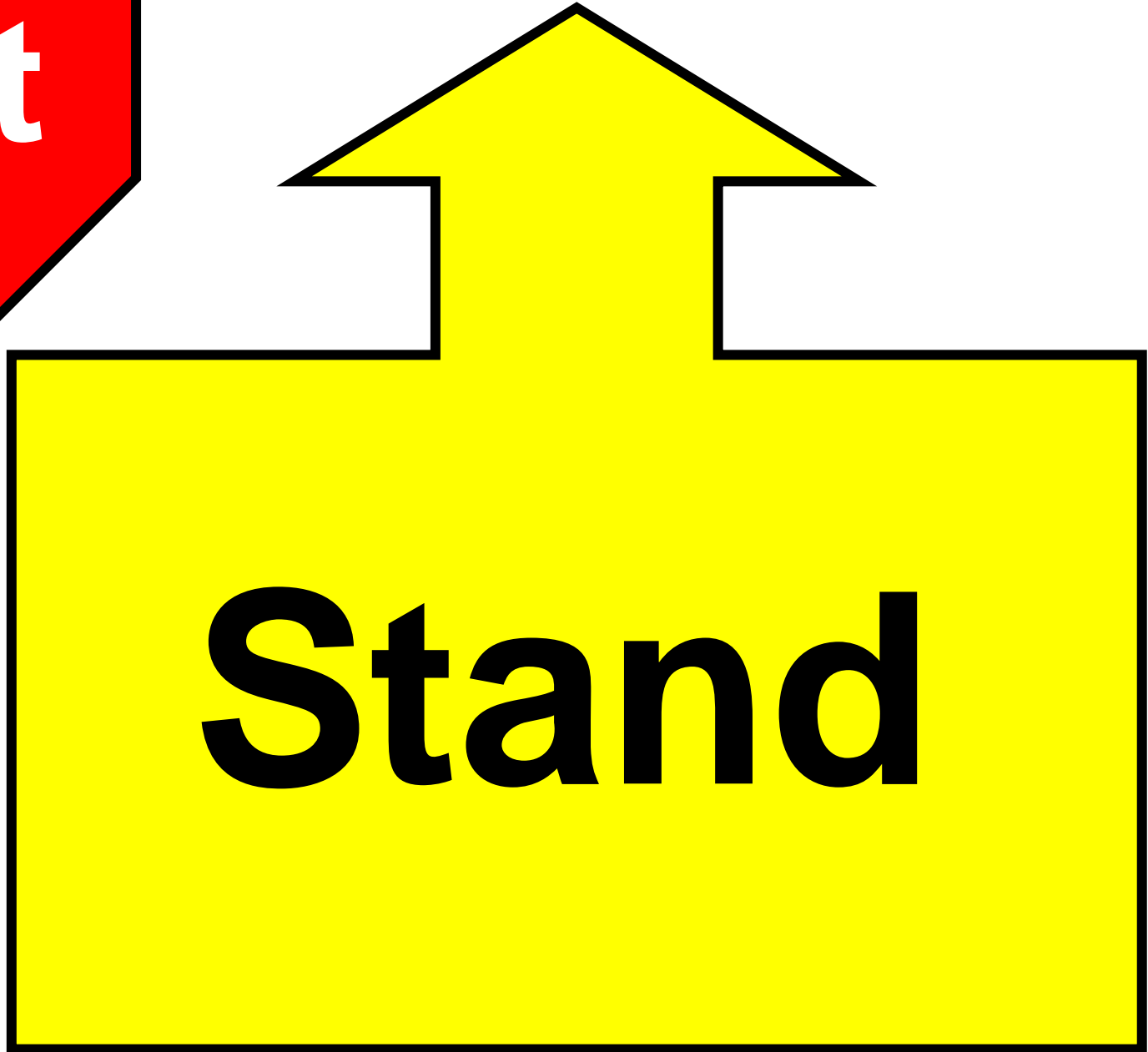




**180°  
Pivot  
Left**

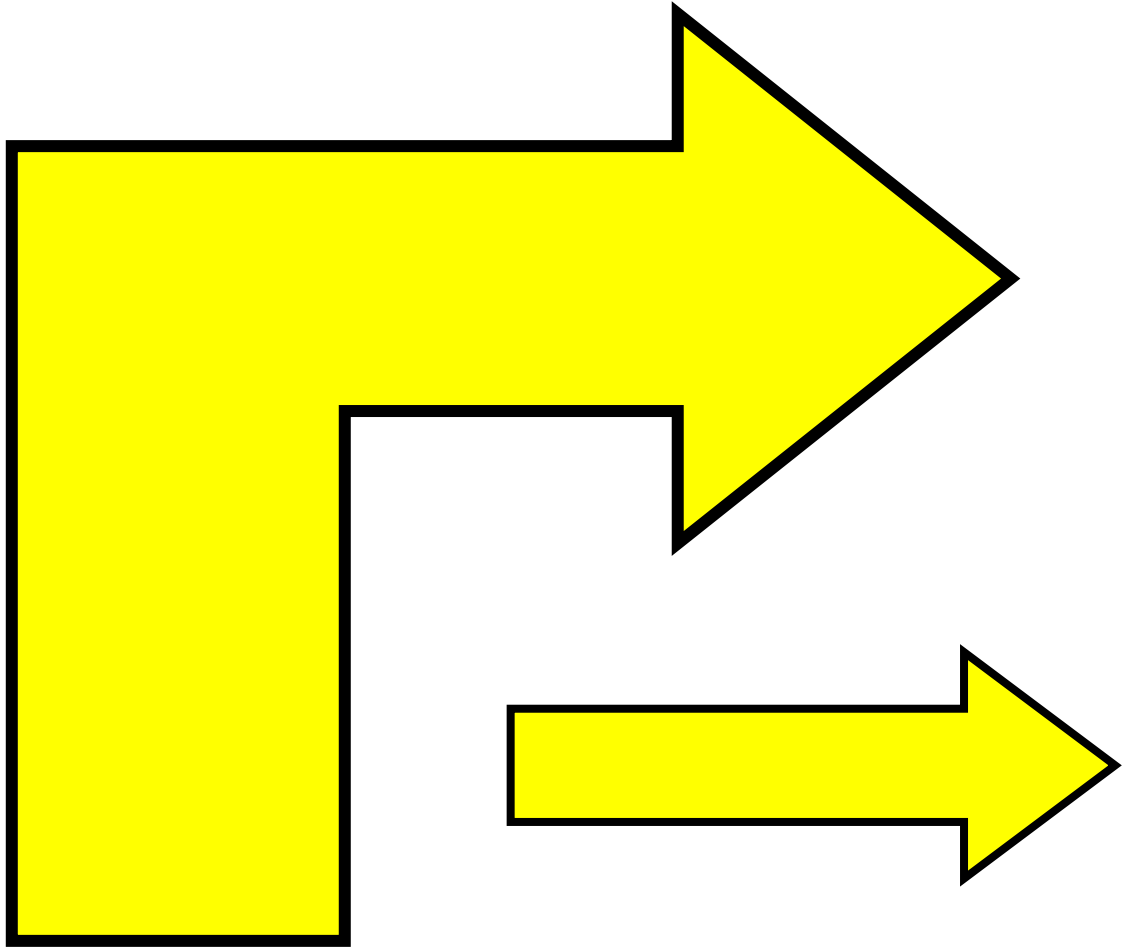




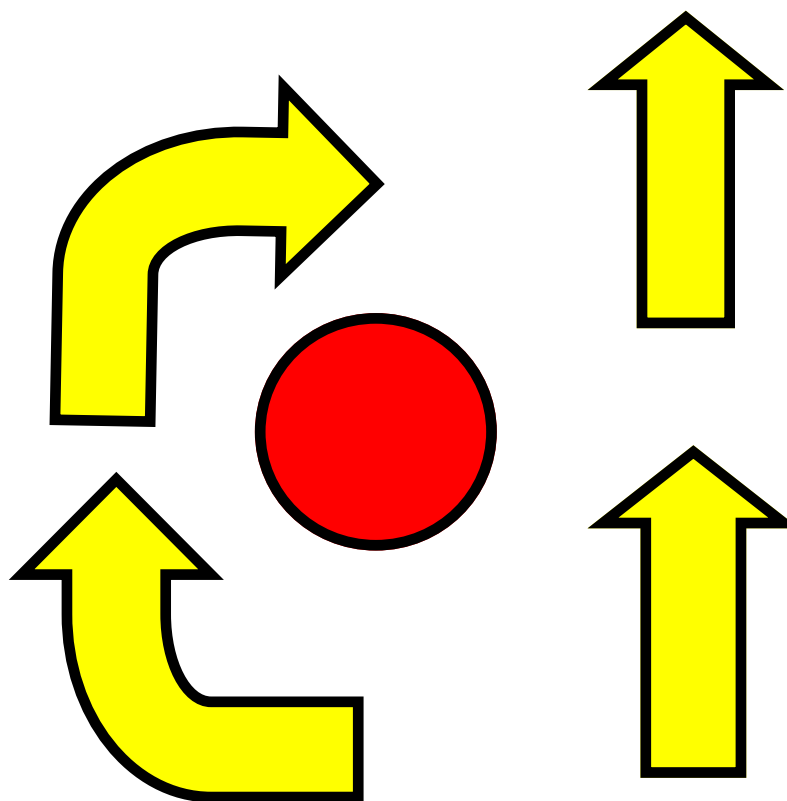




**Pivot  
Right**

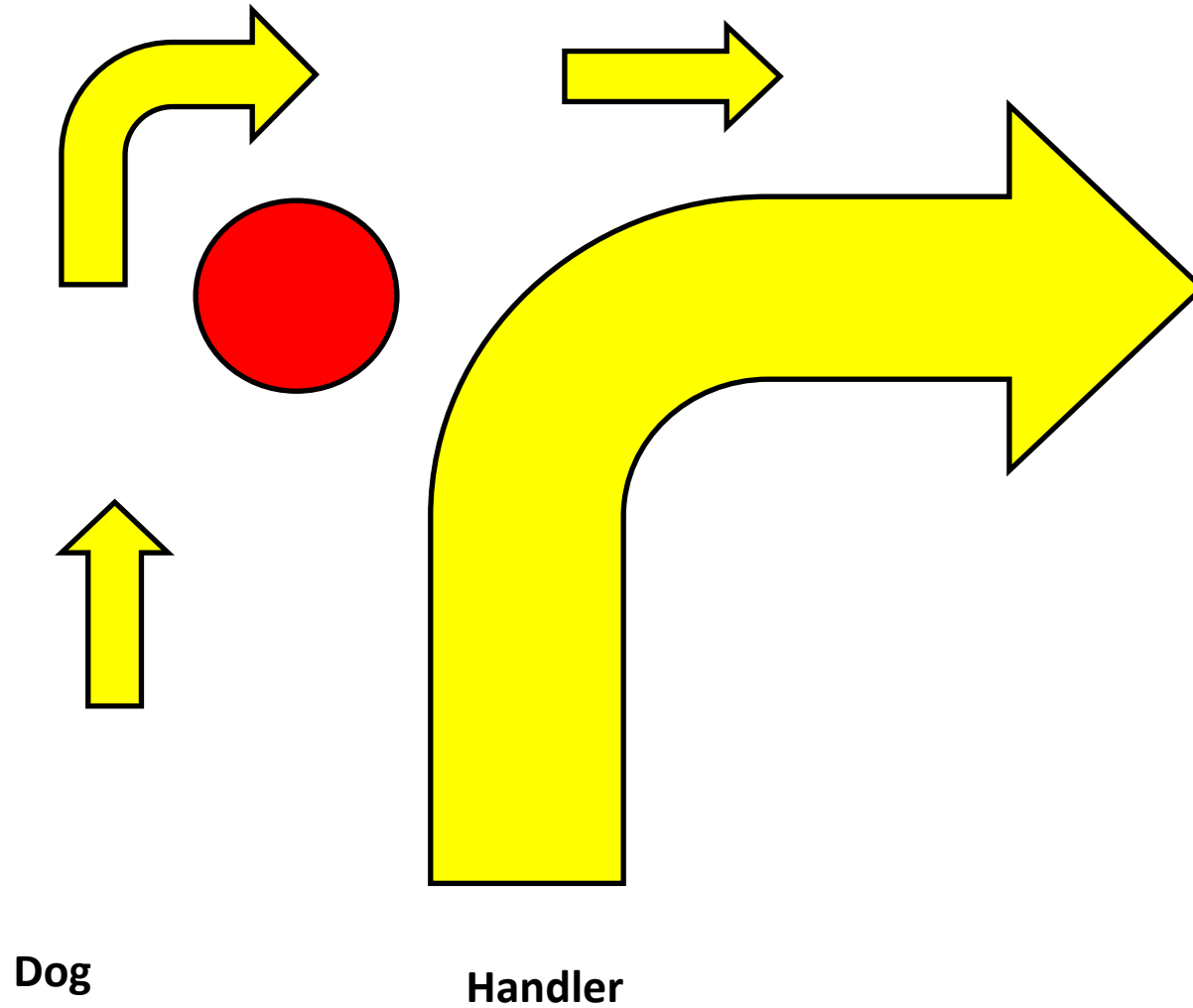


# Forward Around Pole

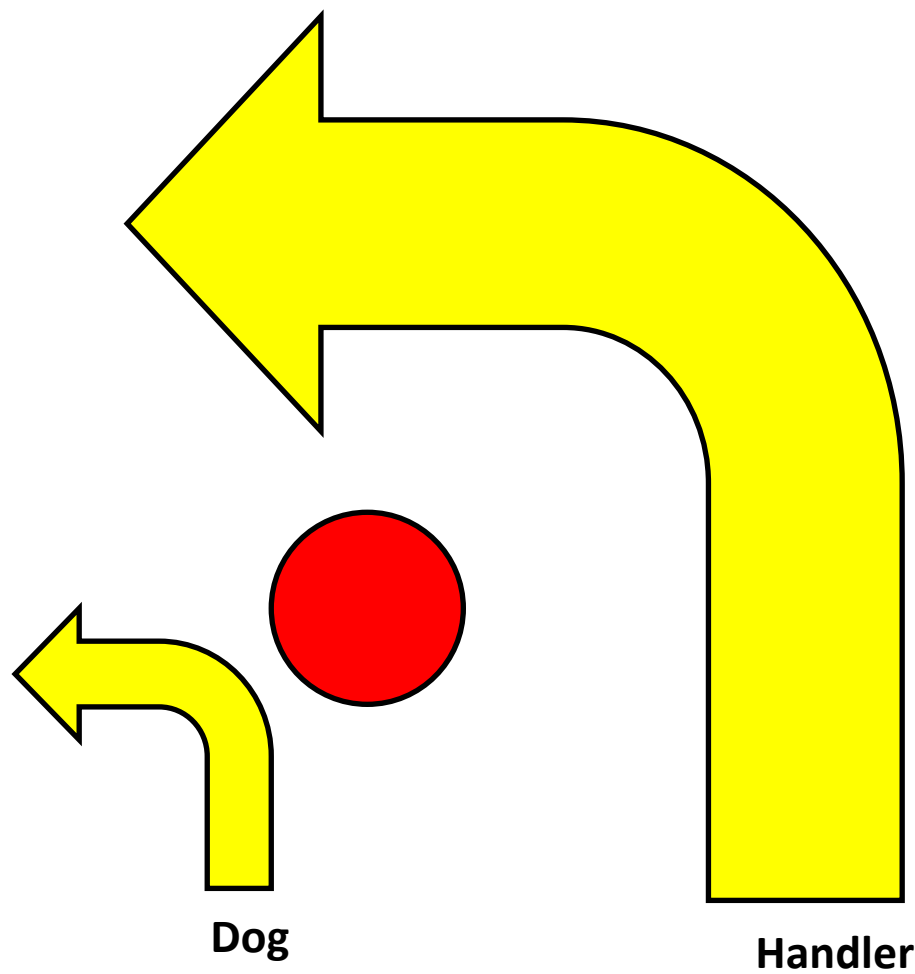


**Handler Passes By**

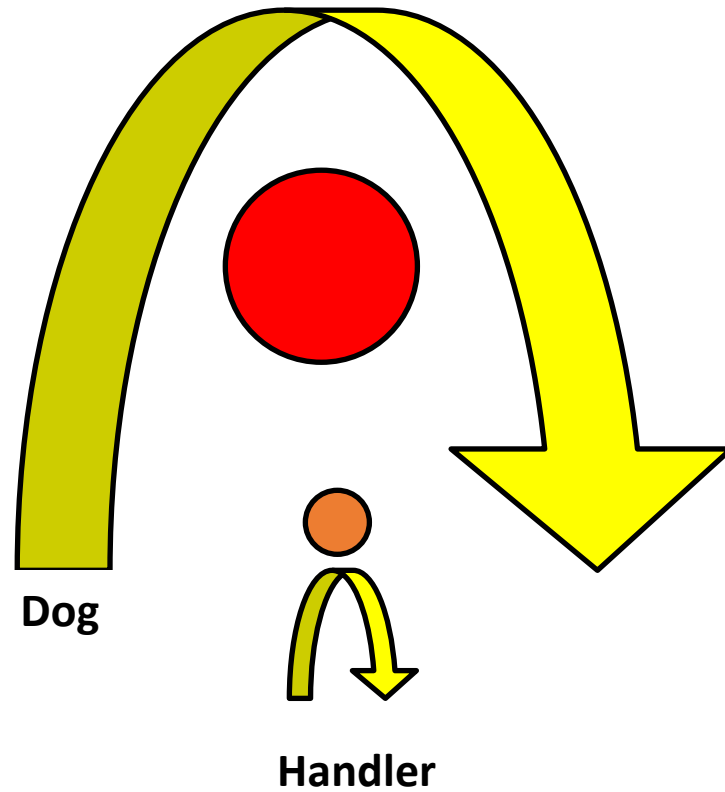
# Right Turn Round Pole

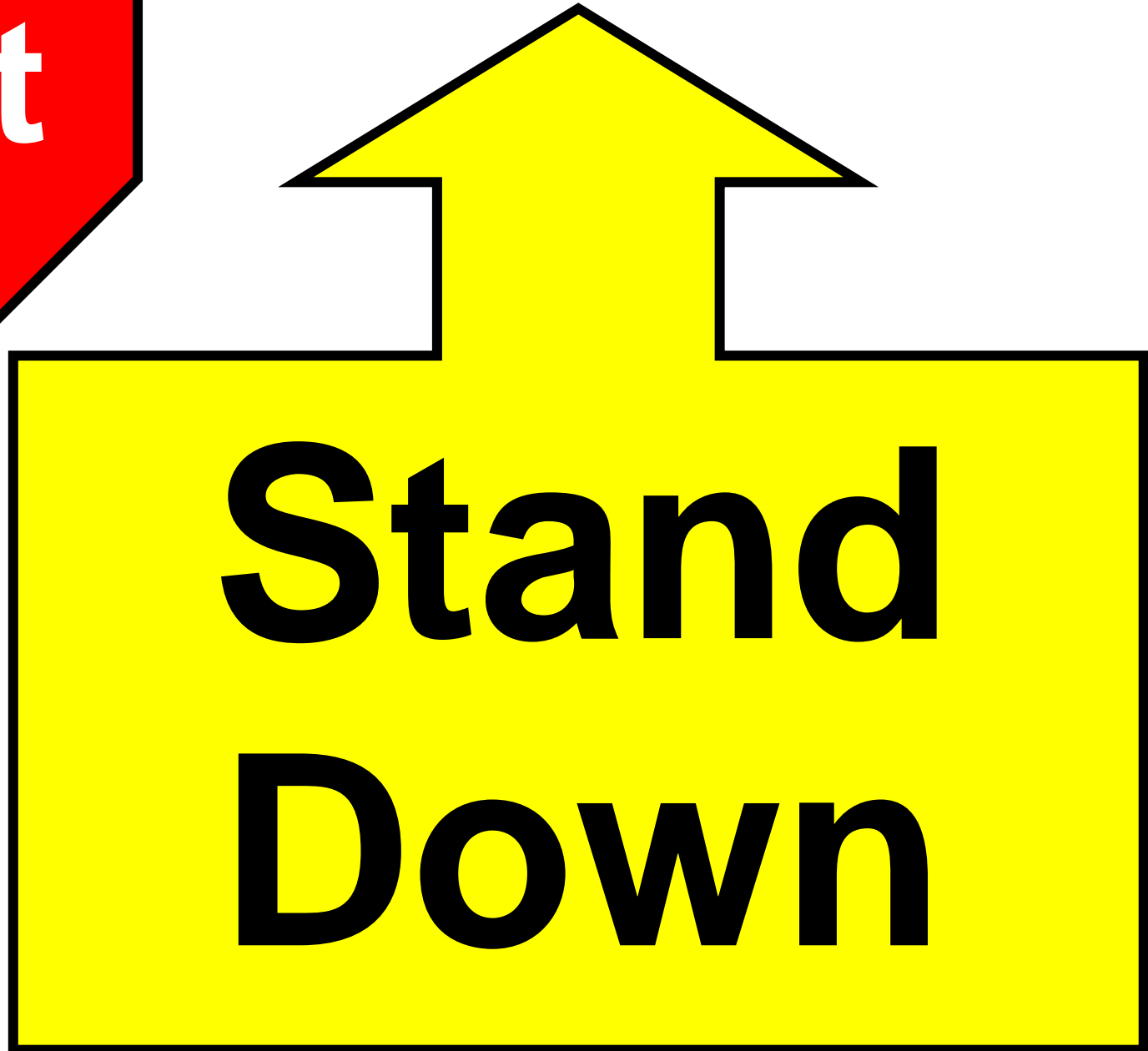


# Left Turn Round Pole

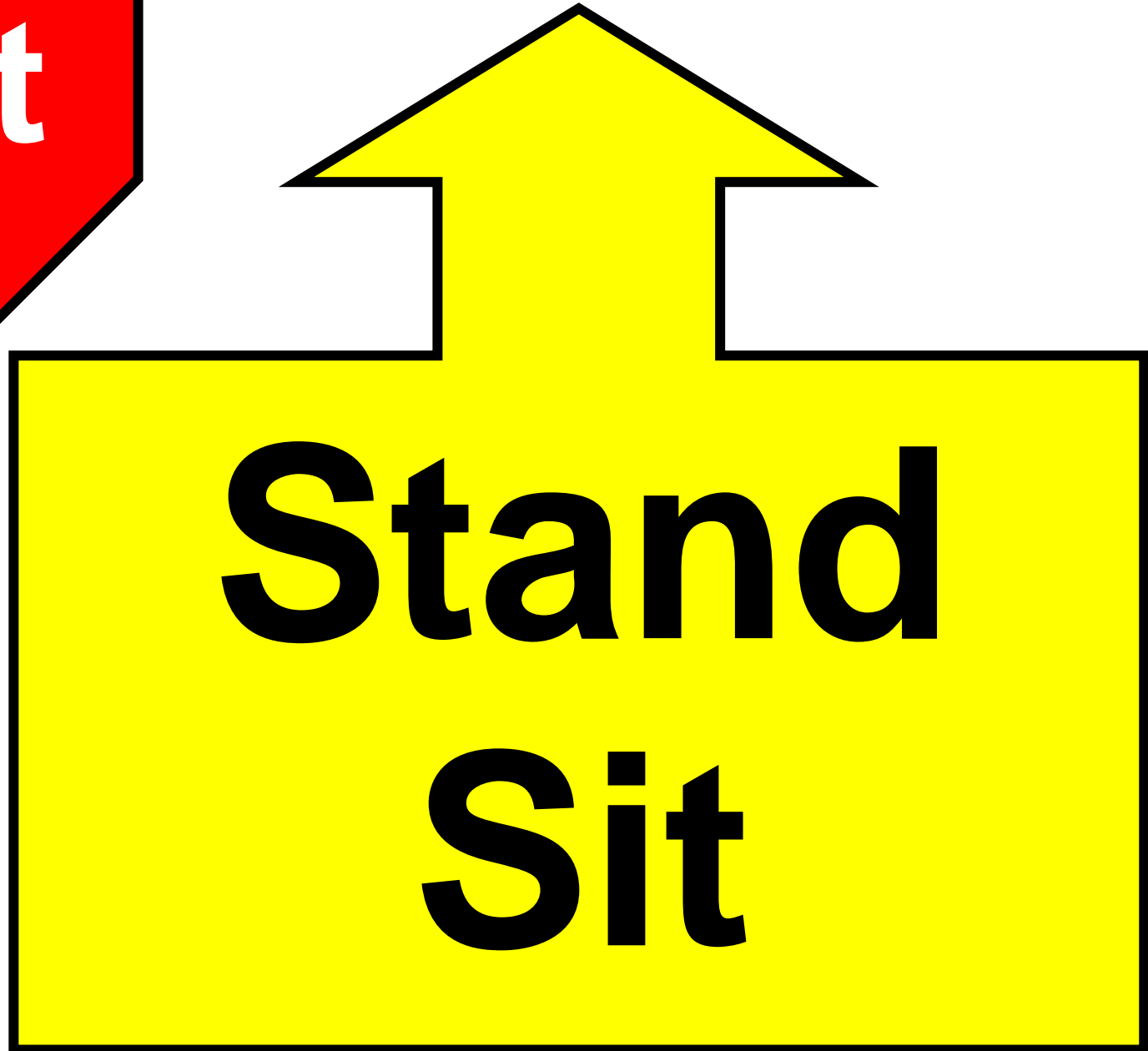


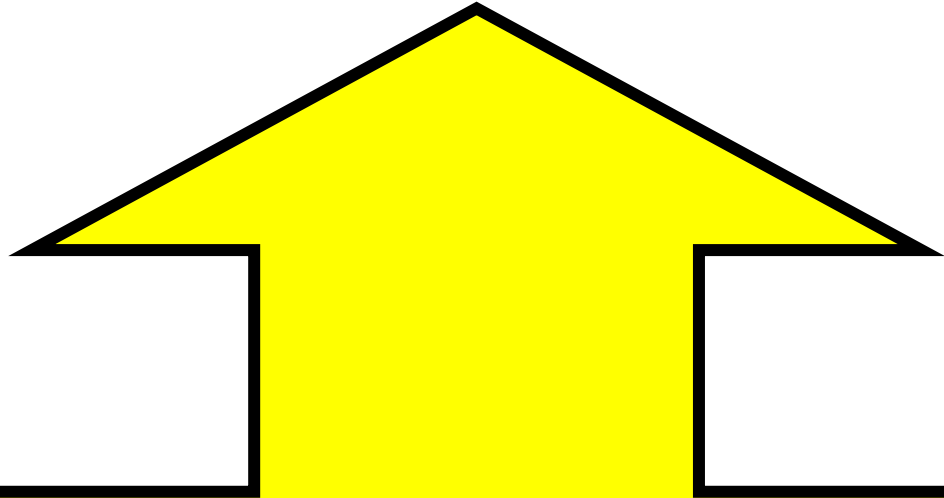
# About Turn Round Pole



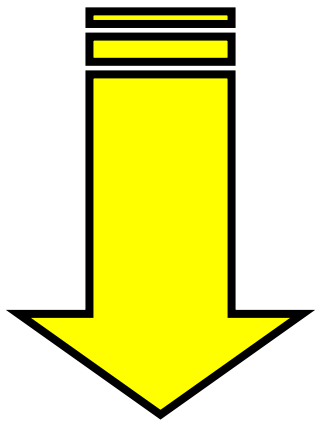
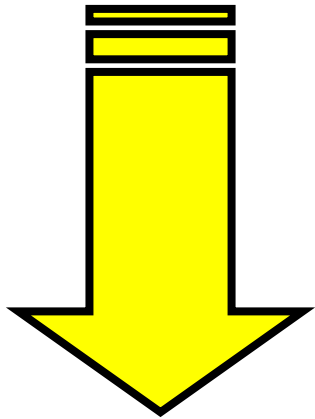
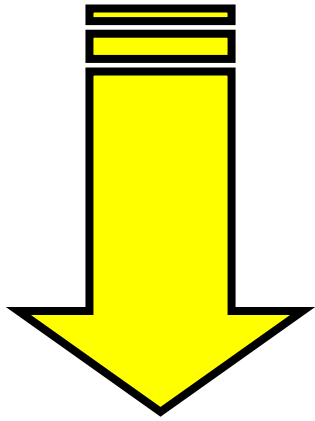




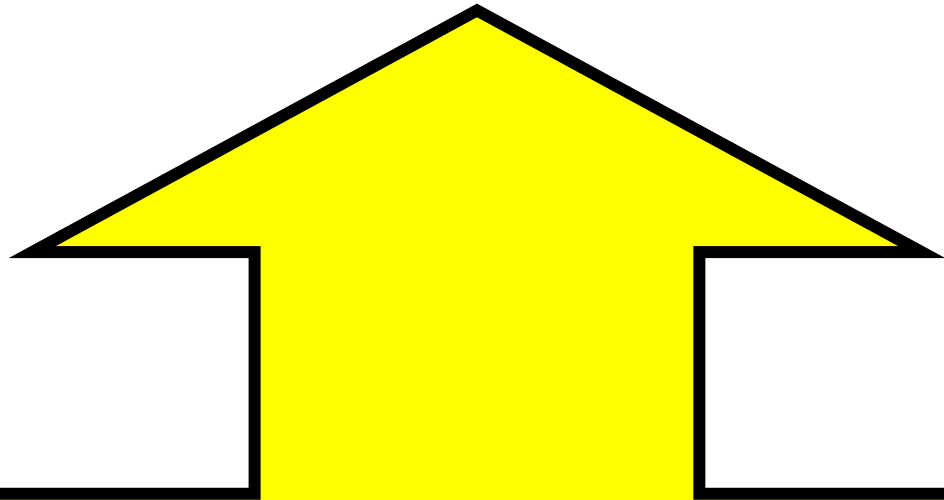




**Moving Stand  
Walk Around  
Dog**



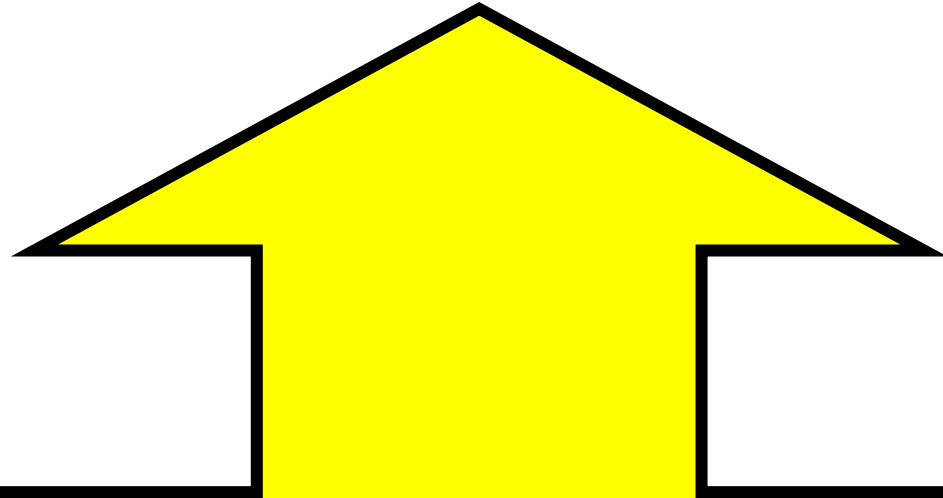
**Back Up**  
**3 Steps**  
**Dog Stays**  
**in Position**



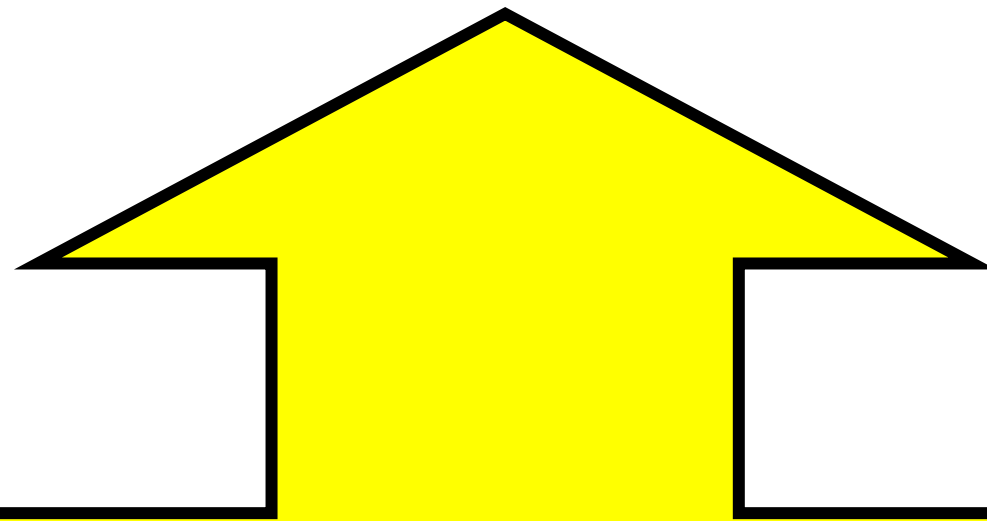
**Moving Down  
Walk Around  
Dog**



**Down  
While Heeling**



**Stand  
While Heeling**

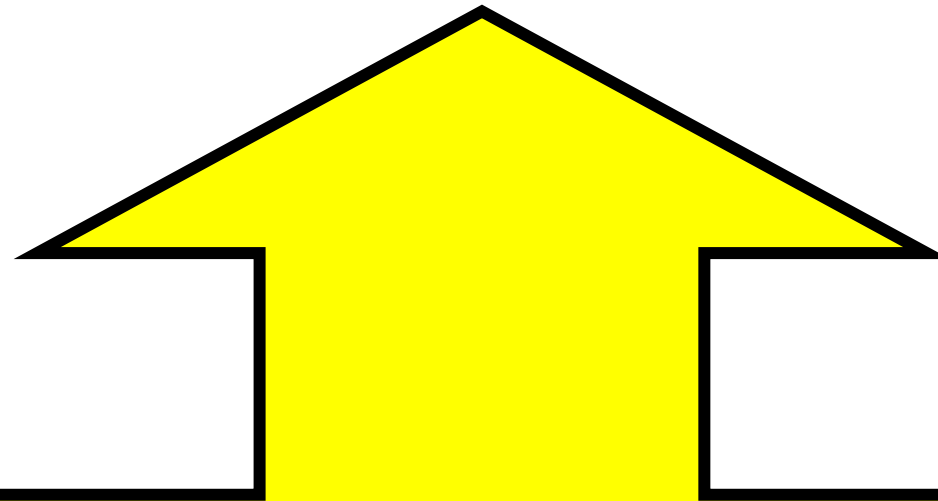


**Stand**

**Leave Dog**

**Sit Dog**

**Call Front - Finish**



**Stand**

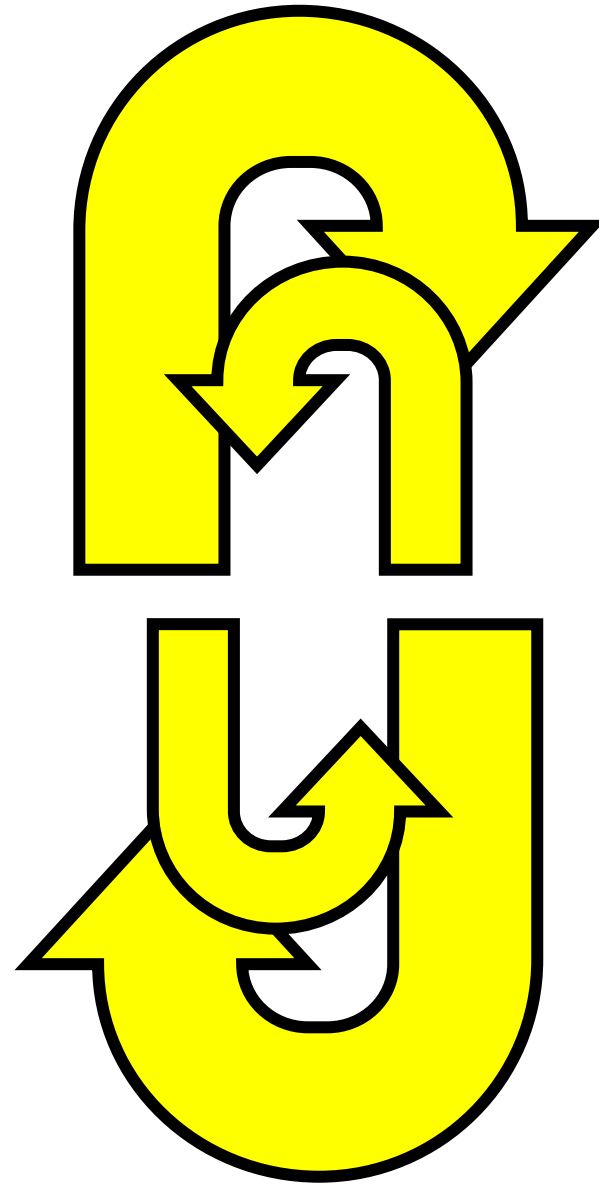
**Leave Dog**

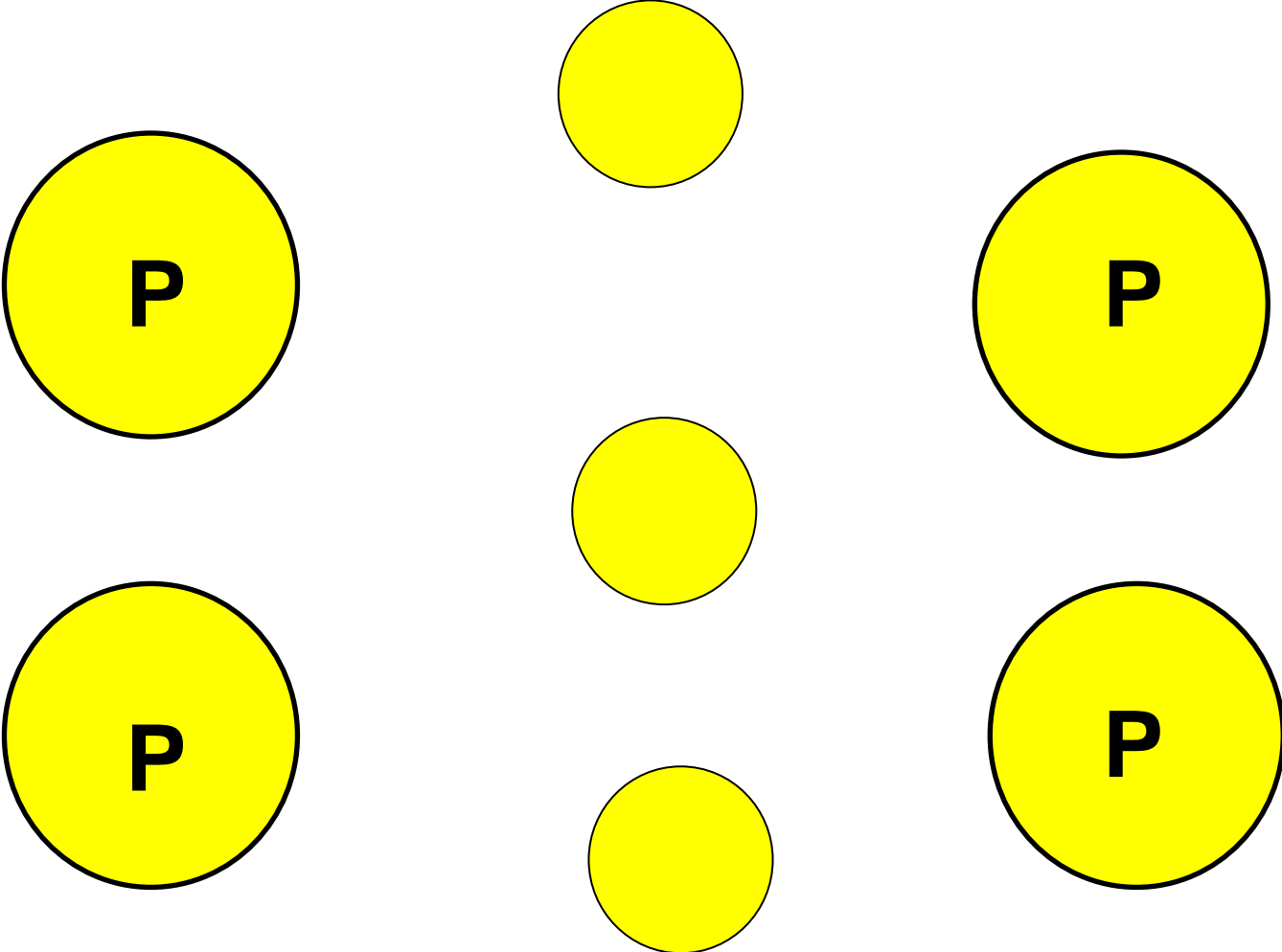
**Down Dog**

**Call Front -Finish**



**Double  
Left  
About  
Turn**

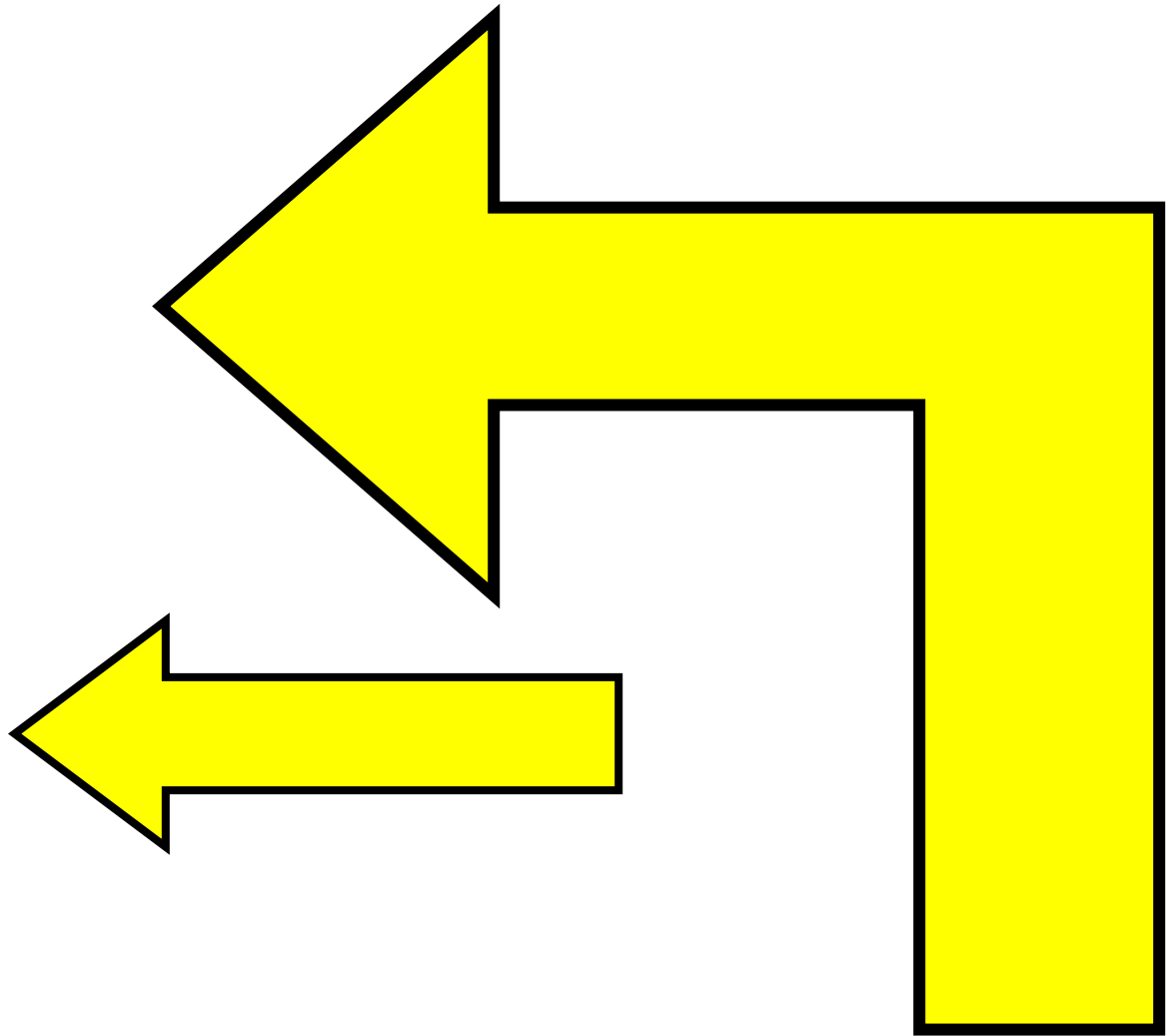


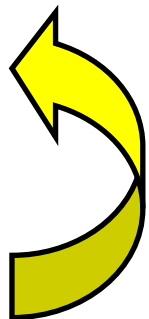
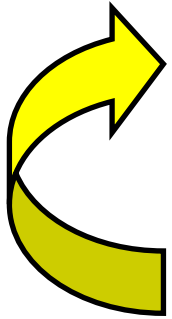
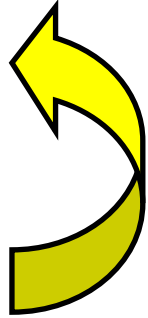
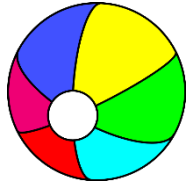
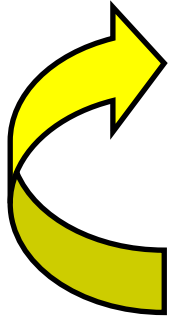


# Double Off-Set Figure Eight

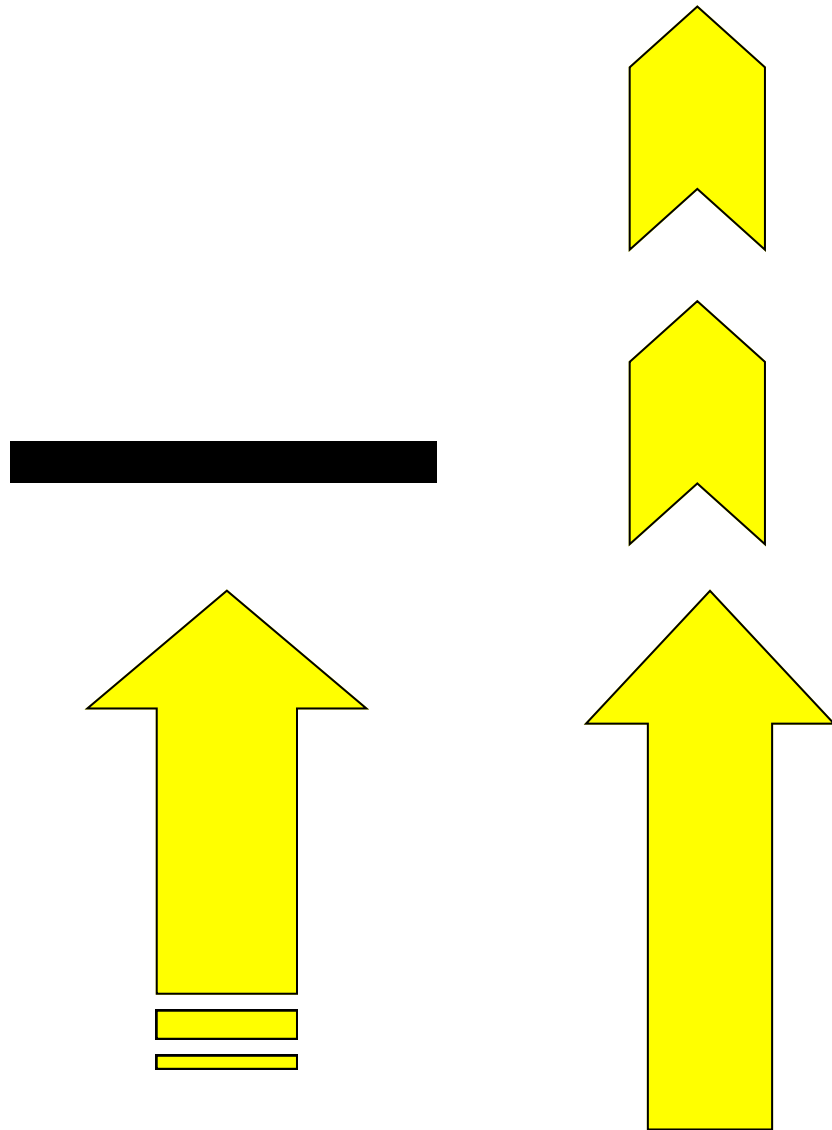


**Pivot  
Left**

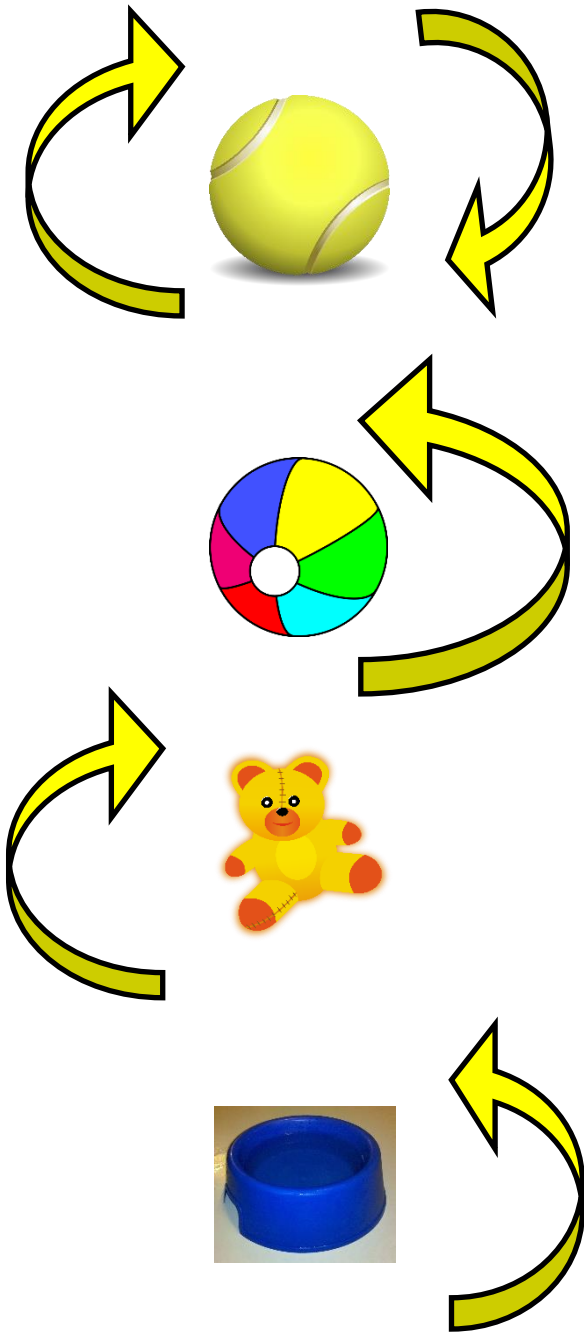




# Weave With Distractions



**Stand**  
**Leave**  
**dog**

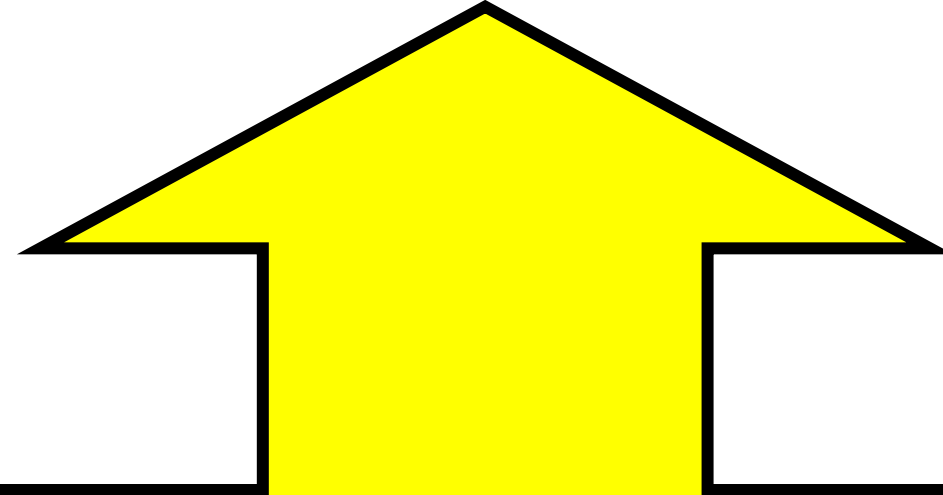


# Weave Twice With Distractions

**Lead**

**Wait**





**Recall**