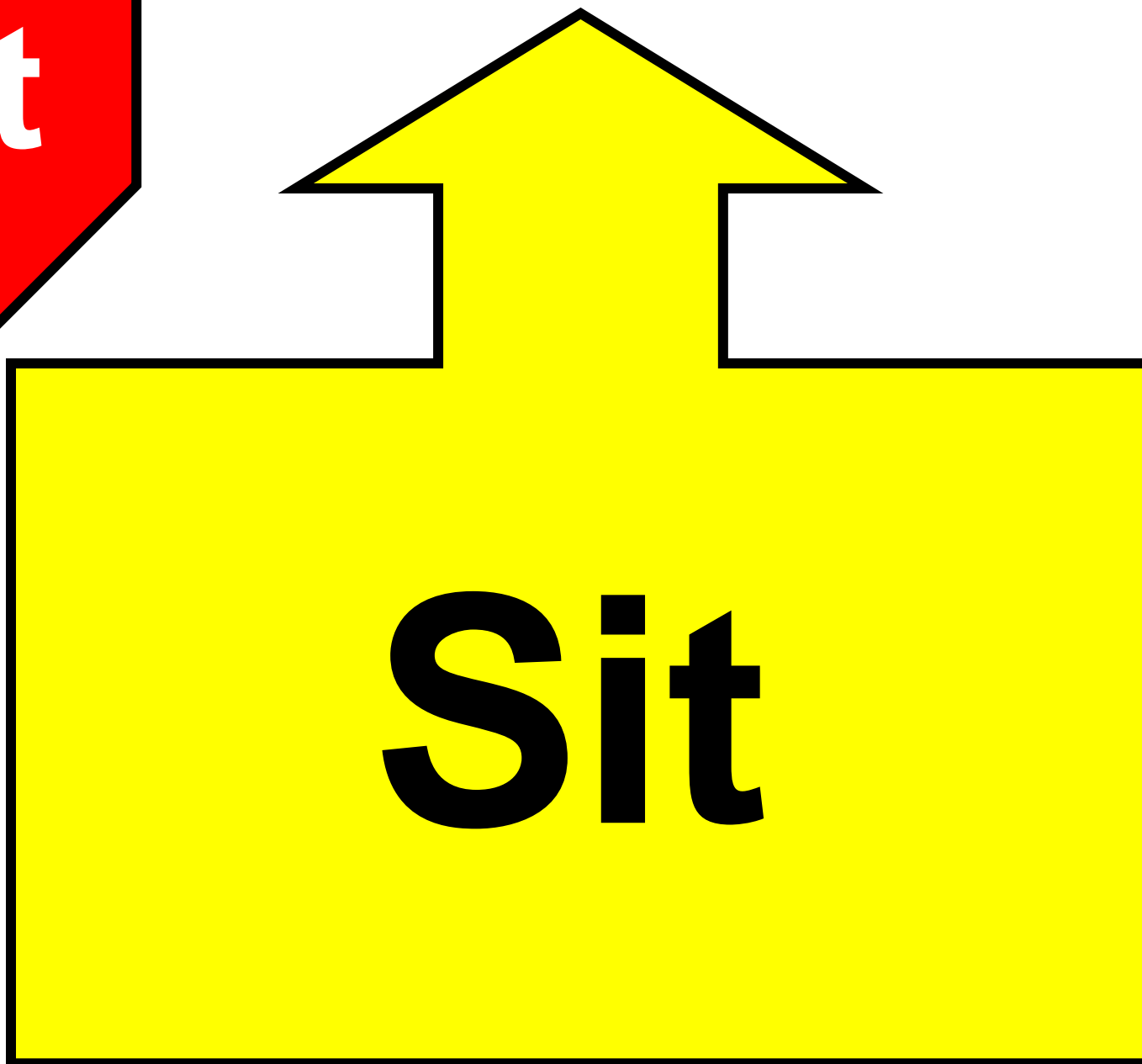


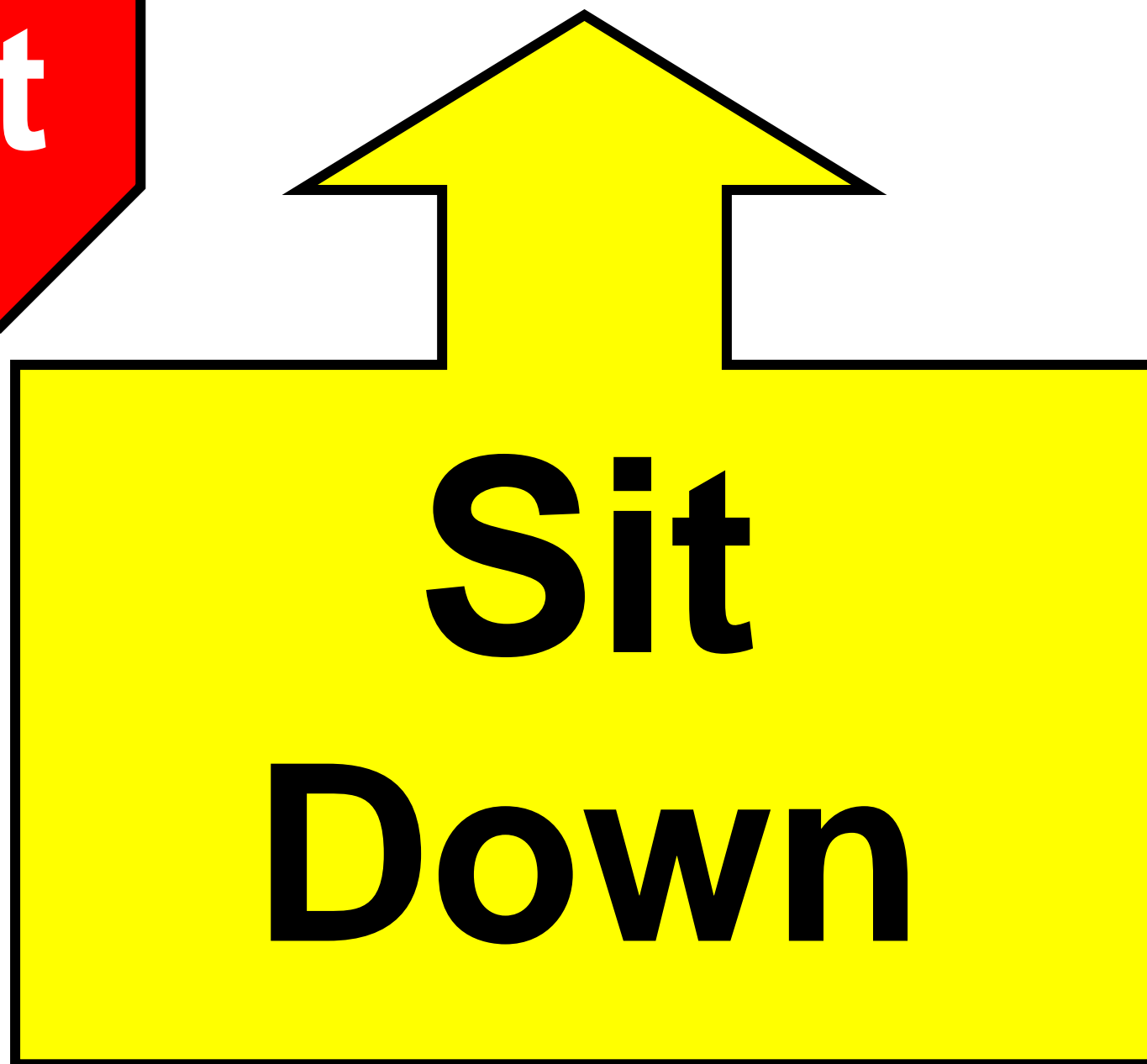


**Start**

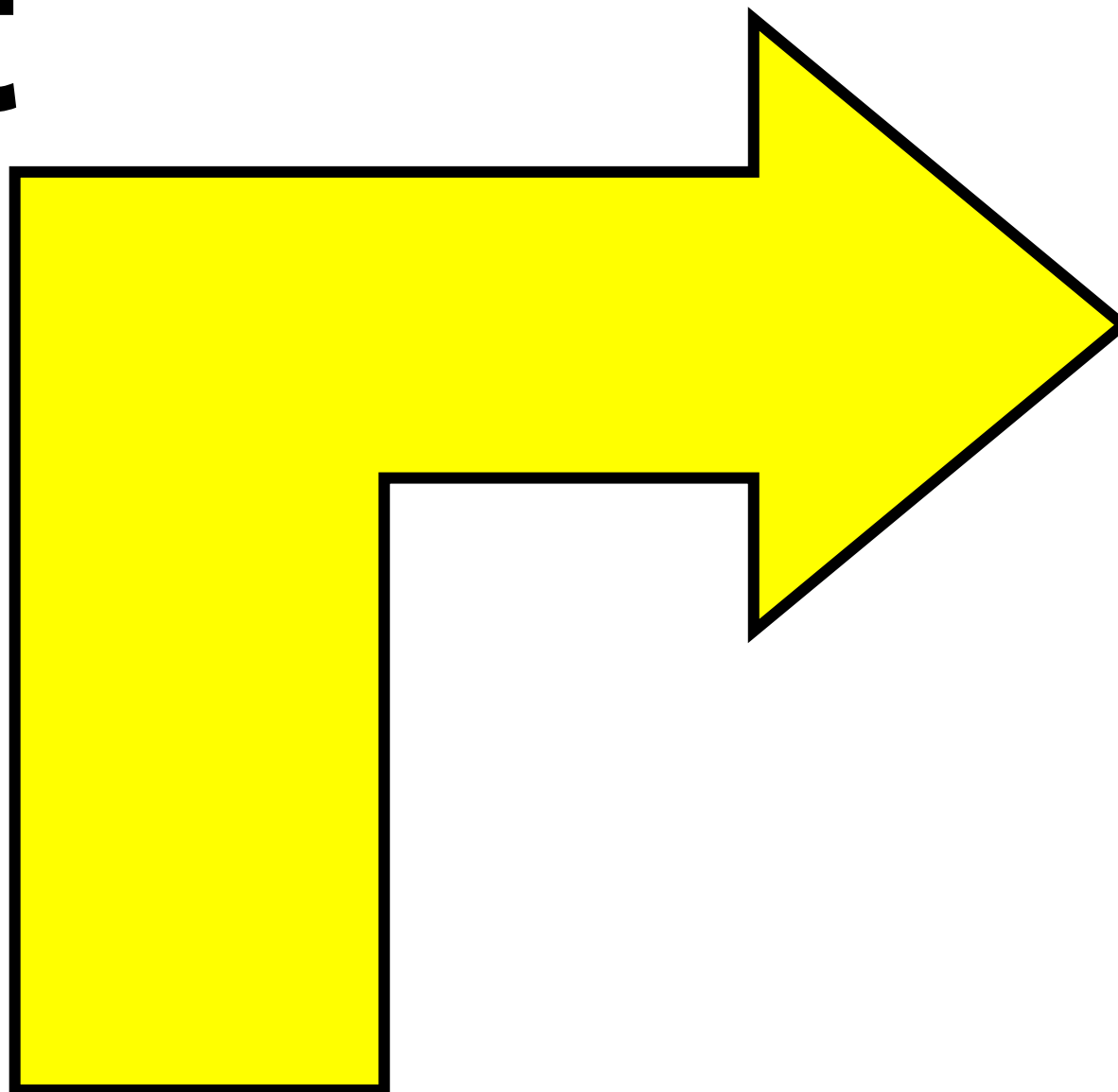


**Finish**

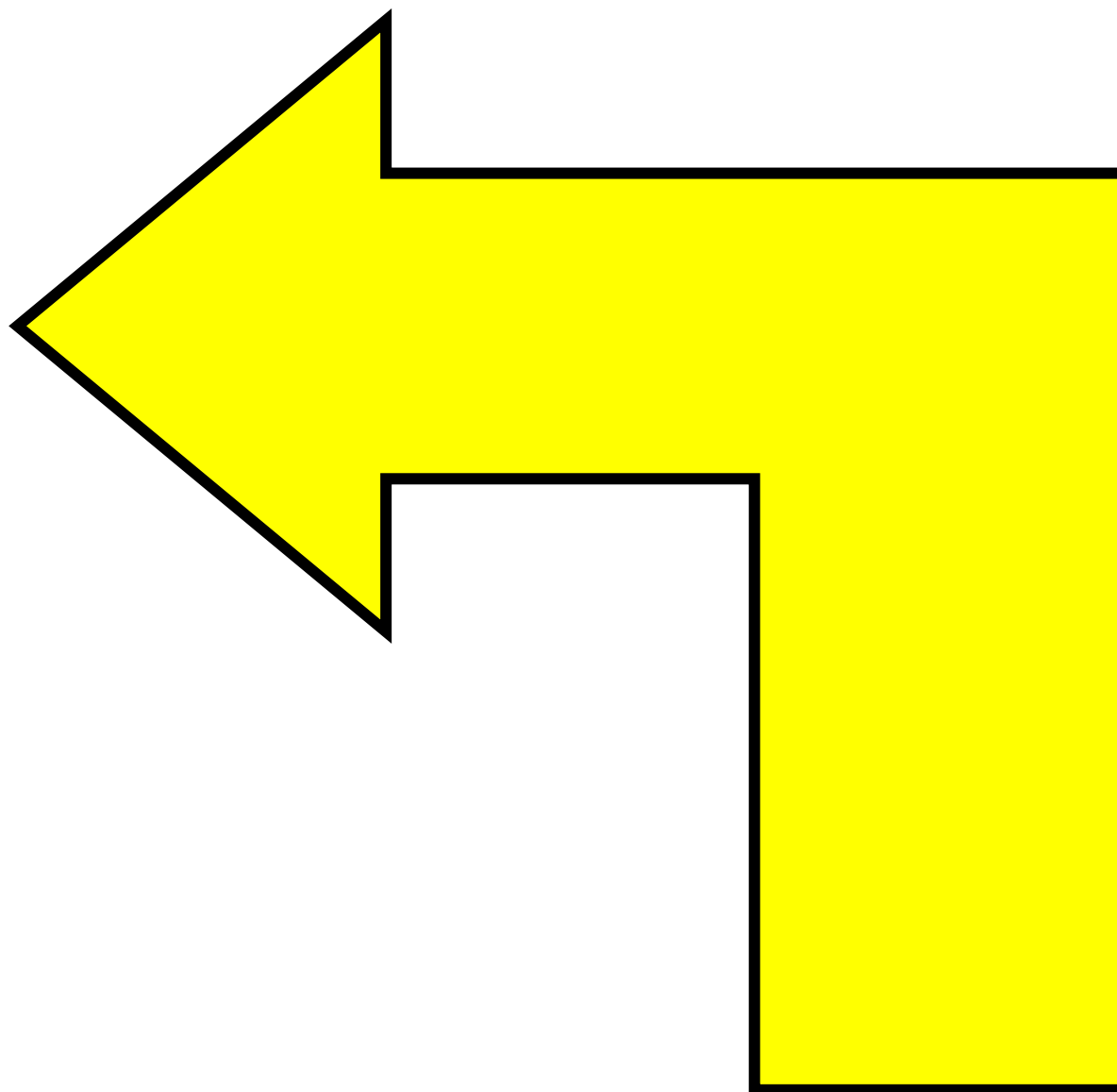




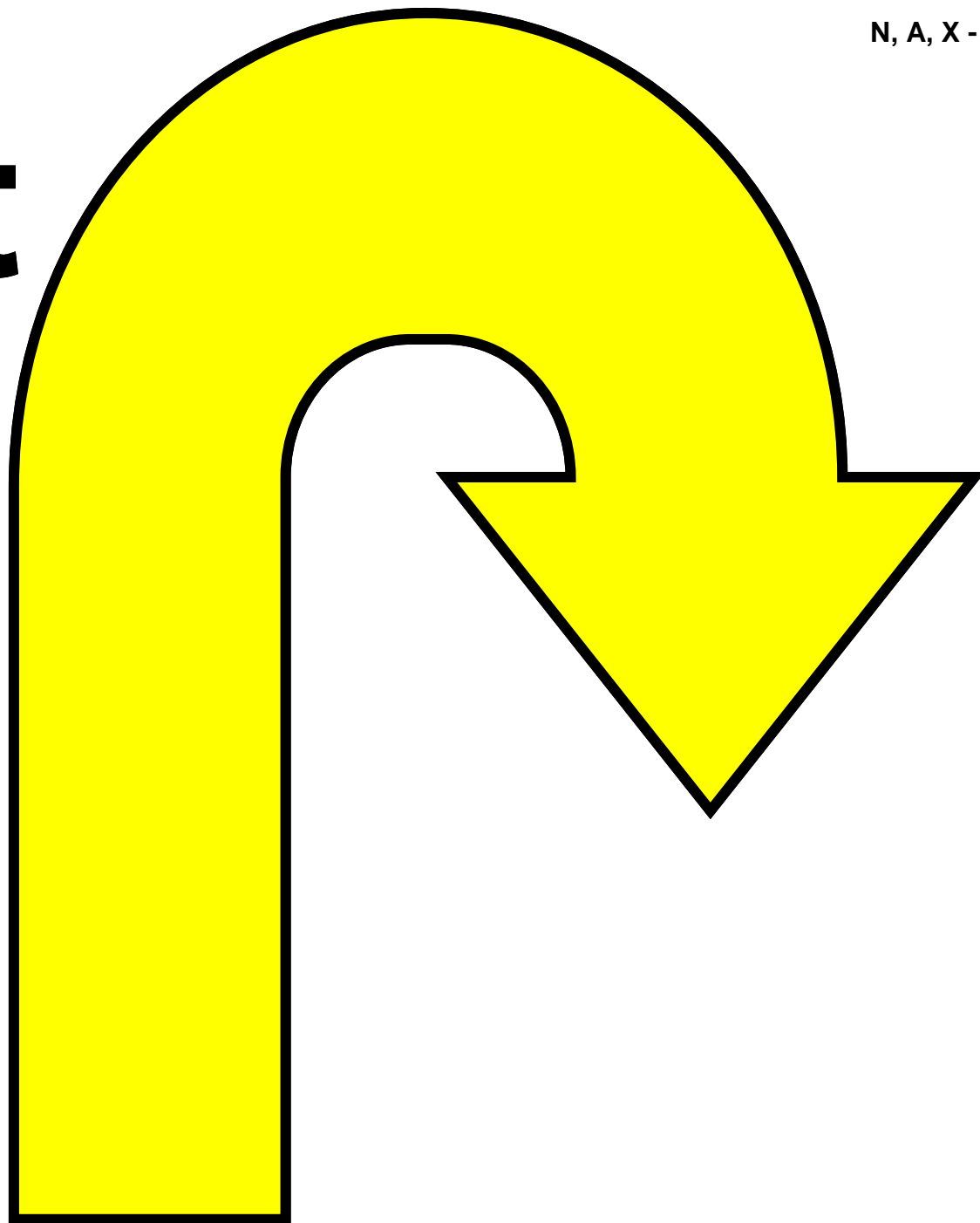
**Right  
Turn**



**Left  
Turn**



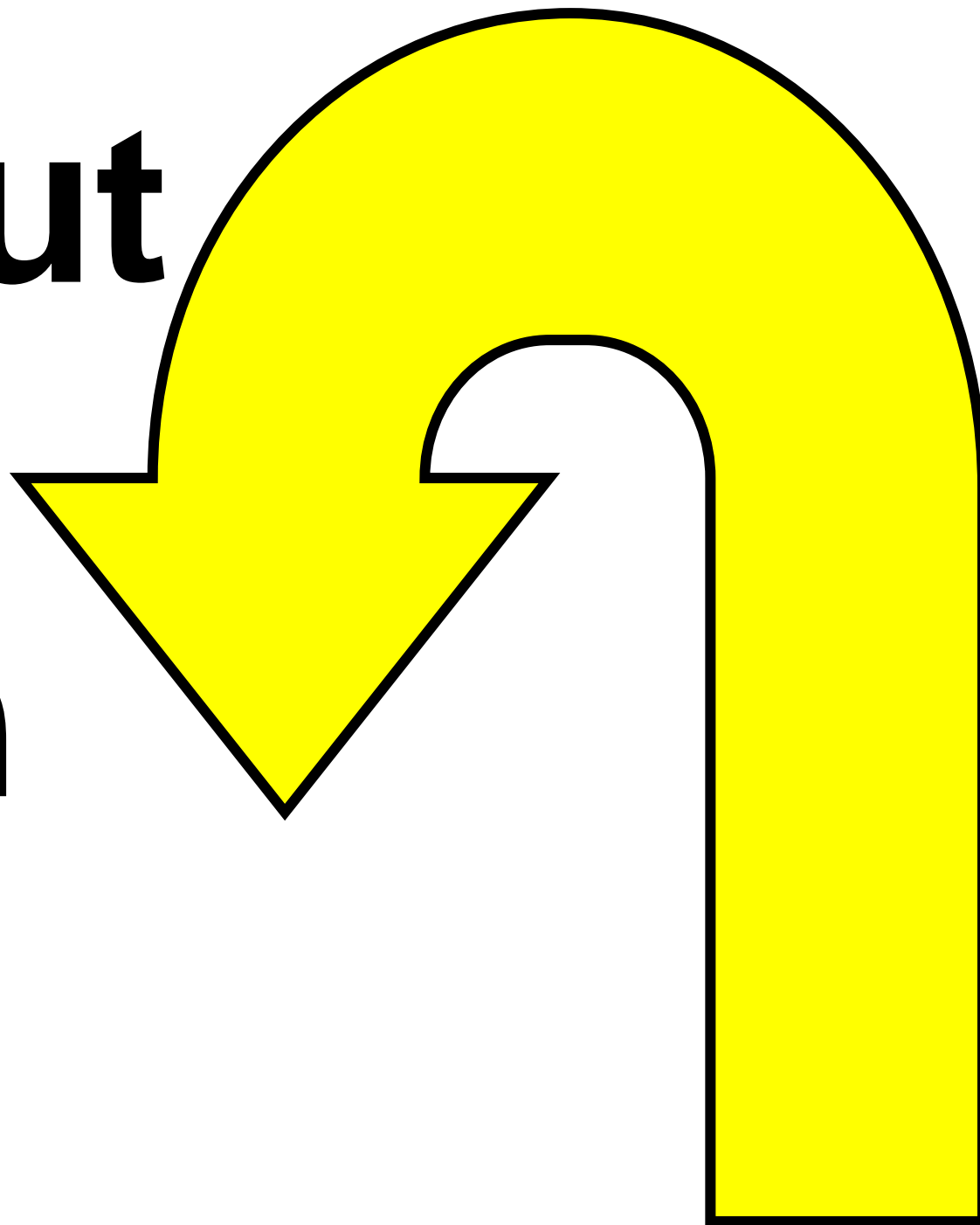
**About  
Turn  
Right**



**About**

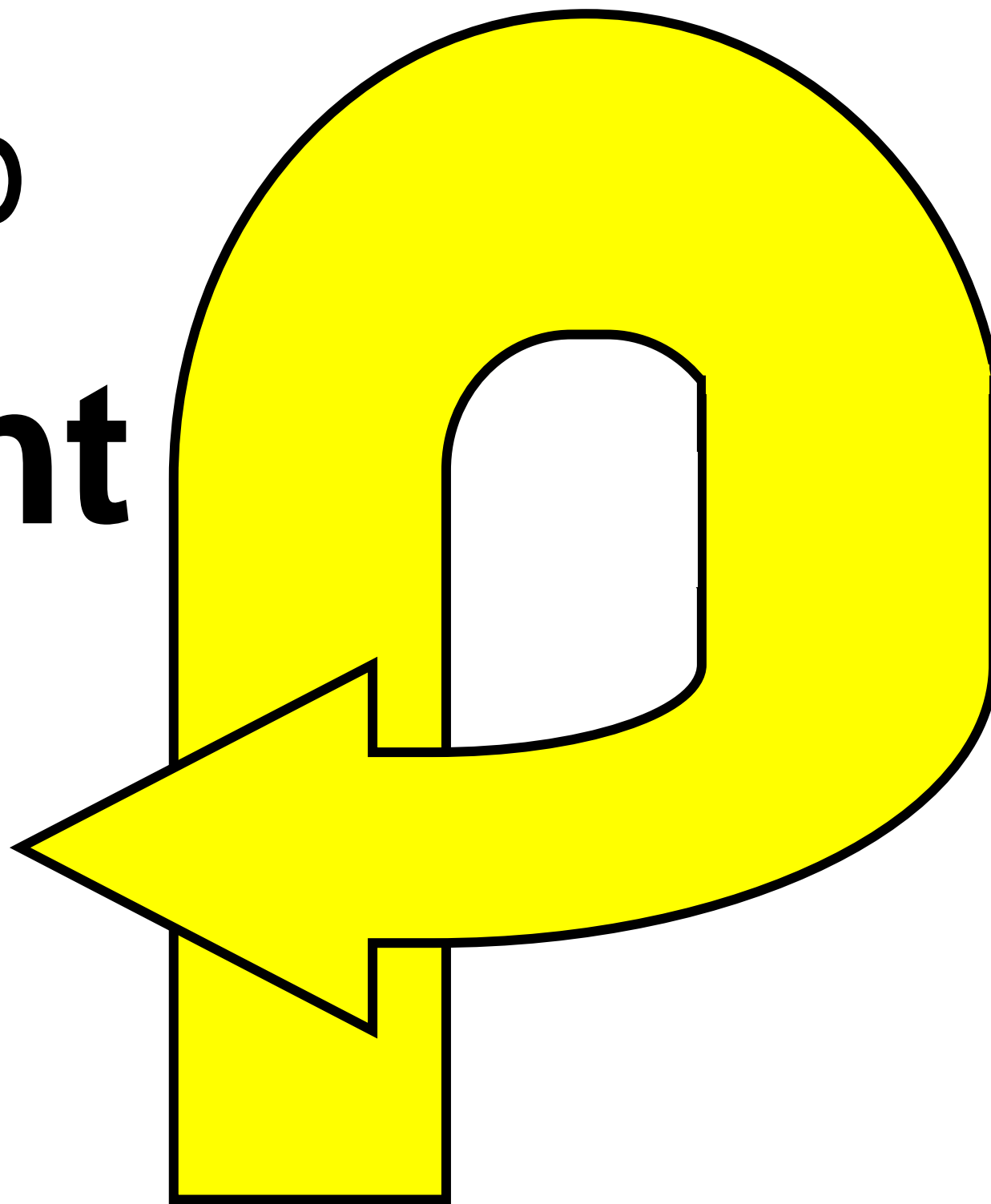
**U**

**Turn**



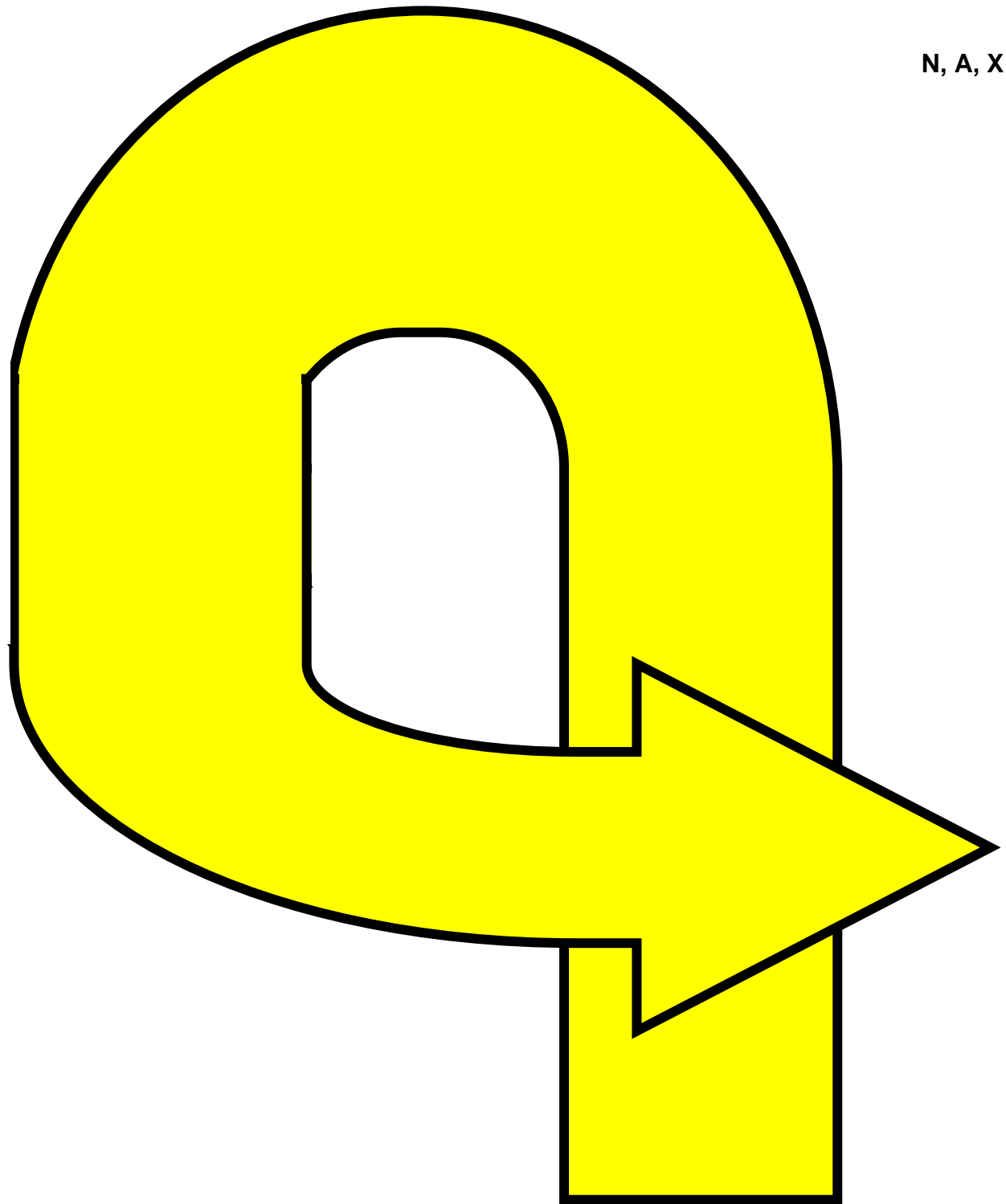


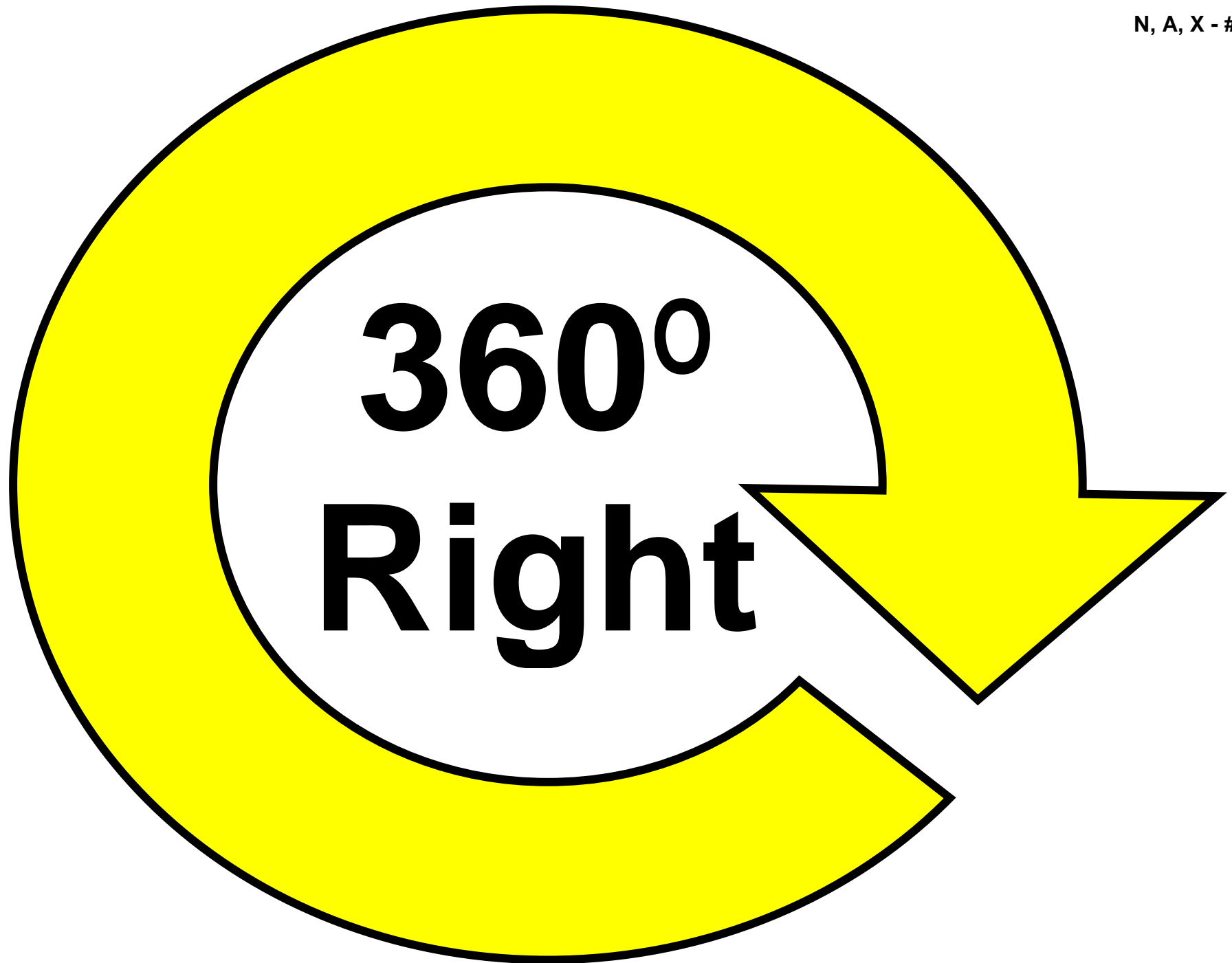
**270°**  
**Right**



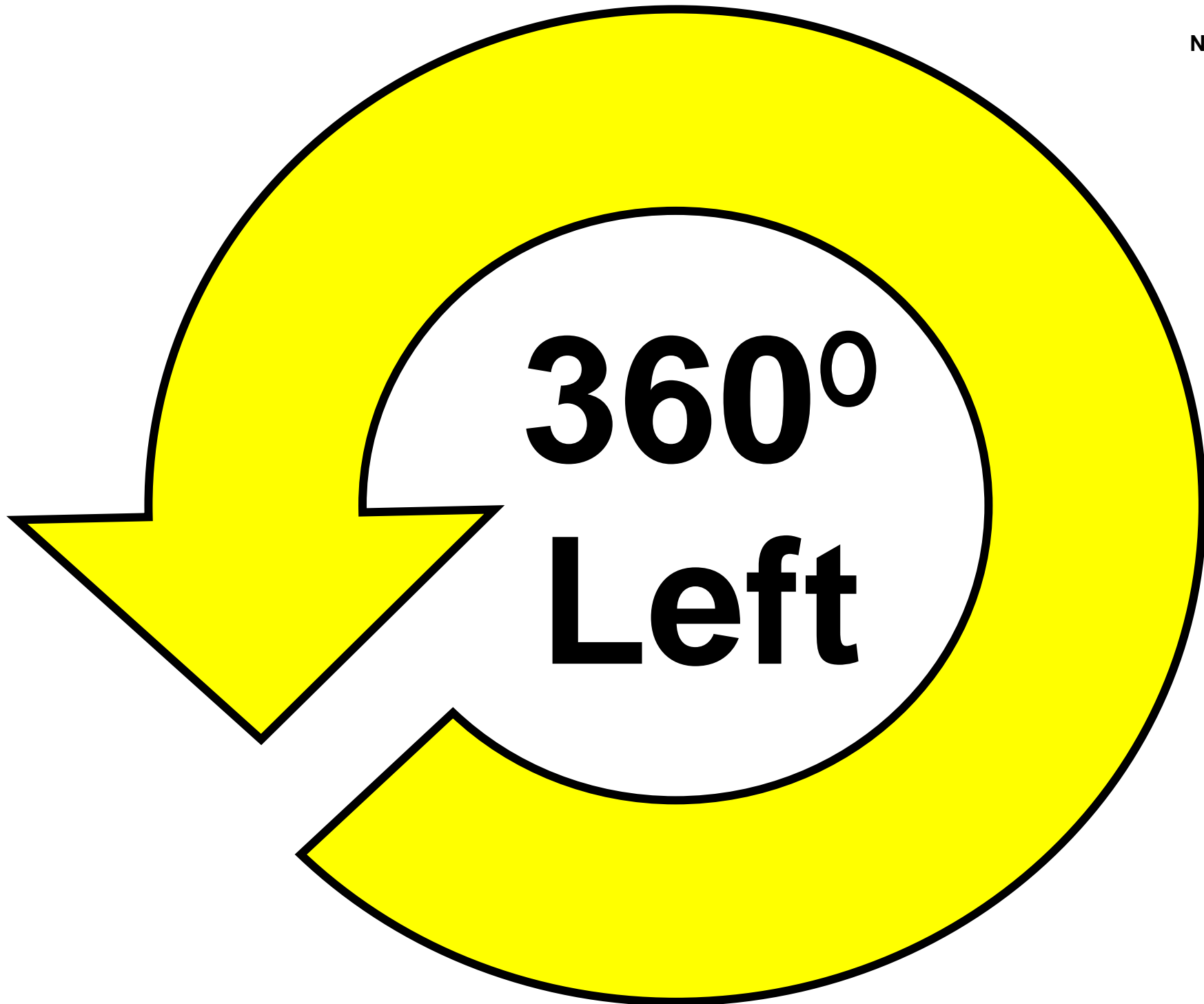
**270°**

**Left**





**360°**  
**Right**



**360°**

**Left**



**Finish Right  
Forward**

**Call  
Front**



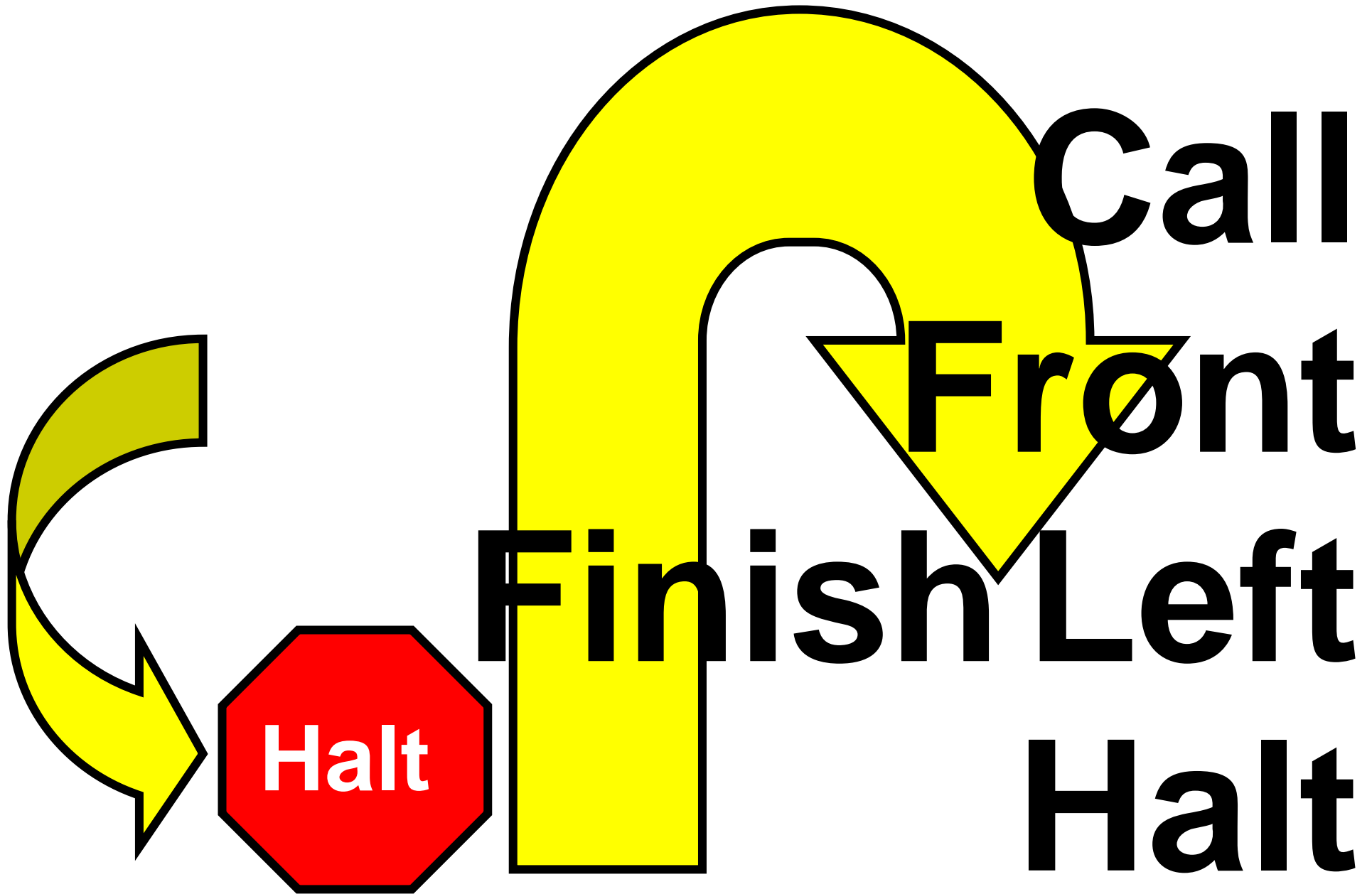
**Call**

**Front**

**Finish Left**

**Forward**









**Slow  
Pace**

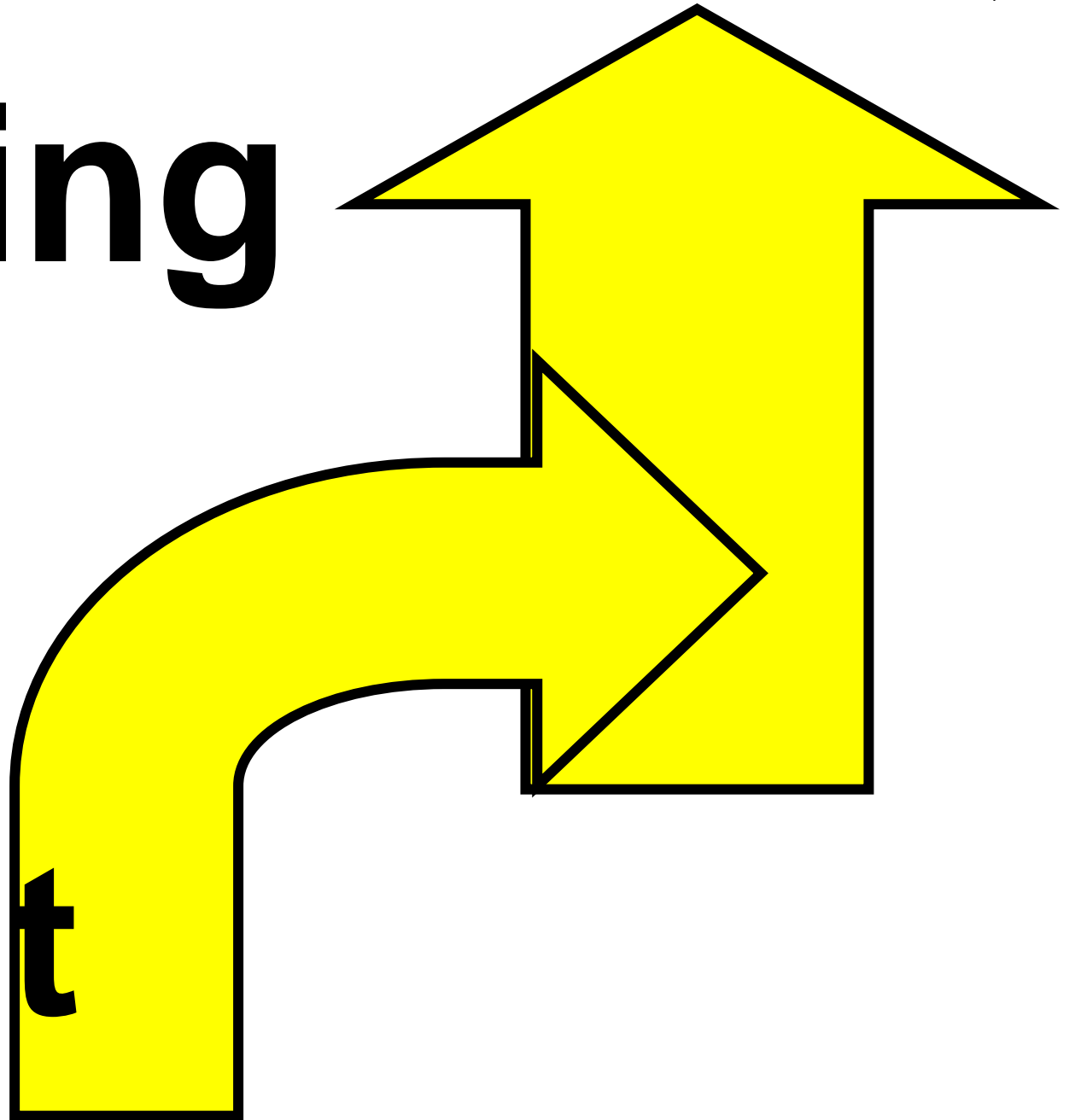


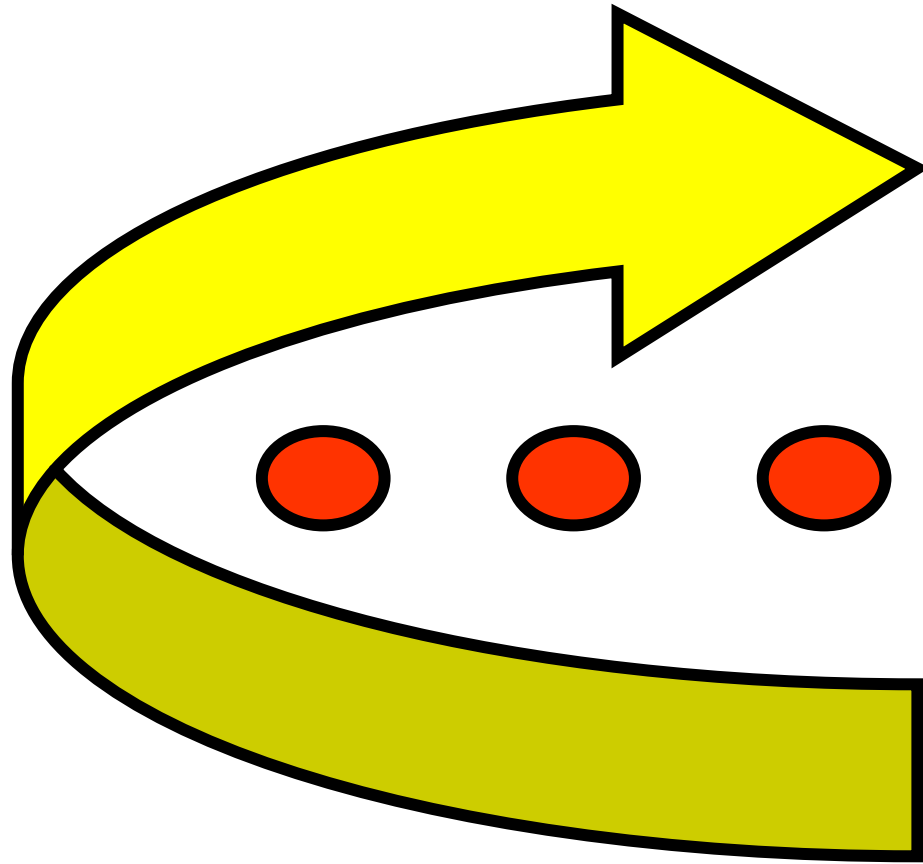
**Fast  
Pace**



**Normal  
Pace**

**Moving**  
**Side**  
**Step**  
**Right**



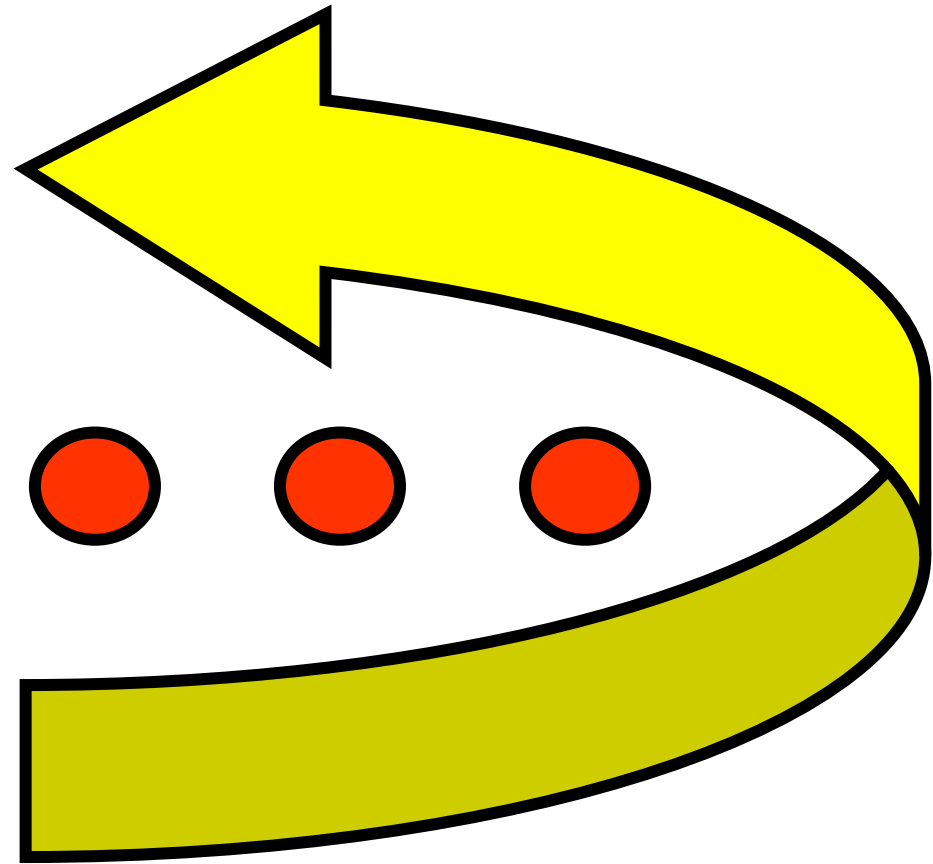


**Spiral  
Right**

**Dog Outside**

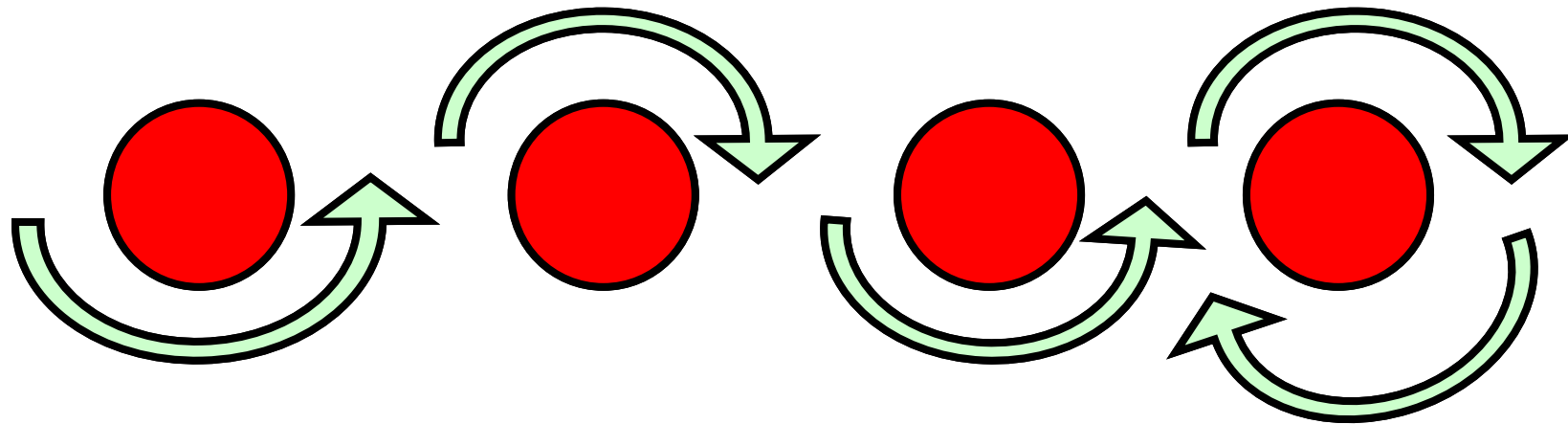
**Spiral**

**Left**

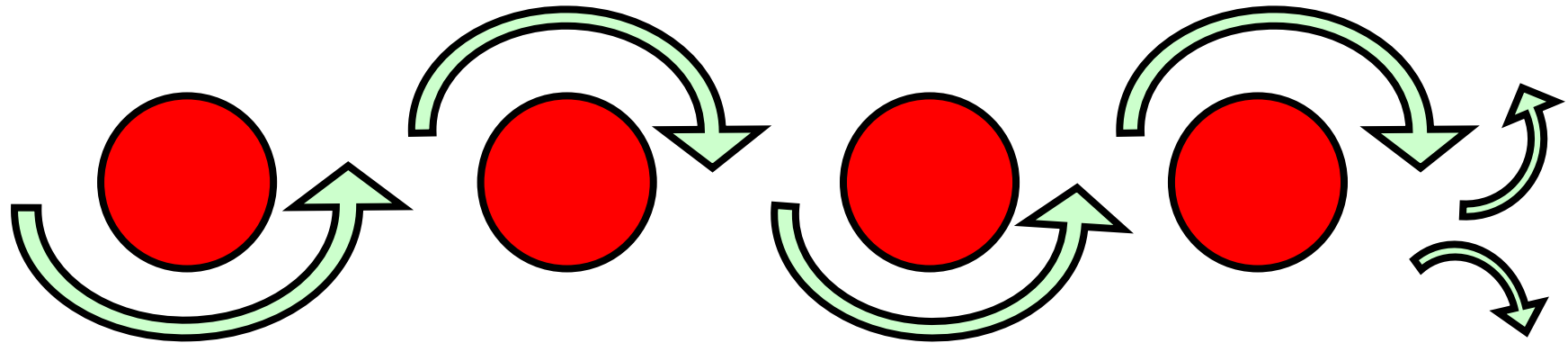


**Dog Inside**

# Straight Figure 8 Weave Twice



# Serpentine Weave Once







**1 Step**

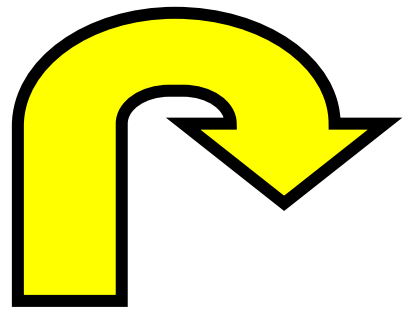


**2 Steps**



**3 Steps**





# Call Front

**1 Step Back**



**2 Steps Back**



**3 Steps Back**

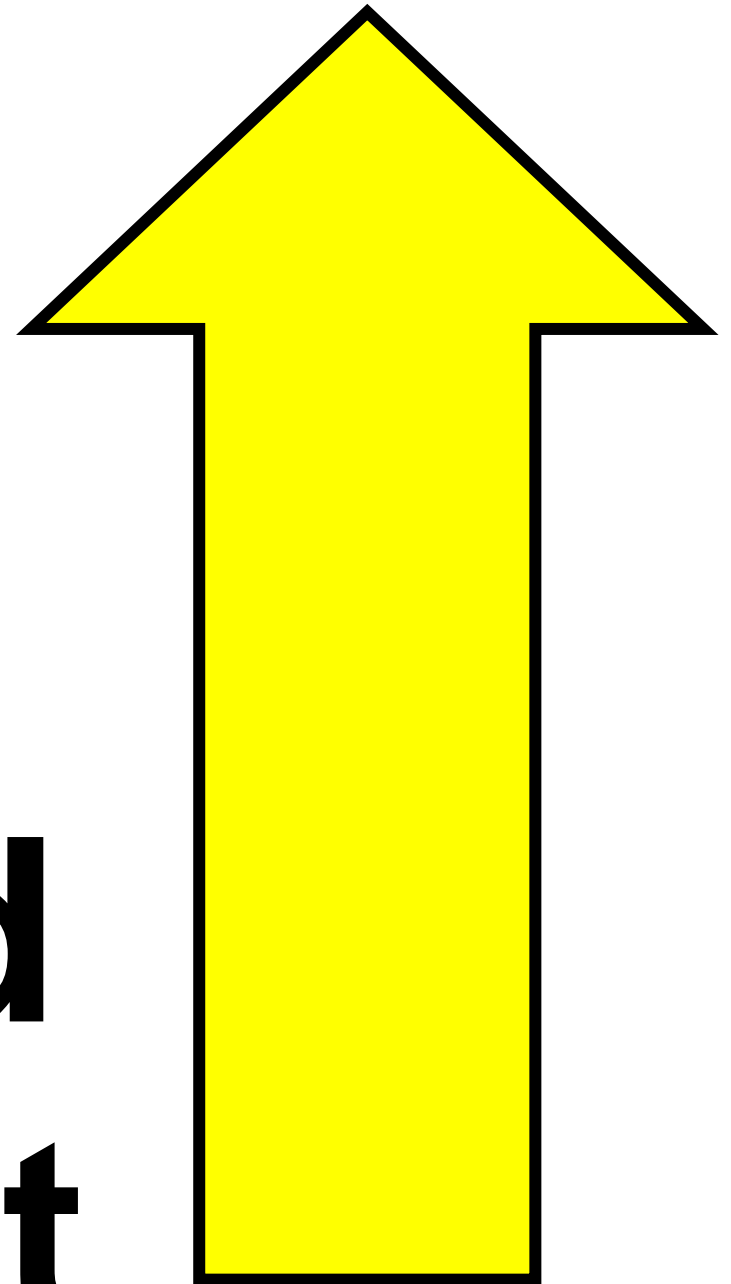




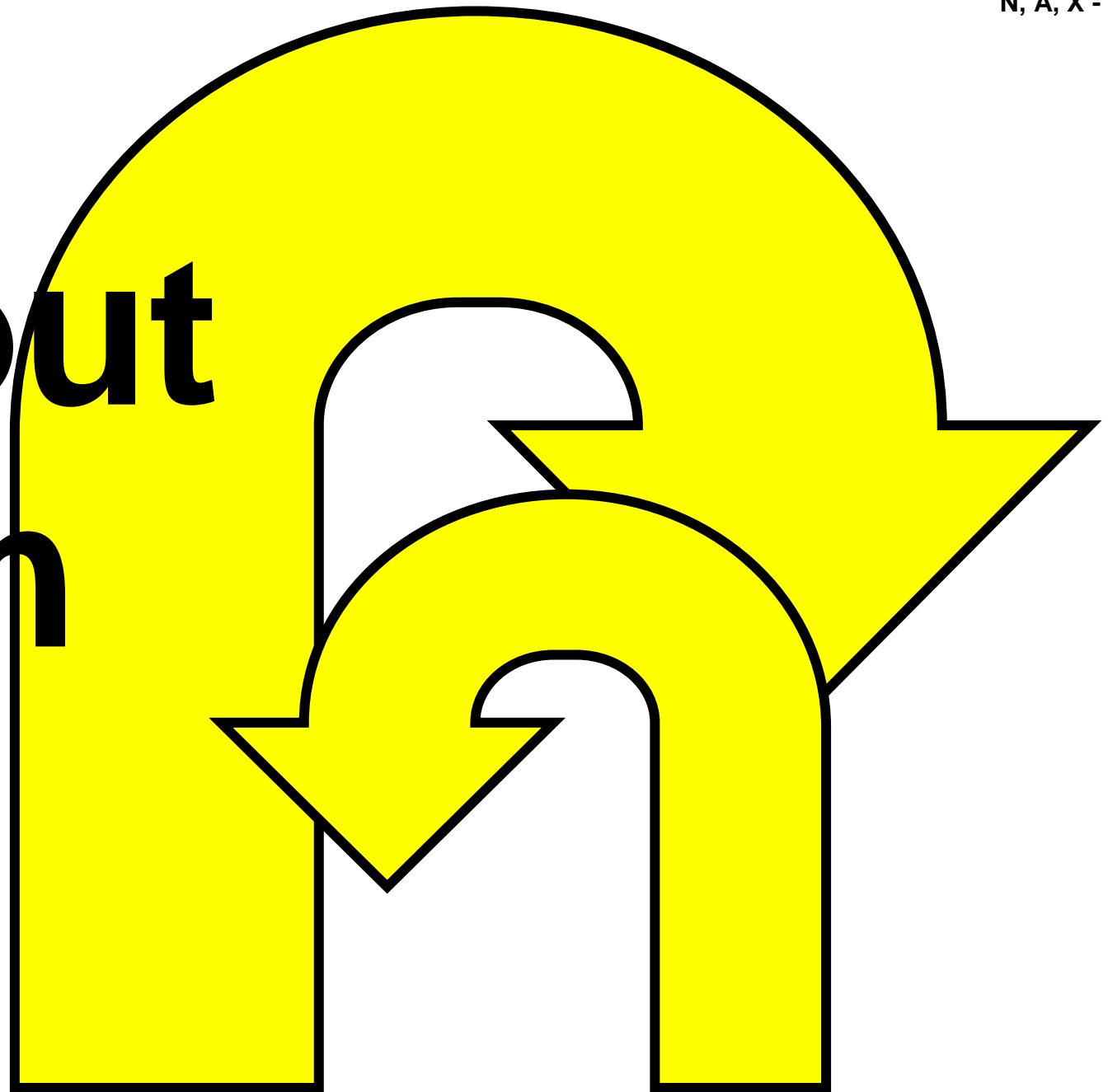
**Fast**

**Forward**

**From Sit**



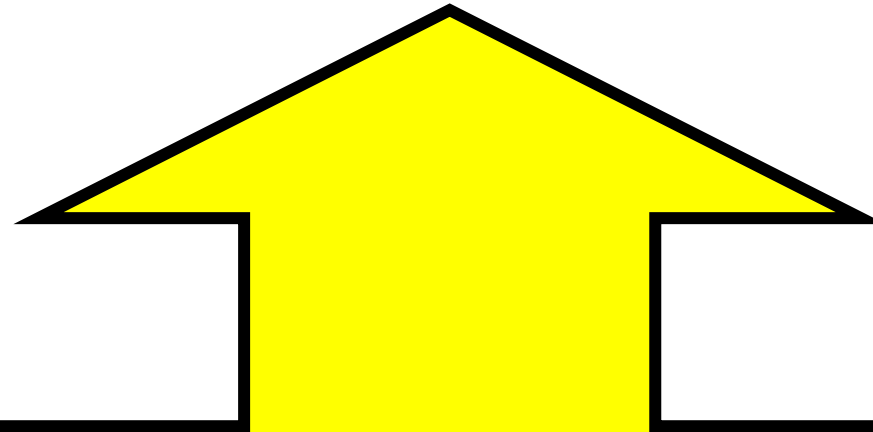
# Left About Turn



DOG

HANDLER

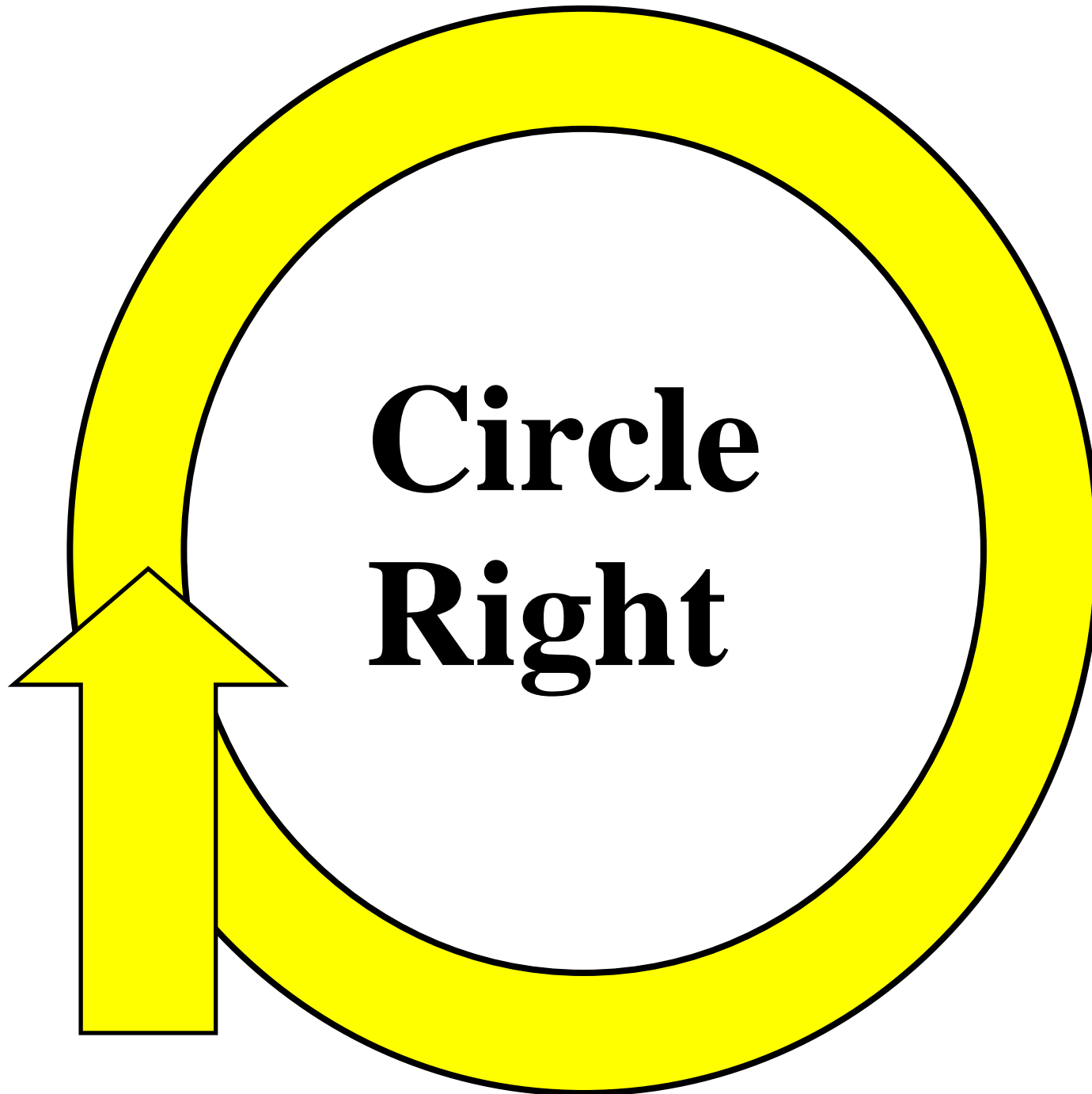




**Down  
Walk Around  
Dog**

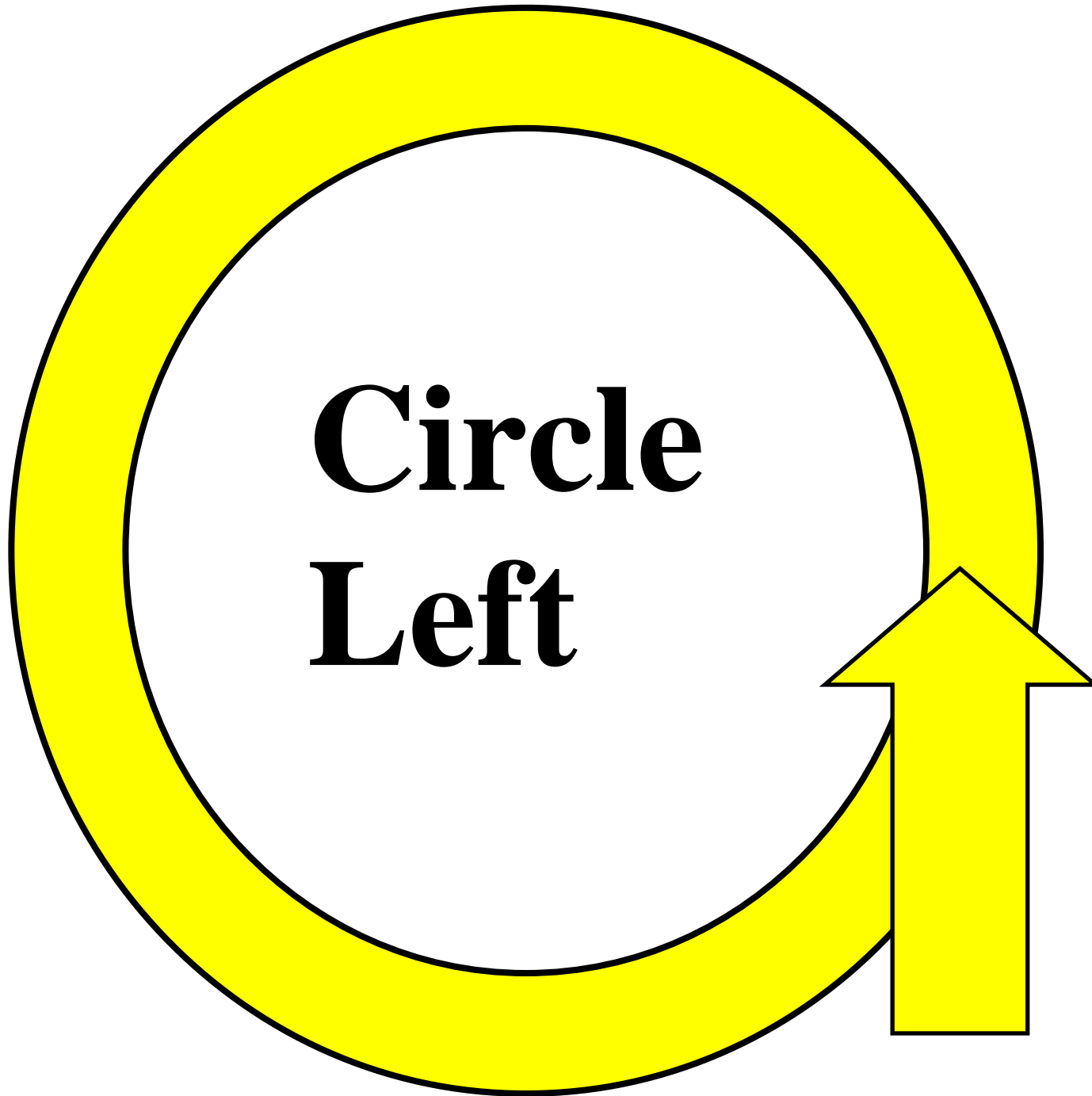


**Off-Set**  
**Figure Eight**

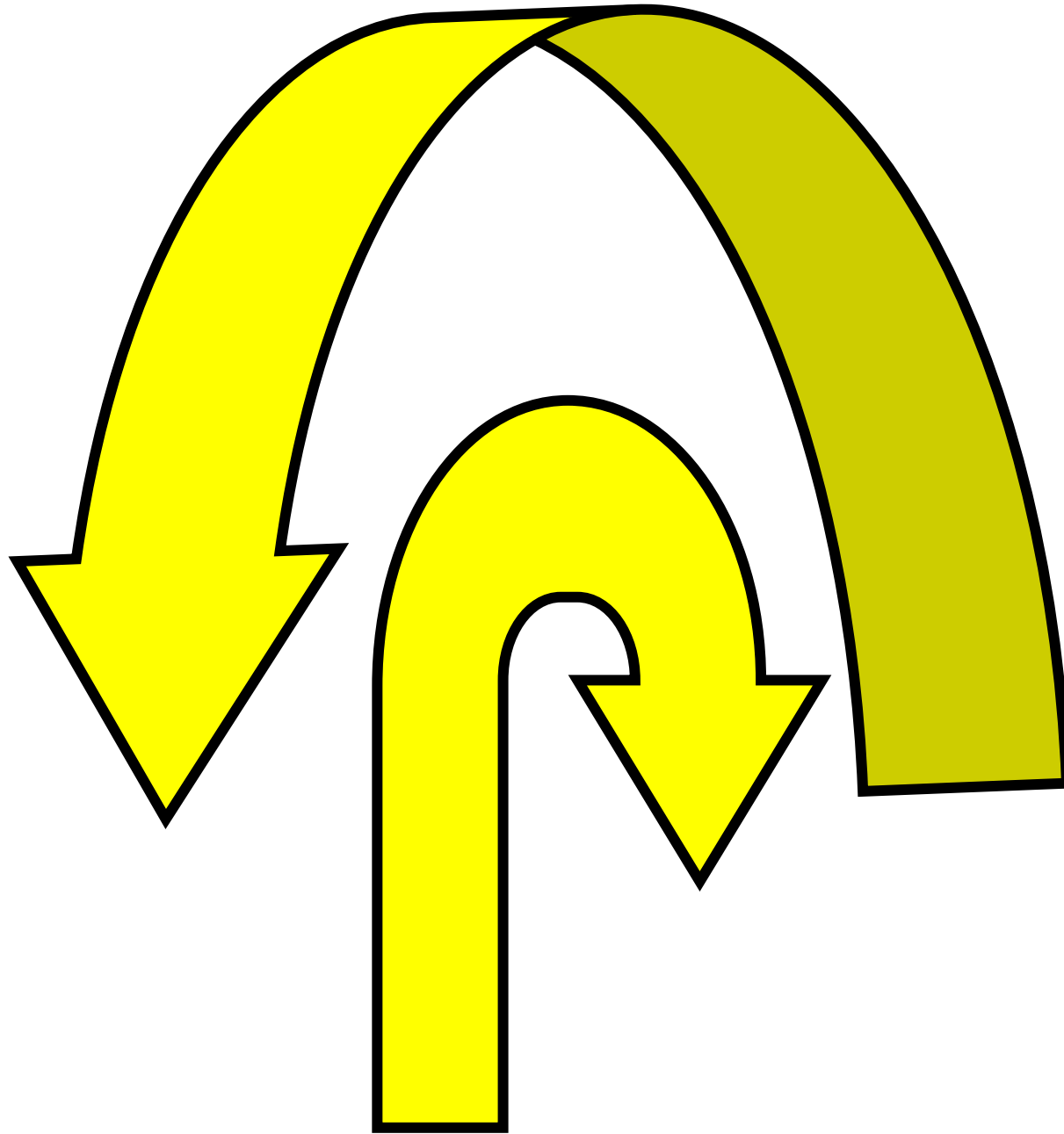


**Circle  
Right**

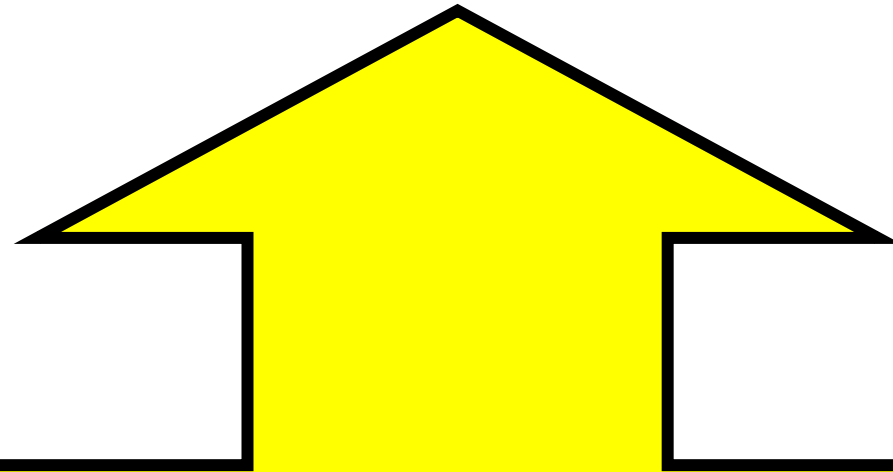




**Circle  
Left**



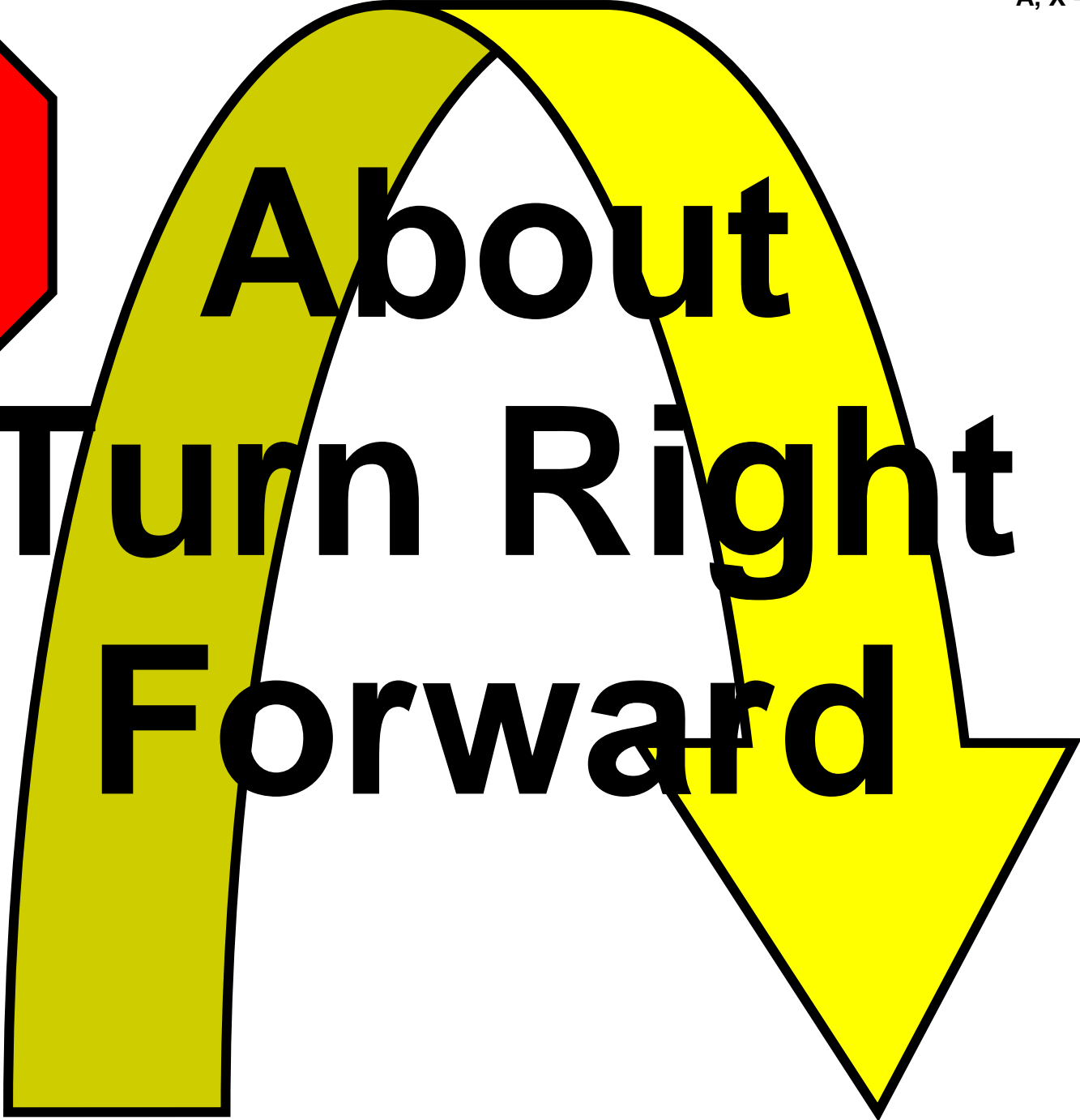
**Call  
Front  
Return  
To Heel**

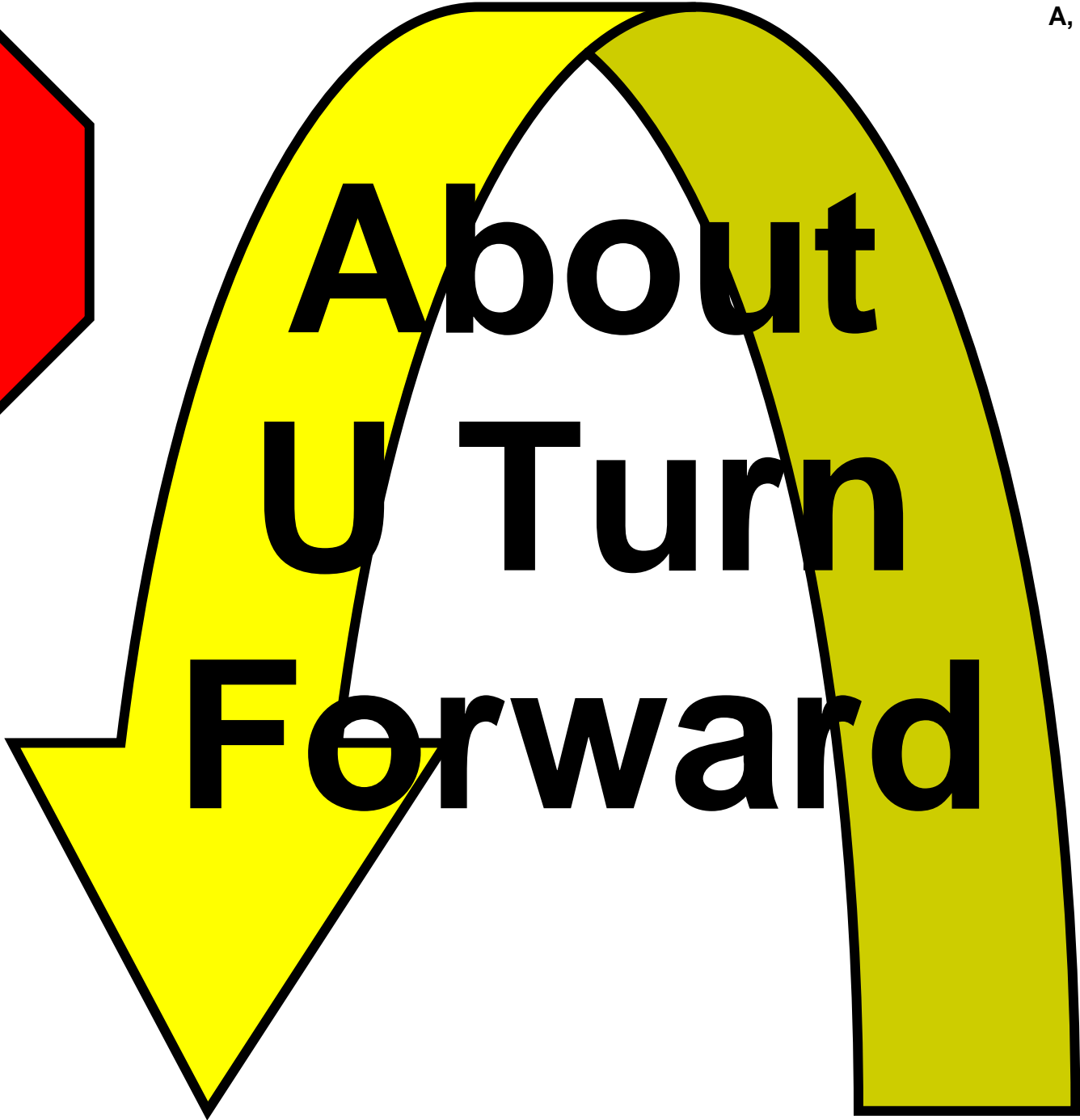


**Moving  
Down**

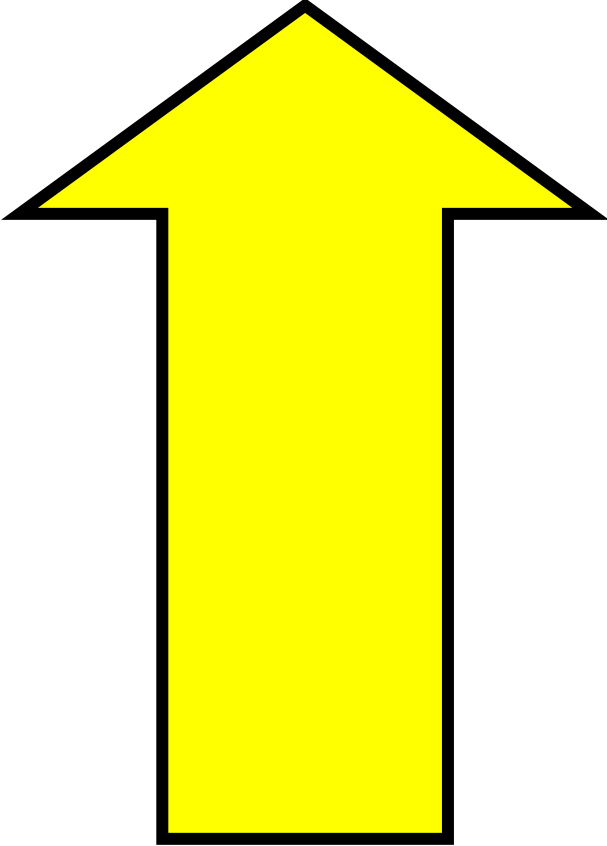
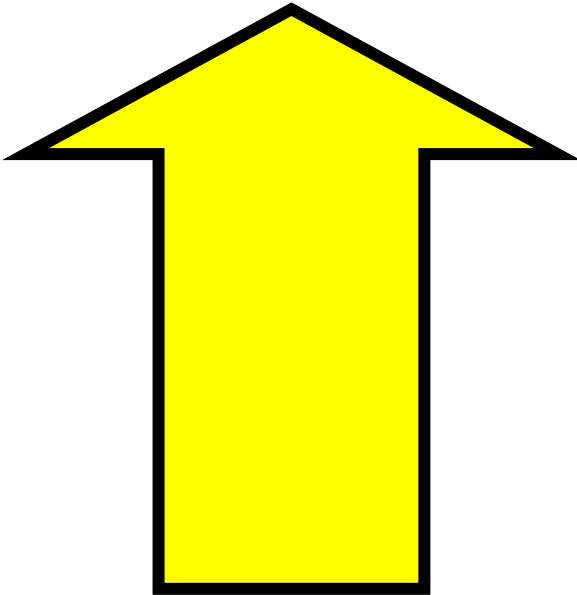


**About  
Turn Right  
Forward**





# Send Over Jump

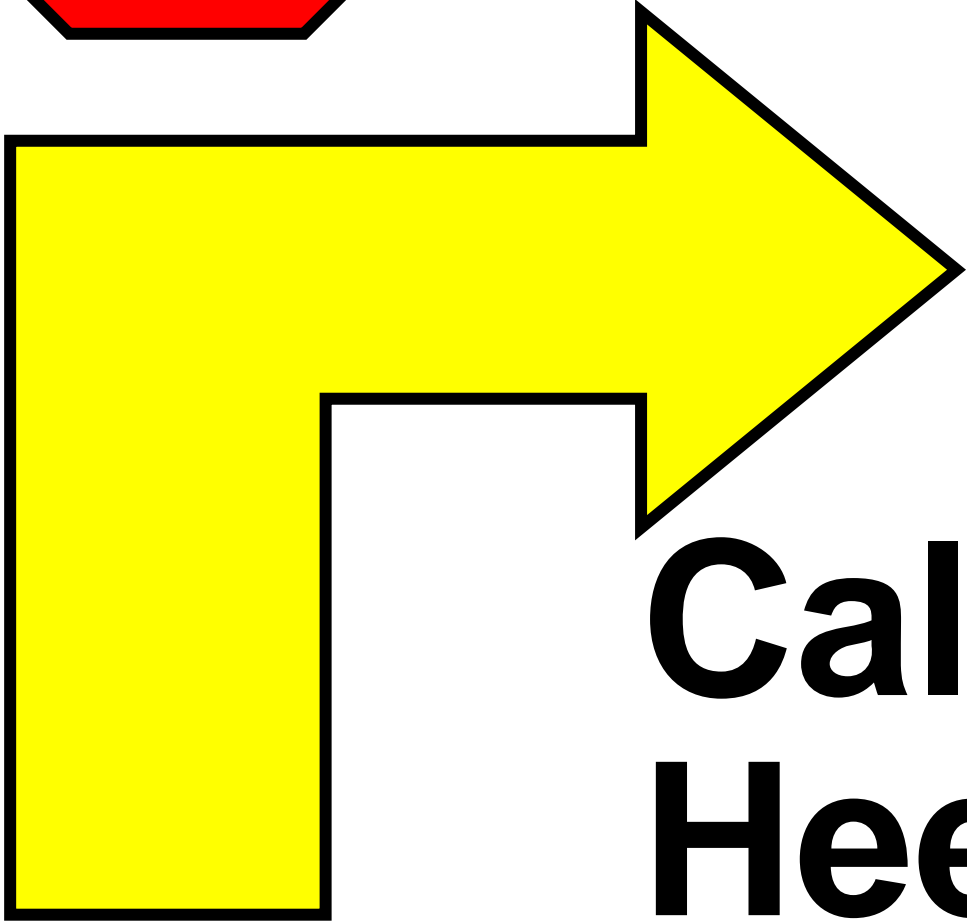
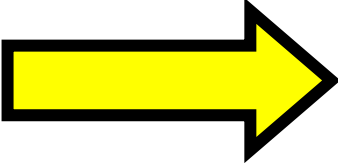


Handler Passes By



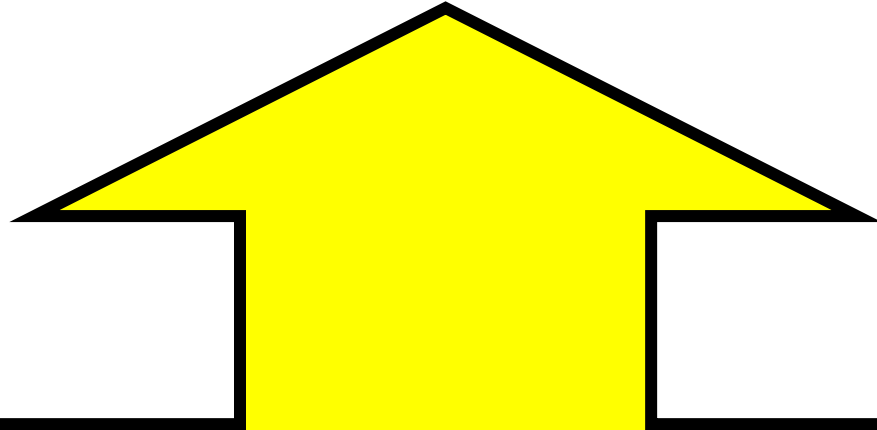
**Turn Right**

**1 Step**



**Call To  
Heel**



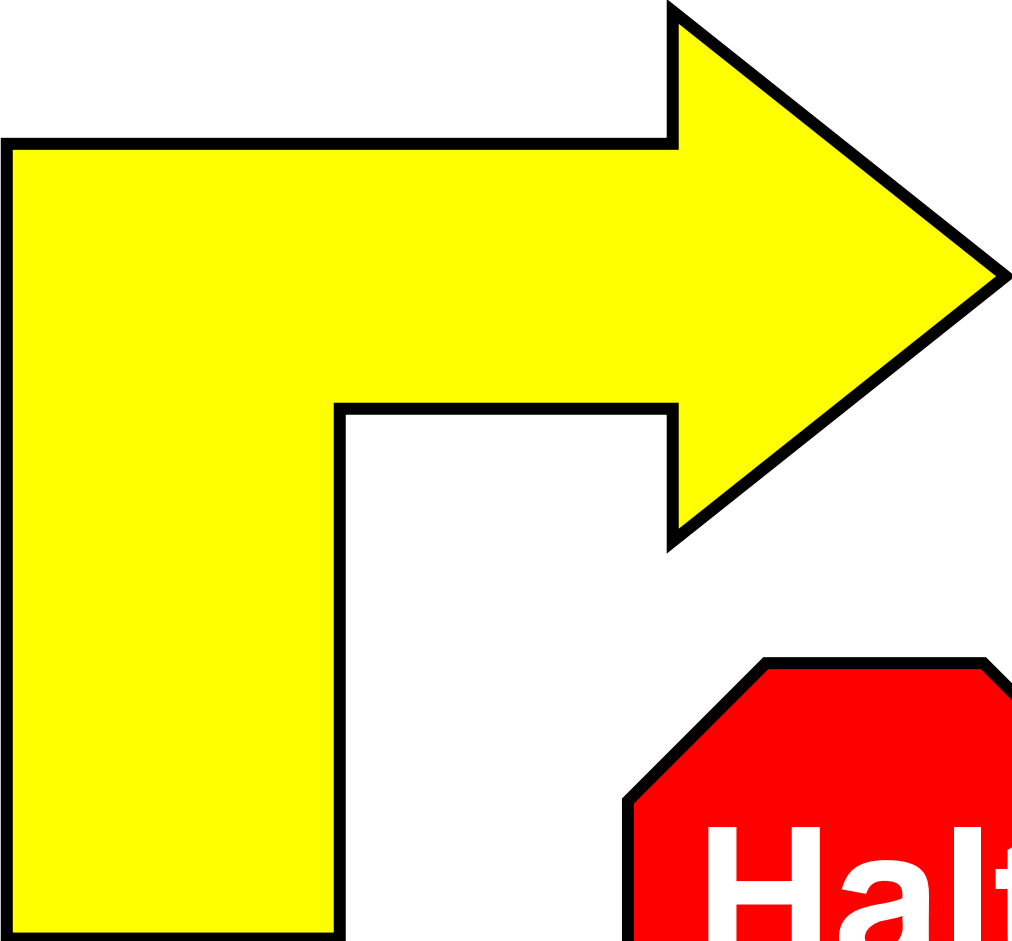


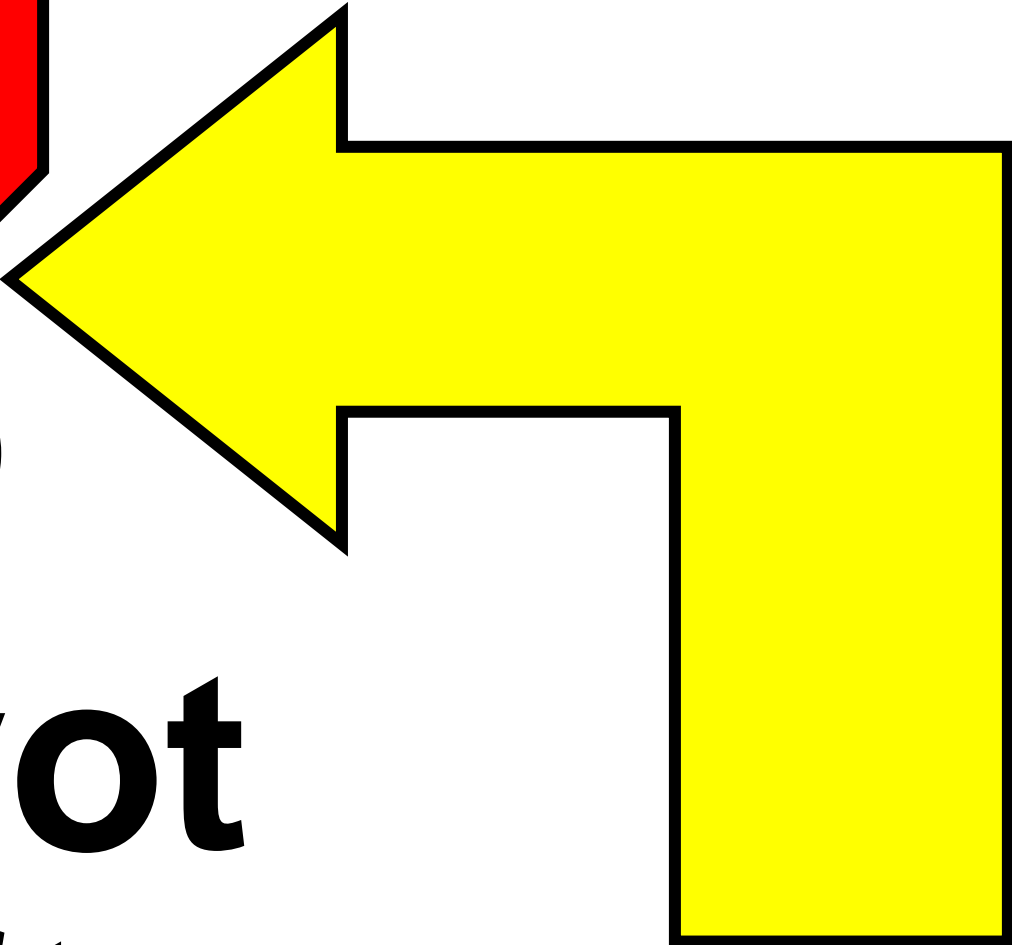
**Stand  
Walk Around  
Dog**





**90°  
Pivot  
Right**



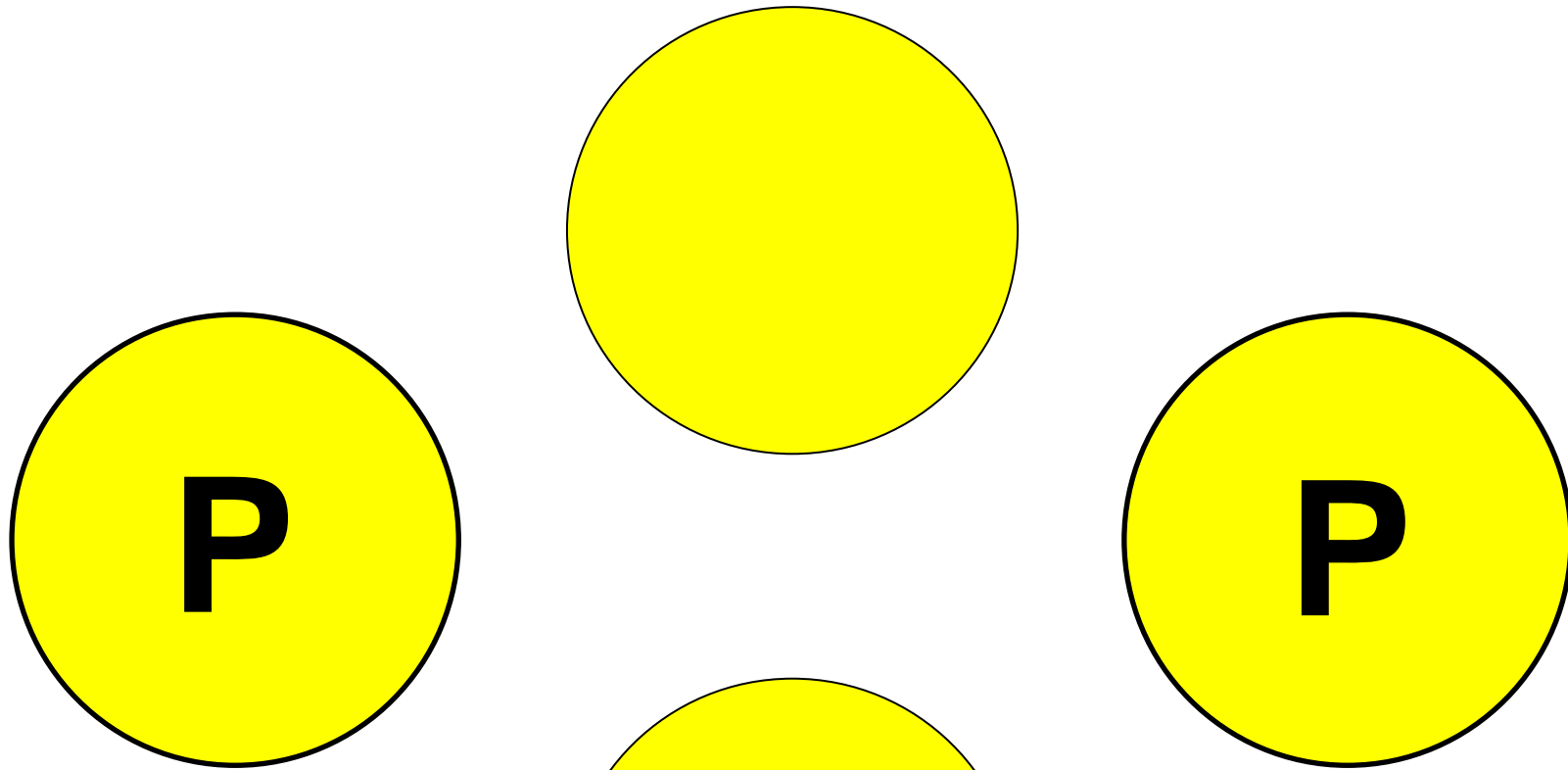


**90°**

**Pivot**

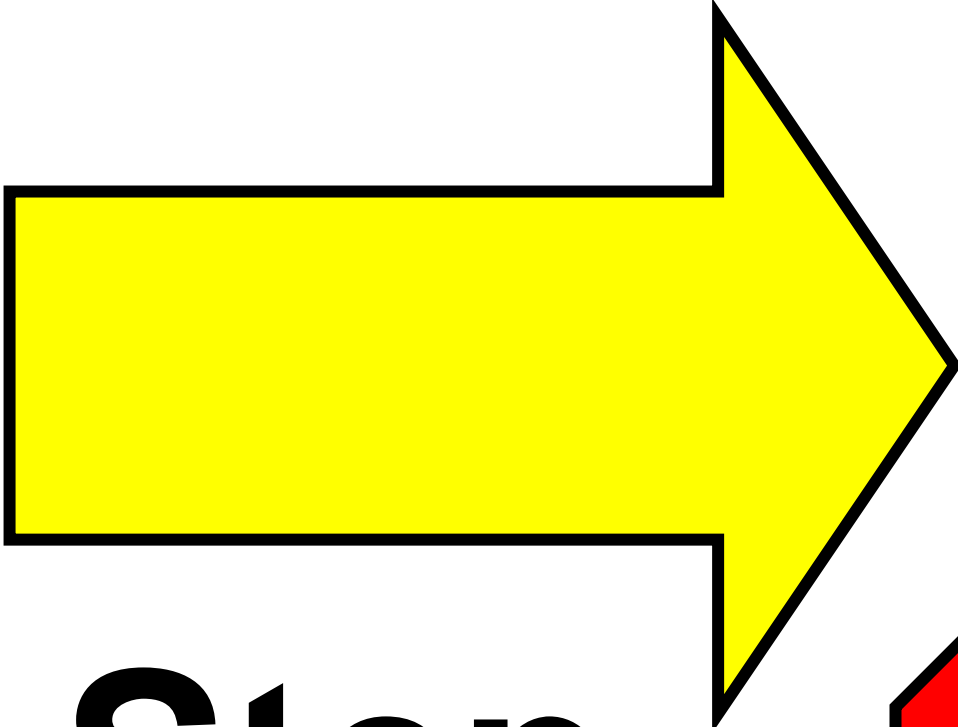
**Left**





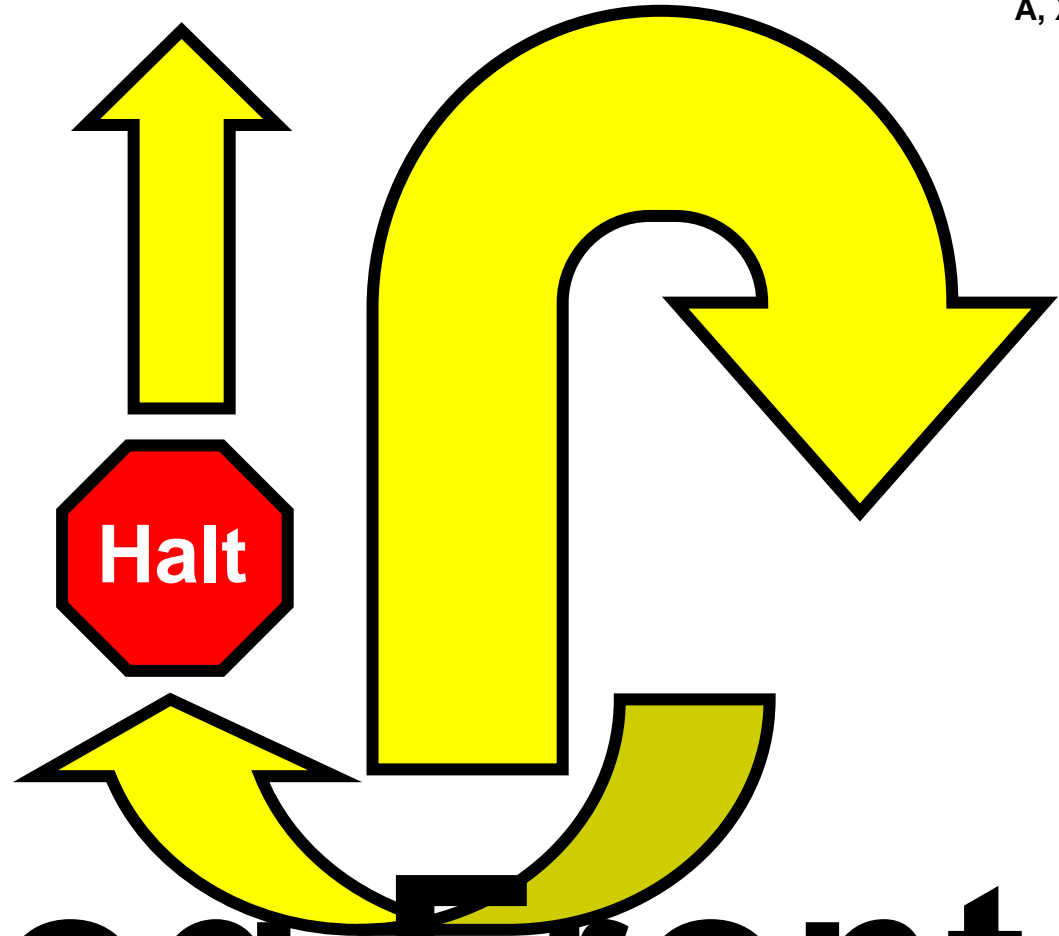
**Off-Set**

**Figure Eight**

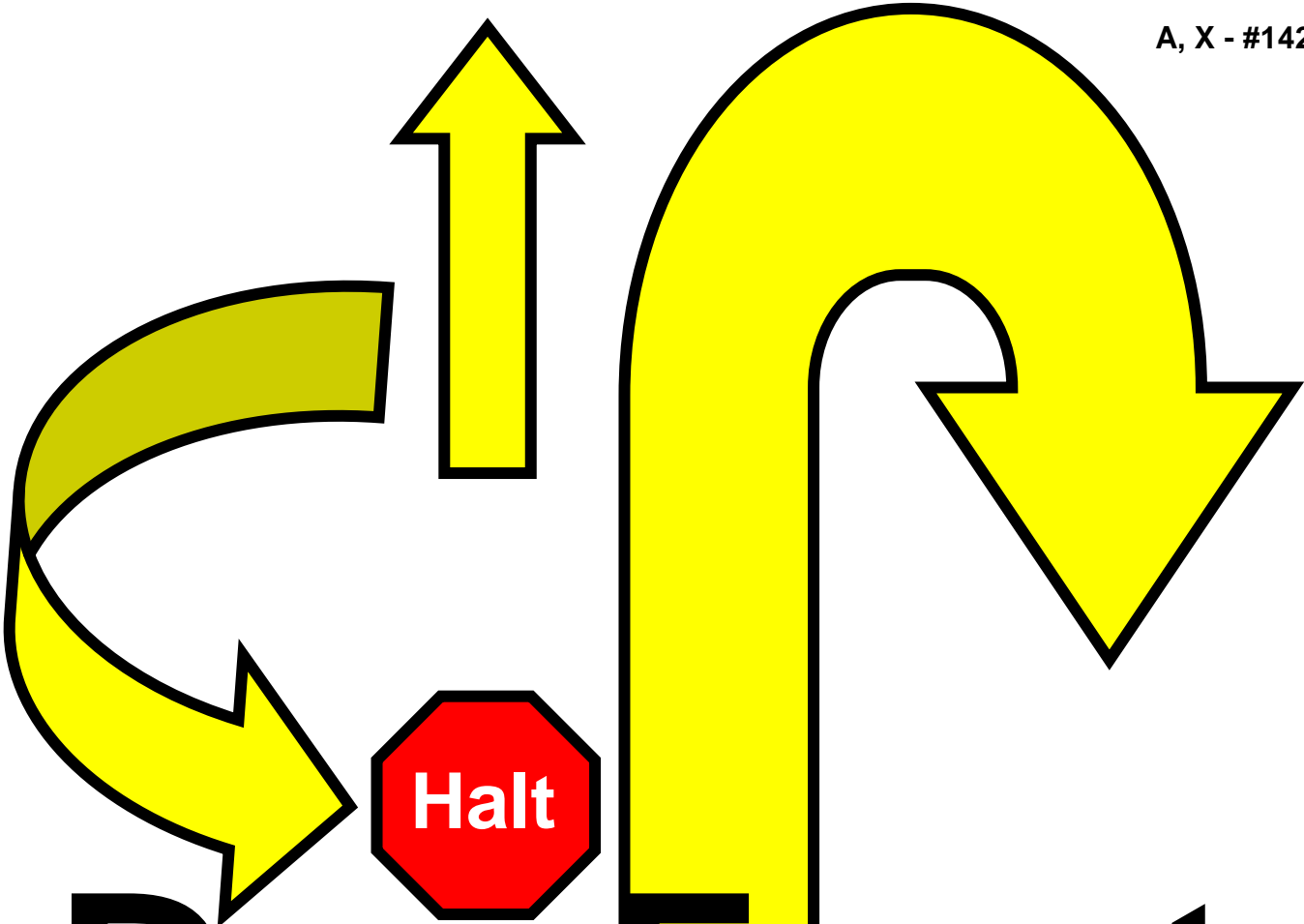


**Side Step**

**Right**



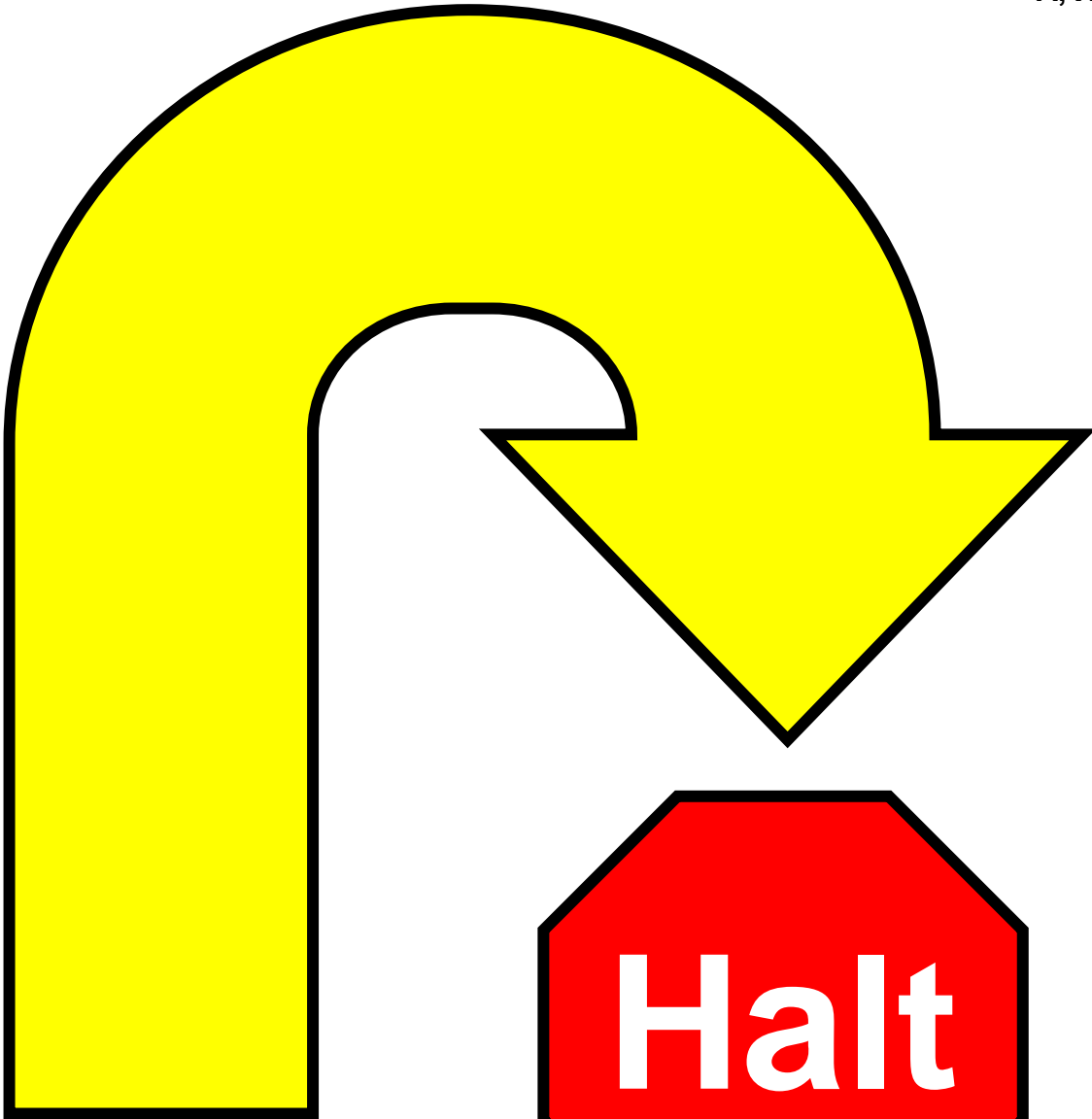
**Call Dog Front**  
**Finish Right**

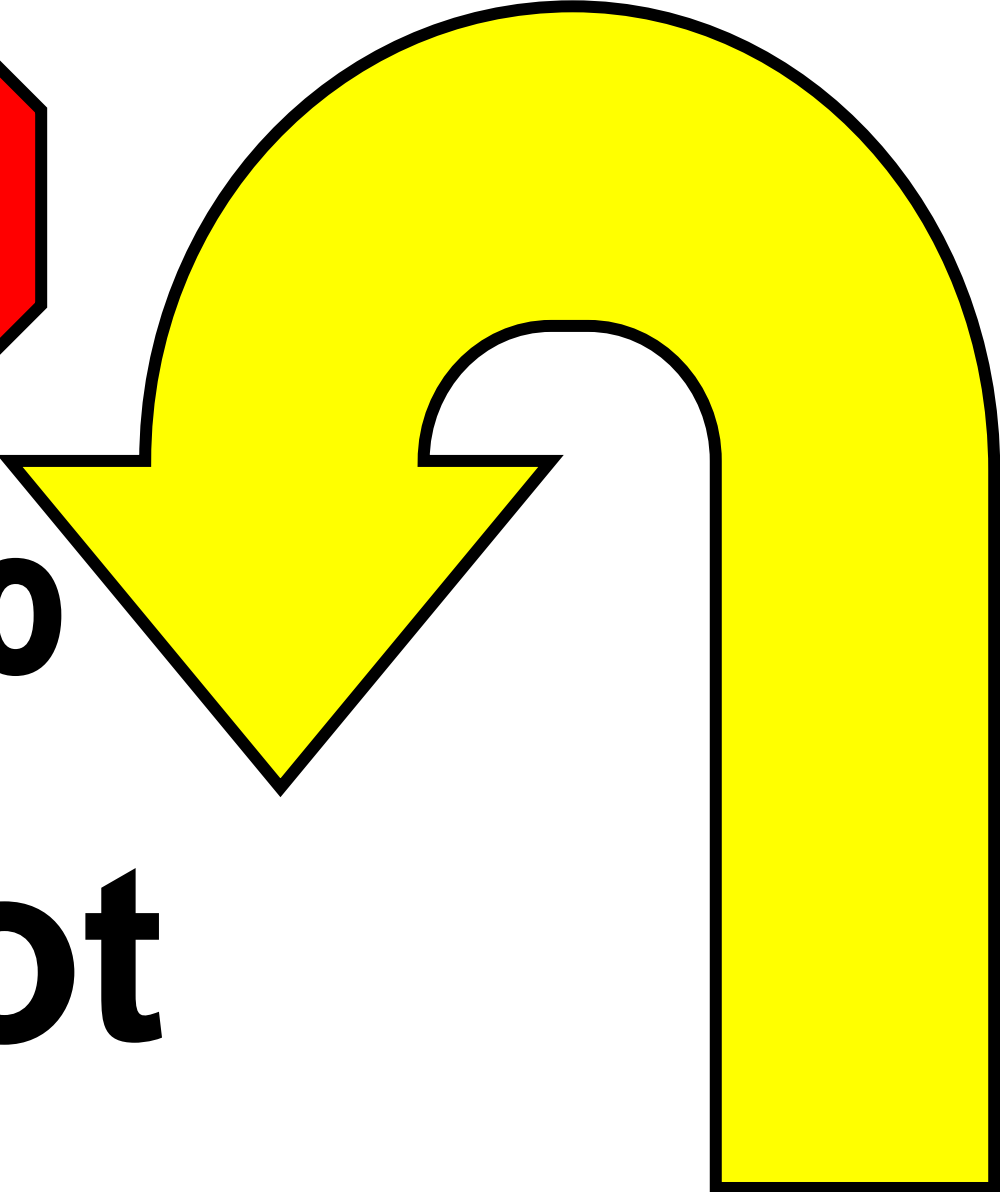


**Call Dog Front**  
**Finish Left**



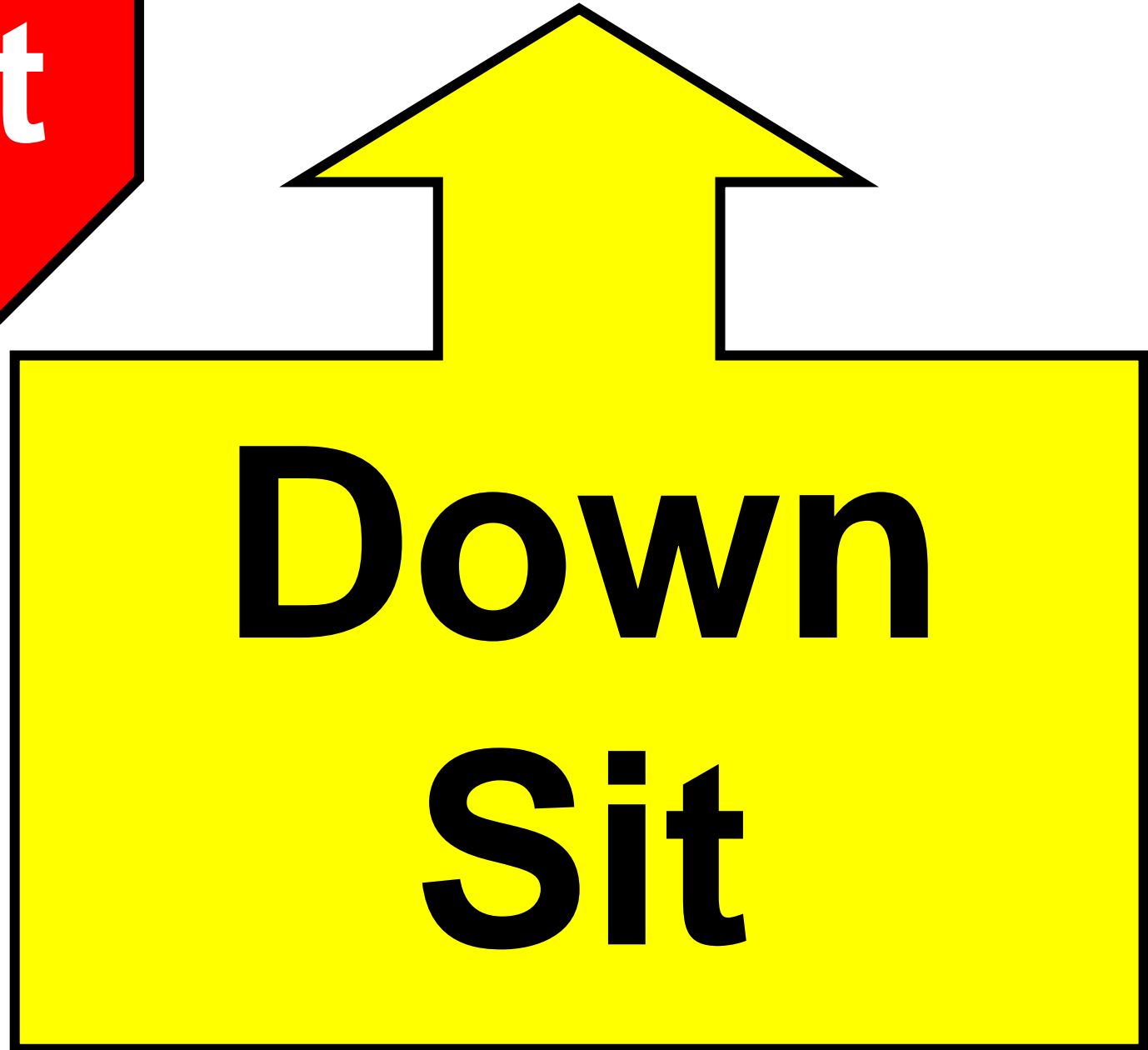
**180°  
Pivot  
Right**

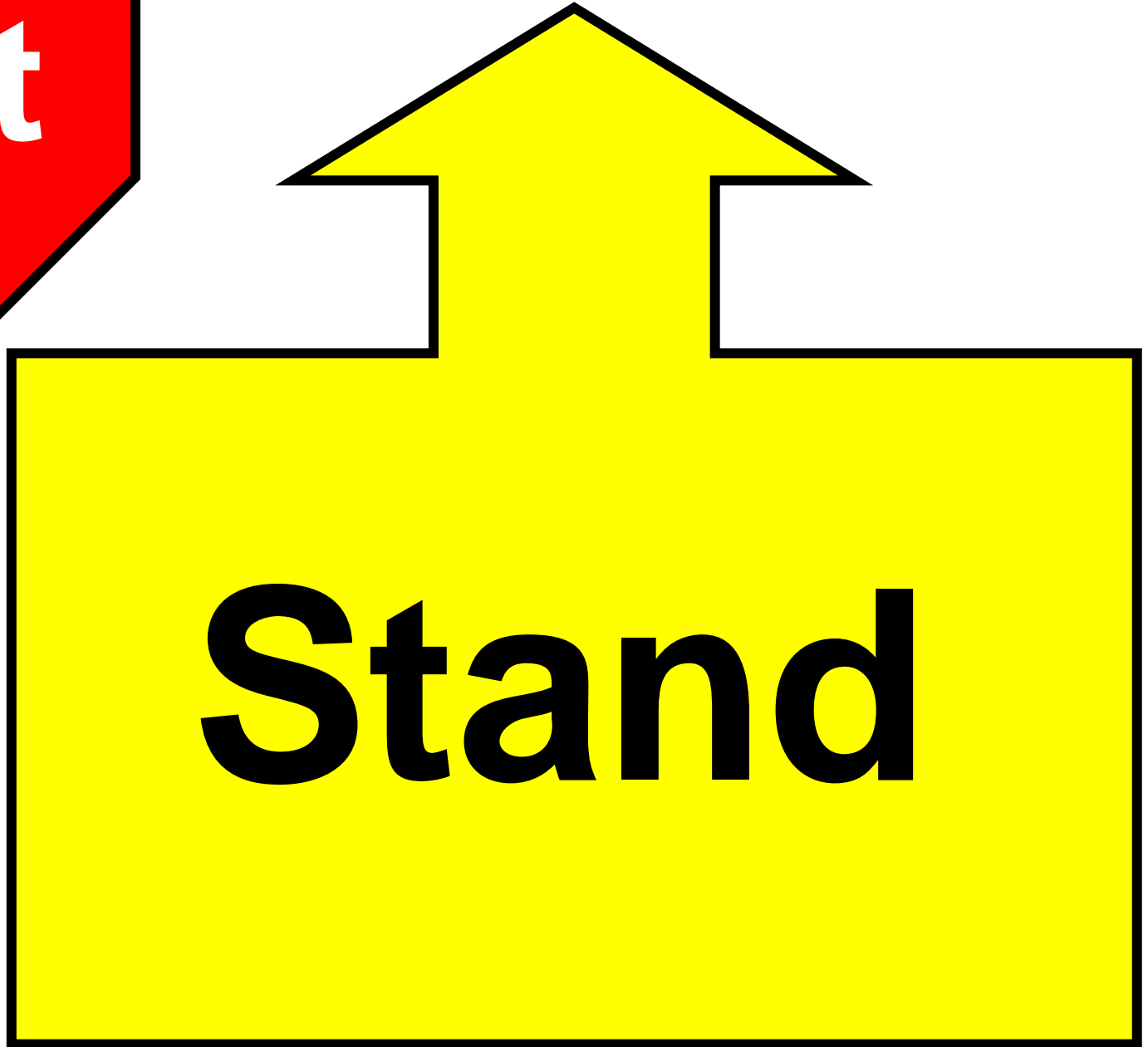




**180°  
Pivot  
Left**

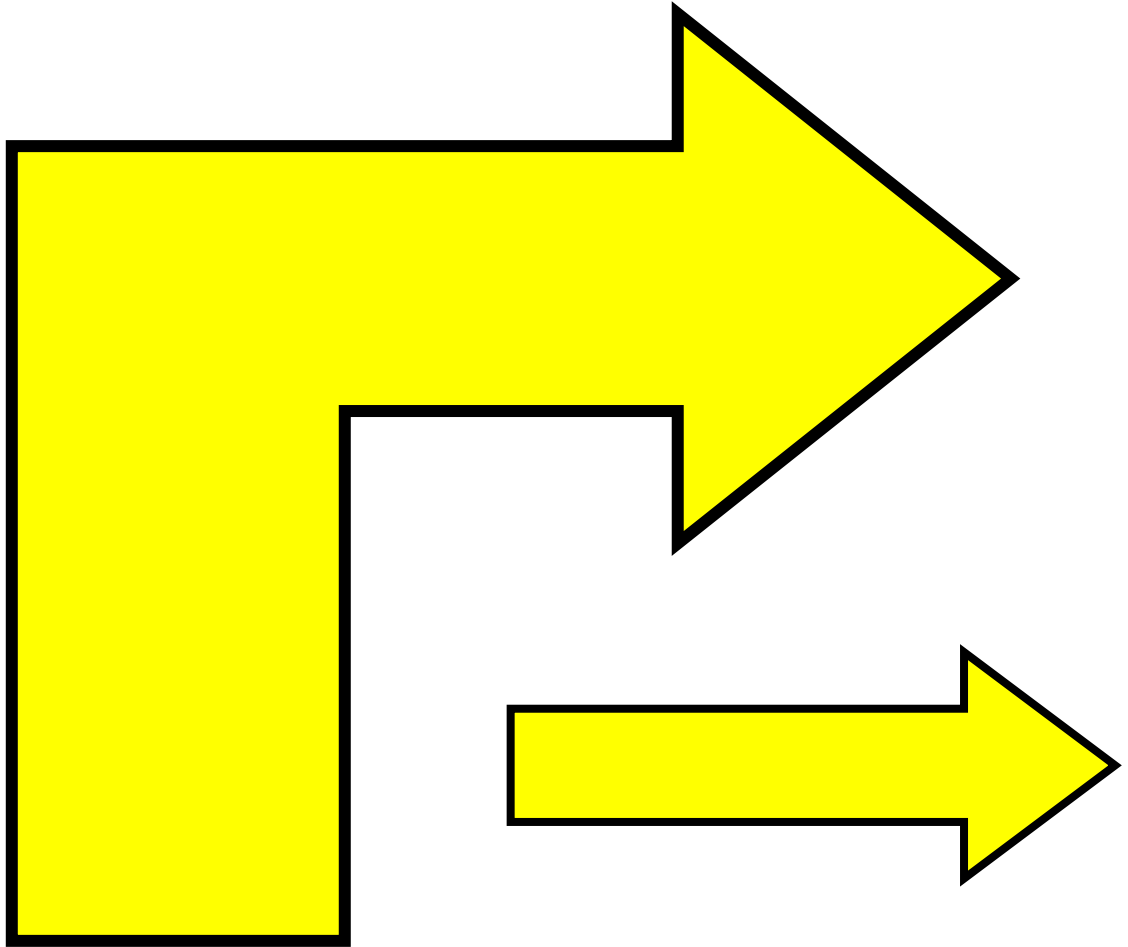




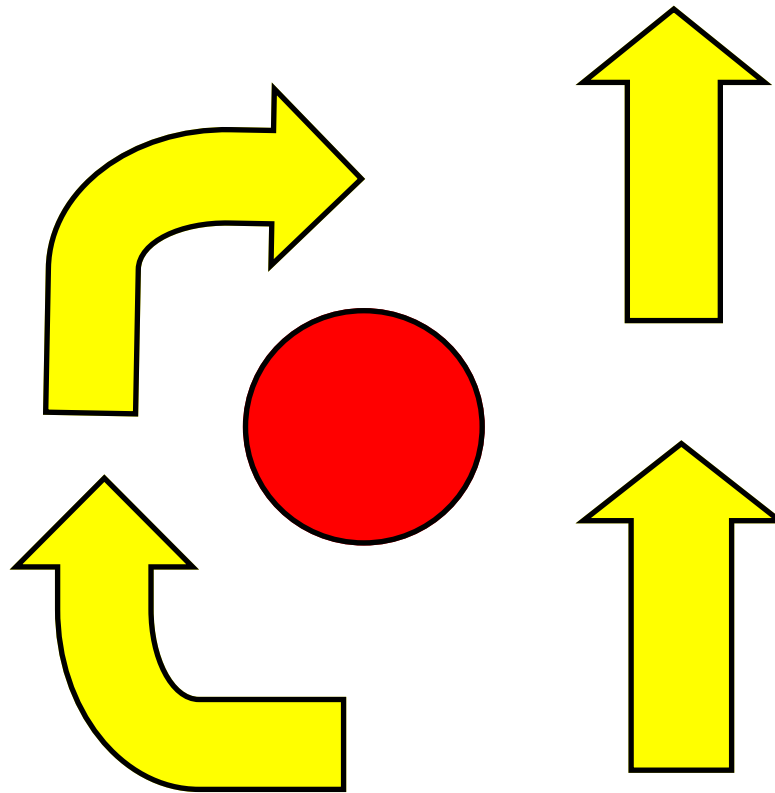




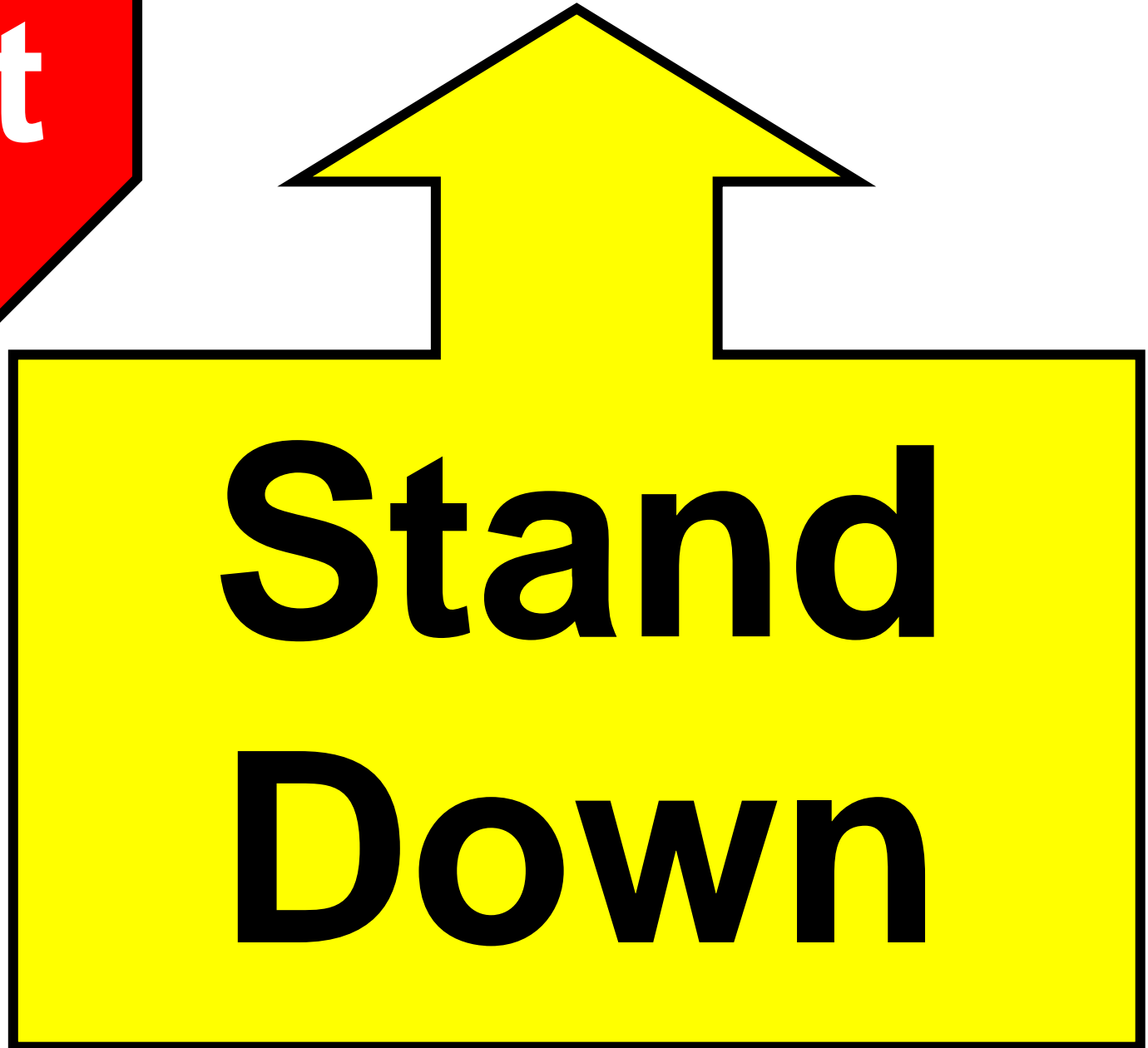
**Pivot  
Right**

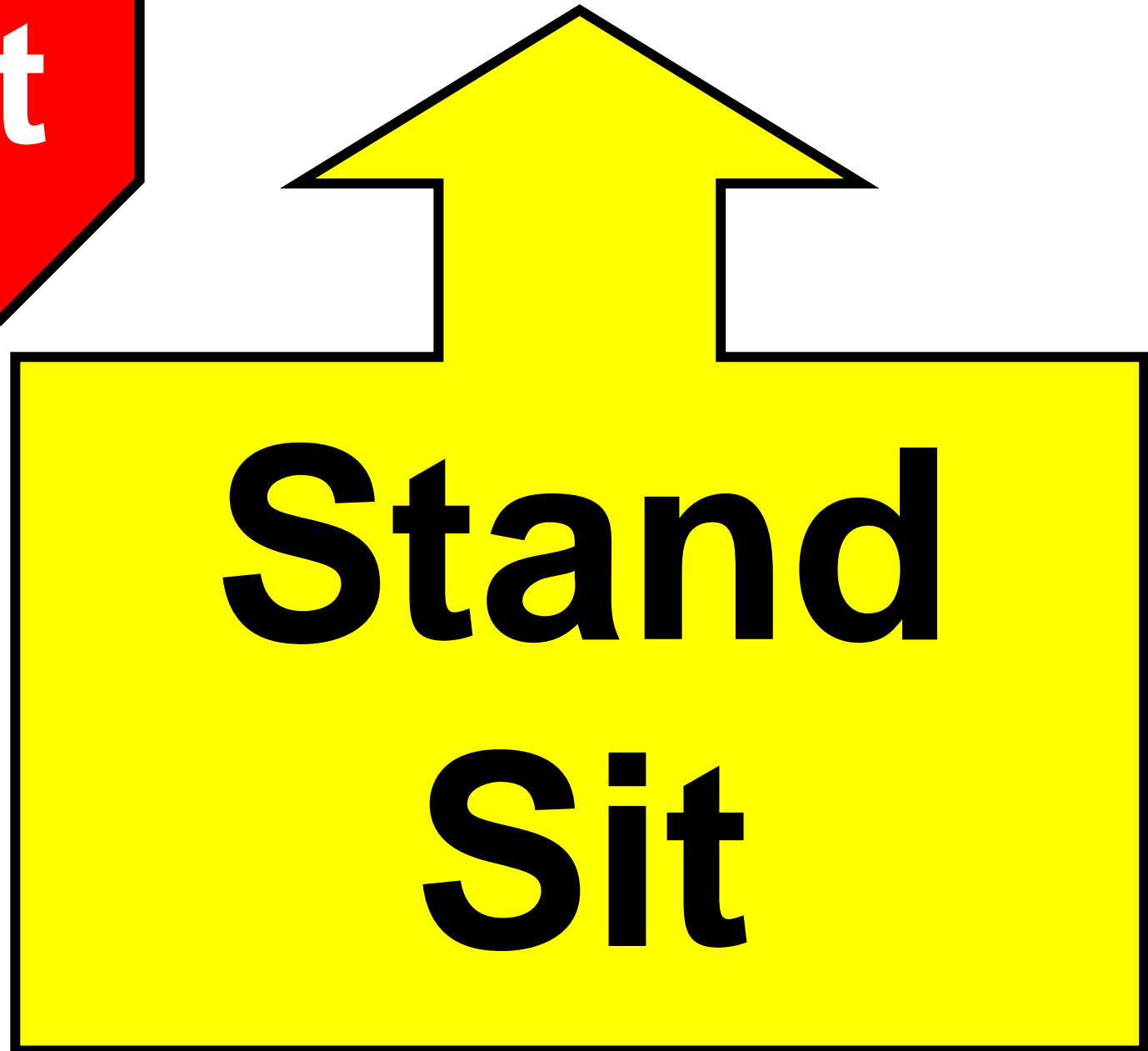


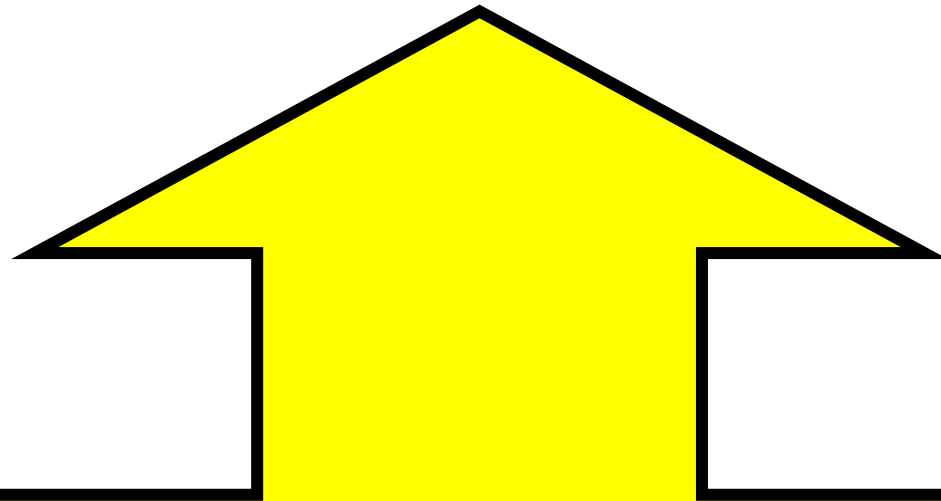
# Forward Around Pole



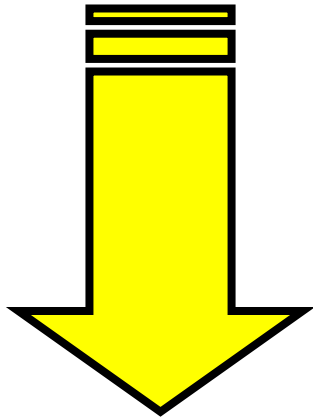
**Handler Passes By**



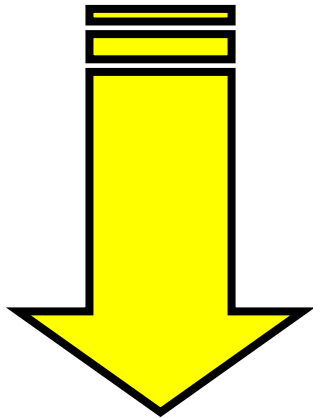




**Moving Stand  
Walk Around  
Dog**

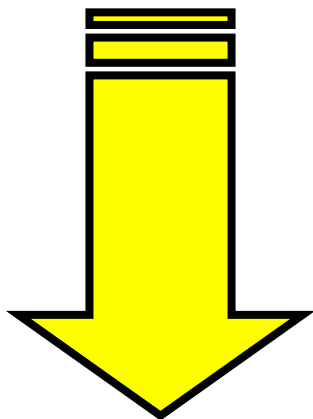


**Back Up**



**3 Steps**

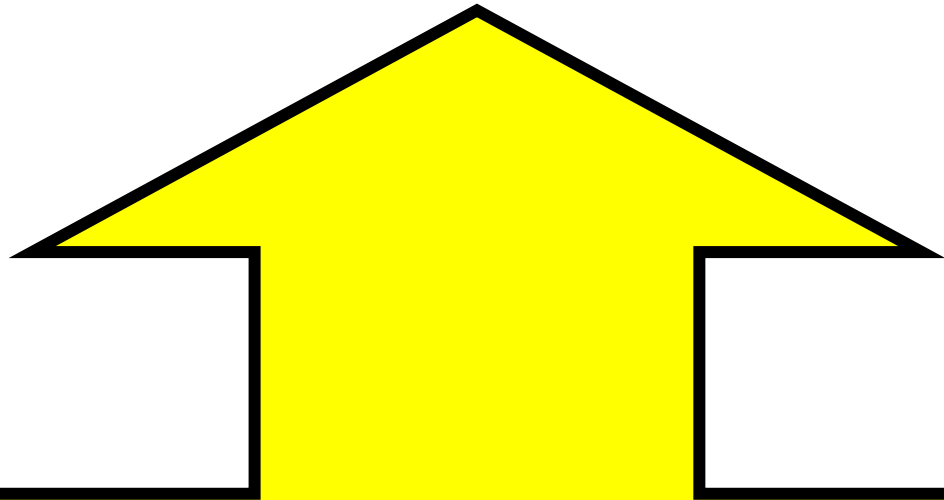
**Dog Stays**



**in Position**



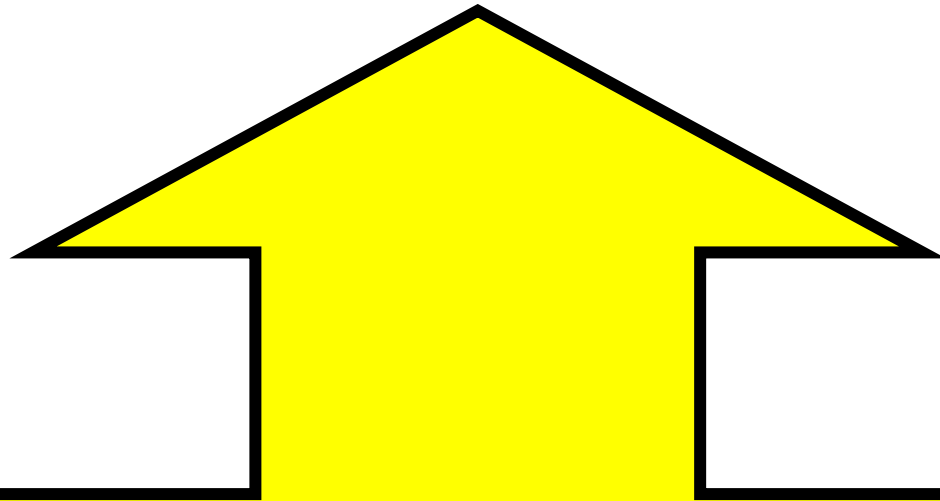
**Stay**



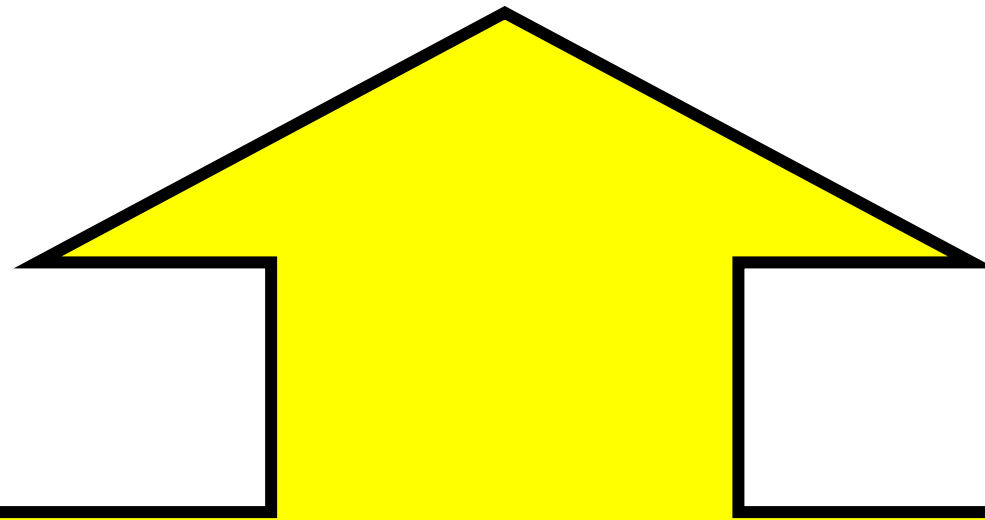
**Moving Down  
Walk Around  
Dog**



**Down  
While Heeling**



**Stand  
While Heeling**

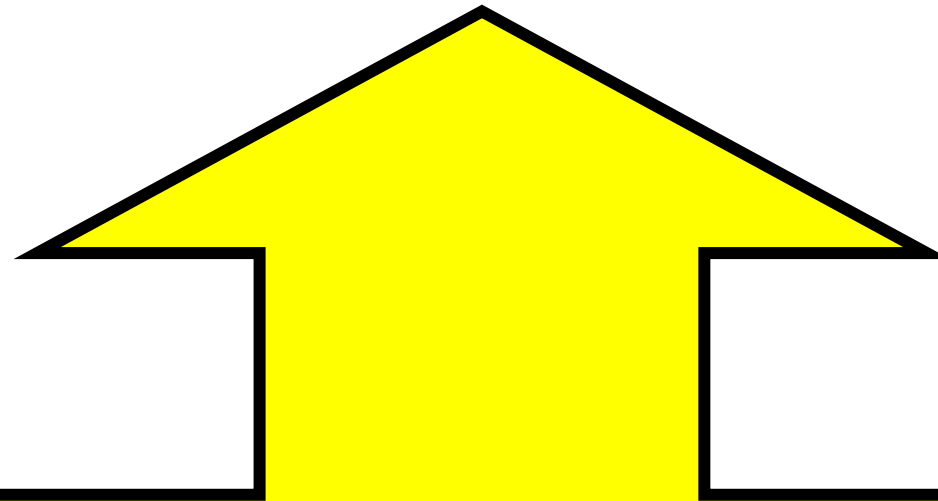


**Stand**

**Leave Dog**

**Sit Dog**

**Call Front - Finish**



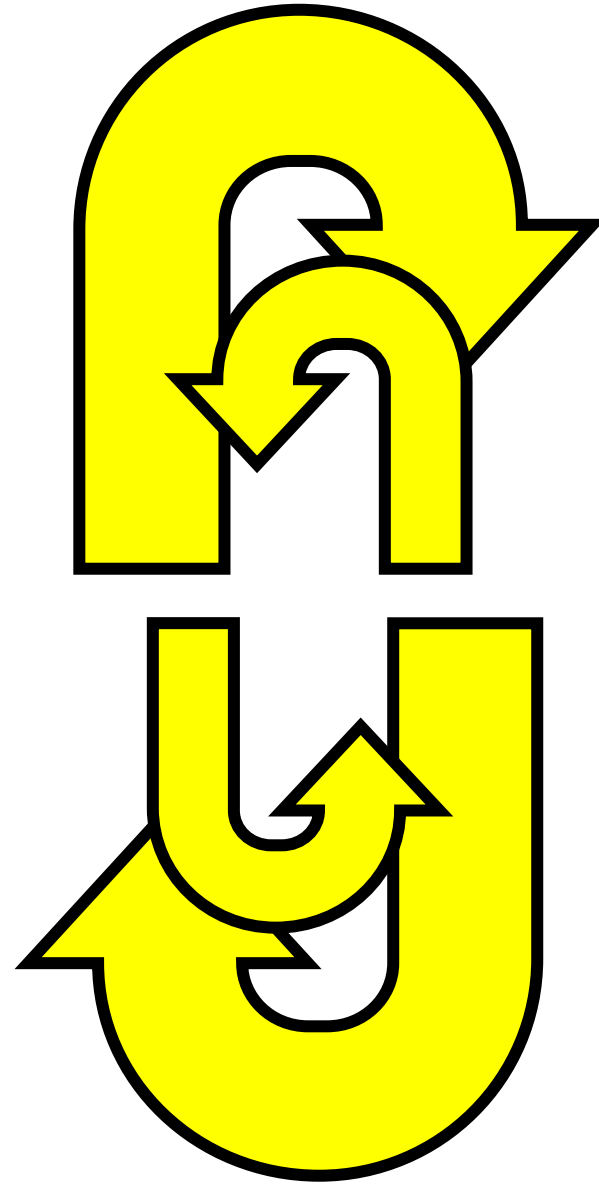
**Stand**

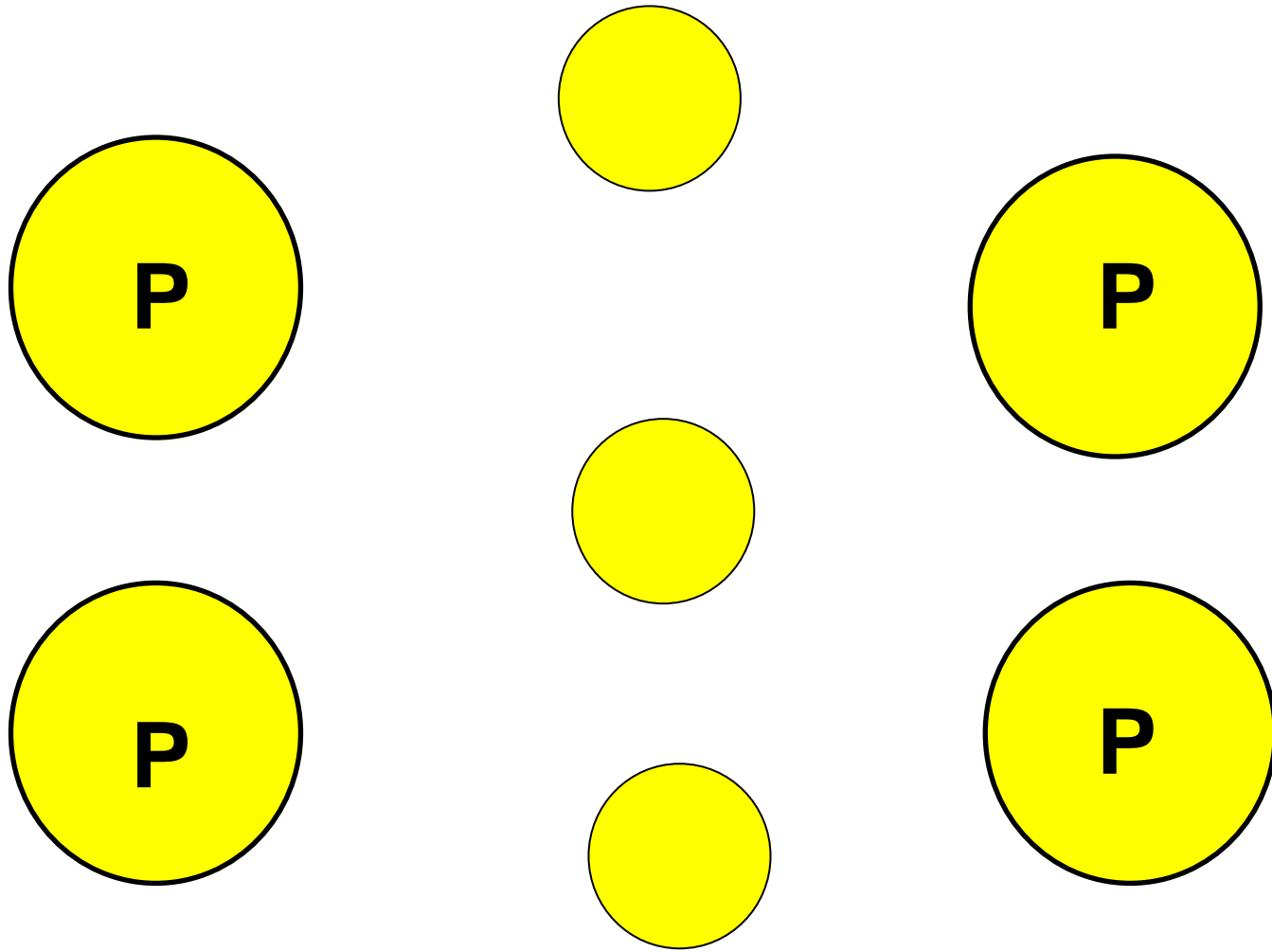
**Leave Dog**

**Down Dog**

**Call Front -Finish**

**Double  
Left  
About  
Turn**



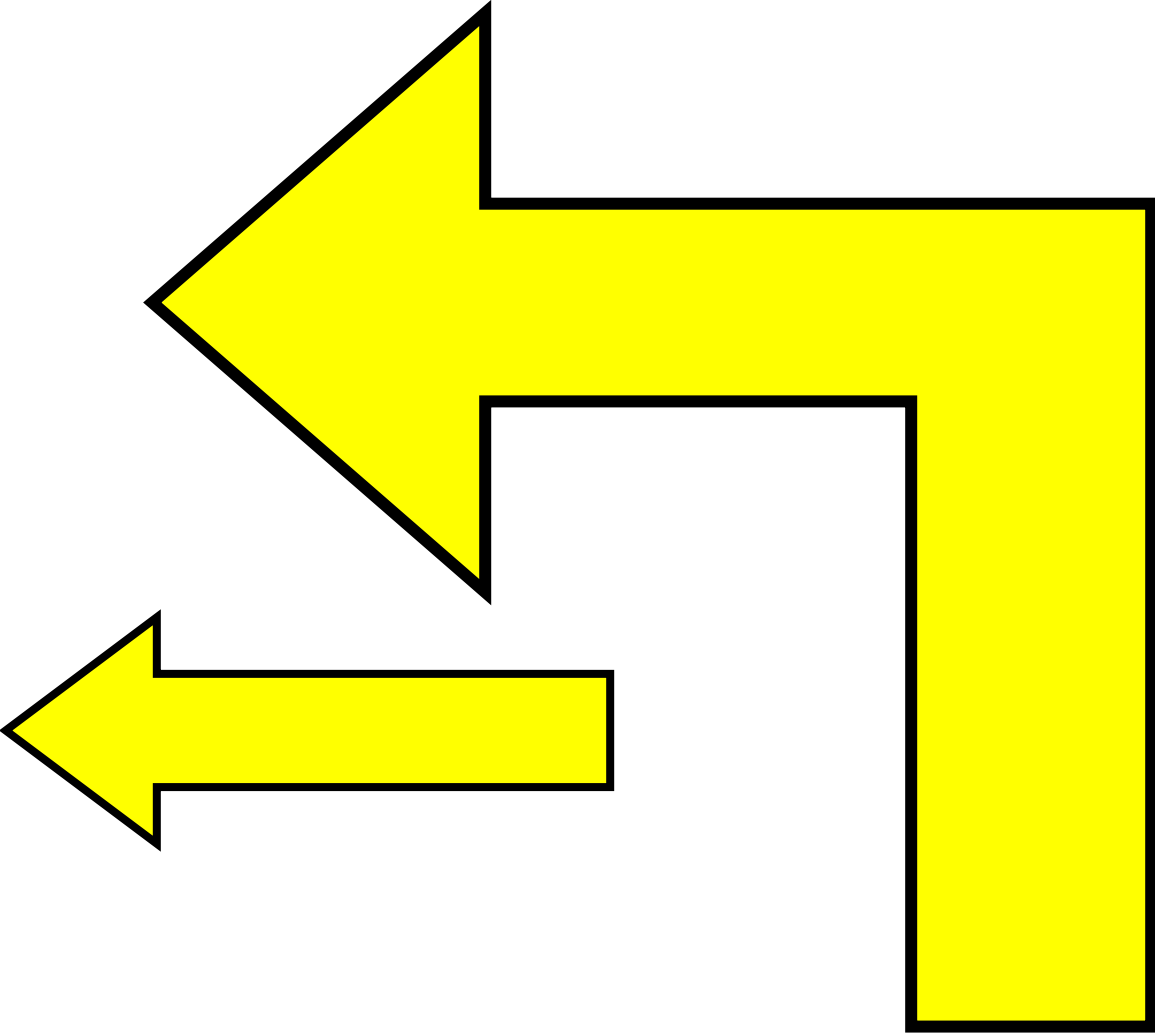


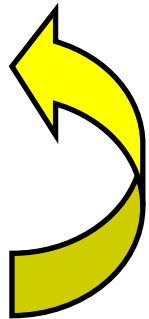
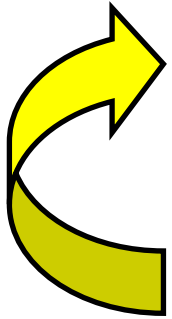
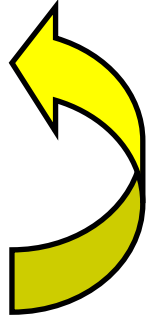
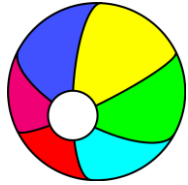
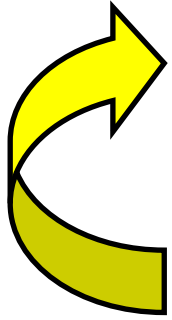
# Double Off-Set Figure Eight



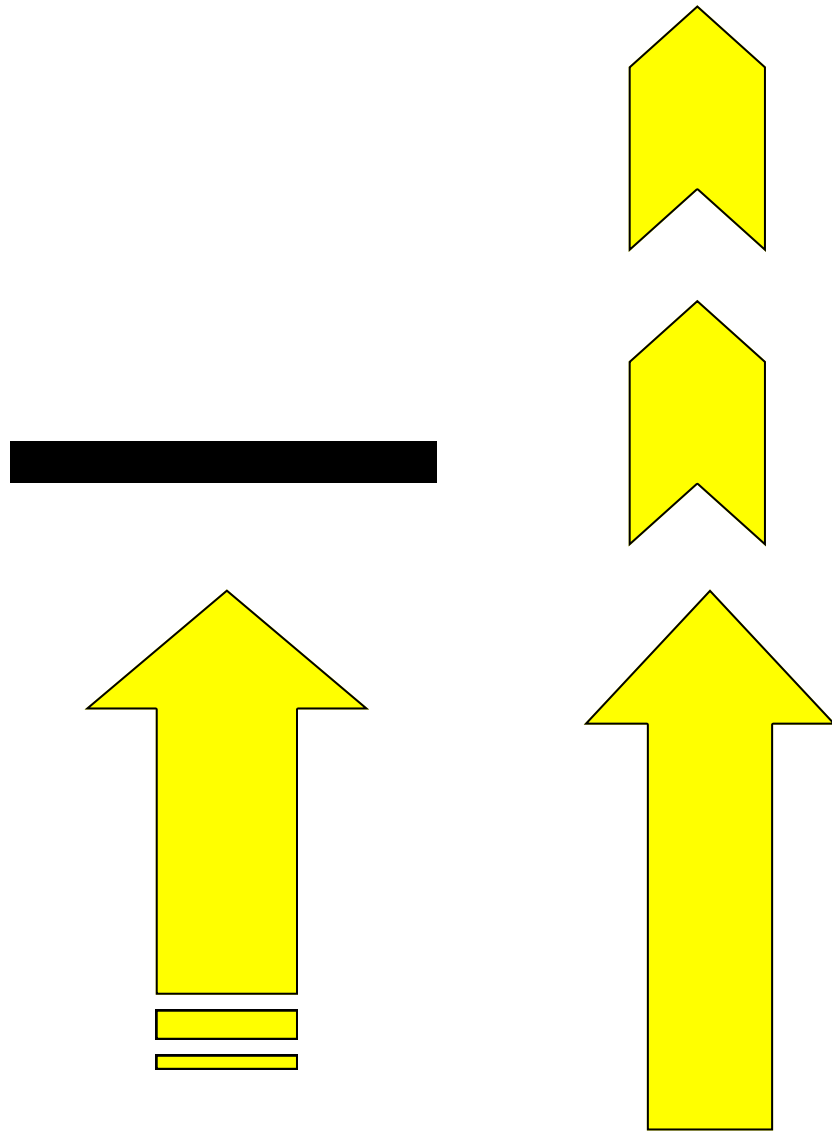


**Pivot  
Left**

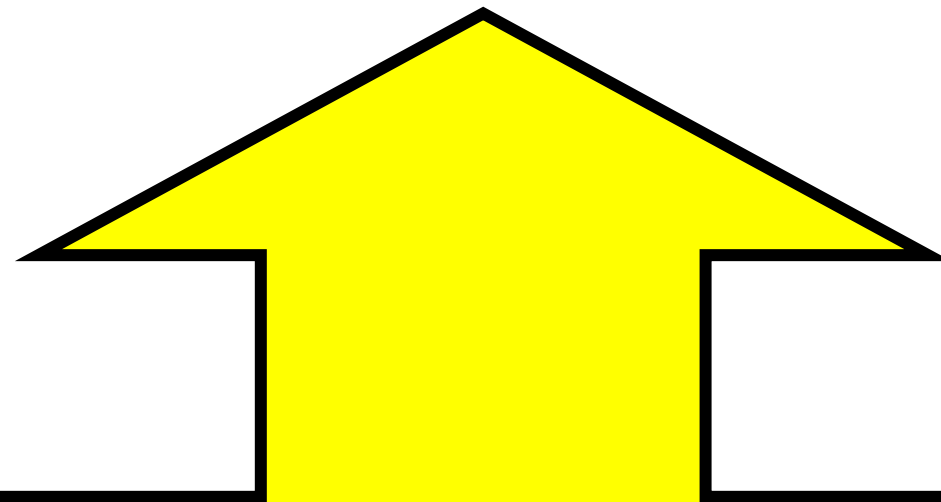




# Weave With Distractions



**Stand**  
**Leave**  
**dog**



**Recall**